

HITACHI INVERTER

HFC-VWS₃ E(H) SERIES

SERVICE MANUAL

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- 1. Investigation
- 2. Kind of Printed Circuit Board
- 3. Use and level of checkpins
- 4. Trouble Shooting
 - 4.1. Trouble Shooting and message contents
 - 4.2. Contents of check points when trouble happens
 - 4.3. NVRAM failure
 - 4.4. How to return the setting to the initial setting
- 5. Measurement
 - 5.1. PWM output signal waveform from the Control Board
 - 5.2. Motor current signal
 - 5.3. Motor current waveform
 - 5.4. DC-current signal
 - 5.5. Output signal of Base Drive
 - 5.6. How to check Converter Modules
 - 5.7. How to check Inverter Modules
- 6. Appendix
 - 6.1. E-thermal function characteristics
 - 6.2. Block diagram of CFB
 - 6.3. Circuit diagram of printed board
 - 6.4. Sequence diagram
 - 6.5. Structure drawing
 - 6.6. Cabinet volume
 - 6.7. Selection of ventilating fan of inverter box
 - 5.8. How to measure the voltage, current and power
 - 6.9. Rushing current when power supply is turned on.

1 INVESTIGATION

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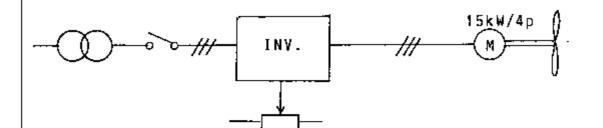
When trouble happens!

- Investigate the customer's application and phenomenon and fill in them on the trouble report sheet.
- Fill in the setting data of customer on the data setting list.
- Investigate the customer's setting data whether they are proper for the application system.
- L-- Check the inverter Which parts have been damaged:See page
- * The reason for the trouble is not always inverter's failure. We must check the system and inverter both of them.

WARRANTY REPORT TROUBLE REPORT

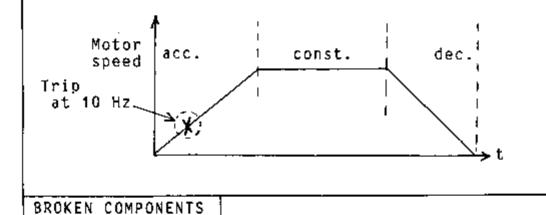
Customer		
Model Type	HFC-VWS 22 HF3E	
Serial No.(MFG.No.)	SE 22 HF 3 82C	
Date of Purchase	JAN.88	
Date of Installation	APR.88	
Date of Failure	MAY.88	

APLICATION Fan drive



DETAILS OF FAILURE

When the reference signal (0~10V) is feeded to the inverter, over current trip comes.



Power module

REMARKS

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WARRANTY REPORT

TROUBLE REPORT

Customer	
Model Type	
Serial No.(MFG.No.)	
Date of Purchase	
Date of Installation	
Date of Failure	

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APLICATION

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DETAILS OF FAILURE

BROKEN COMPONENTS

REMARKS

		Cân
		data
÷		KFC-VWS; inverter has many function; so that the setting data can
	F	the
	HFC-VWS ₃ Series DATA SETTING LIST	that
	ž	3
	E	i on:
	Š	unct
	TA	ny f
	à	
	ies	hæs
	Sa	fer
	ŝ	UVE
	ξ	н
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	Ŧ	HFC

be changed by customerg.

It is recommended to fill the setting data our the following data sheet for service, maintenance and investigation of trouble.

TYPE : LFC-VNS

Described on spec. Label on top cover

Monitor Mode

- ուսեր Հերկո	Monitor Kame	Tottial Diaplay	Secting	Setting Date
_	Outpul frequency displey	ЕМ 000.0Н.	1	
N	Frequency setting commund	£s 000.0н;	1	-
m	Frequency commund method	E-set-M Terbinal	Tertinal	
प	Uperation commend method	É/A5W Termigal	lenterat	
\$	Mator Fyeed Aleptey	EPN 4P 0000APM		
9	Output current display	1 1=000. 0K	1	
~	Manual Torque boort adjustment	<u>Y-8441 (04+(31)</u>	ī	
- 20	Output voltage gaia adjustment	V-G.1. 100K	8	
β.	Jogging Irequency seiring	<u></u>	¢.9	
10	Fault display		1	

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utepter Sequence	Function Hame	Puscijam Mode	Display Contenia	Setting.	Satting Data
-	V/F POLISIN BOLLINE	<u>†</u> - 0 0	V I 1 - F C	V71-VC 050-050	
~	Acceleration time sector		1-13))¥	ę	ı
- -	Decaleración time autring	<u></u>	DECEL-1	8	
3	Manuaute frequency fine adjustment	<u> </u>	• F = 2 .		
3	Starting frequency adjustment	E - 0 -	• F b t n .	0.5	
4	Makimum frequency limiter acting	50-7	H - L I M - F	•	
~	Miniaum (requency limiter metiang	90- 7	1 - N 1 7 - J	-	- - - - -
•	Jump Erequency delting	<u> </u>	<u> </u>	•	
	Jump trequency 2 metting	1 - D E	J L H F - F 2	D	
2	Jump (requency] atting	£ 0 - 7	1 u k P - † 3	- -	
Ξ	Mater moter adjustment	D1-7	C 7 - c b d e		
12	Adjustment of fraquency stop 1364 at start	· · · · · · · · · · · · · · · · · · ·	F. t. b. F.	. P. 4	
ū	Sultistage speed 1 mercang	<u> </u>	Speed-L	D	
7	Tatube 2 pada strengtup	ft-1	5 p e e d - 2	0	
15	Zultterage speed 3 sector	11-7.	6 - b - s q 8		
9T	DC breking trequency edjuctions	- 1 0 2 - T	F-DCE	-	
17	DC braking power adjustant	I I I I	. v - p C B	91	
11	AC bisking the solution.	I - 1 1	1 - b C B		
19	Electric thereal level adjustment	£-2)	4 - C M a F A	100	
DZ.	Lineur/5+churaccar chrvad accaleracten gelaction	ţ-2 4	A C C 1 1 1 4	Libeer	
11	Libear/S-character curved deceieration aetaction	<u>-</u> -25	D 2 6 1 5 5 6	Linger	
ដ	Statt point frequency of external frequency setting	92-2	F-START	•	
:	End point frequency of externel frequency metiling	12-1	F - 1 H D	a	
72	Svitch selection	<u>T</u> - 2 B	I R D I T A S	1010000	
71	Overland kimit time countant satukat	0 F - 1	2 N . C 0 P \$	1.4	
36	Automatic torque bogat adjuntant	E-12		93	
27	Stand-by the setting for restart star intraction power failure	<u>-</u>	175-8-7	-	

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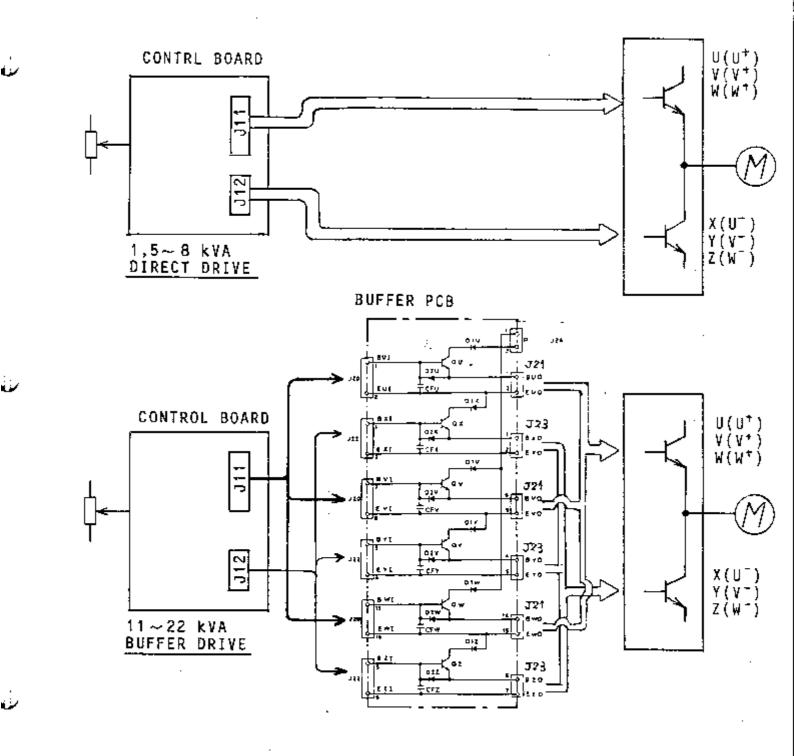
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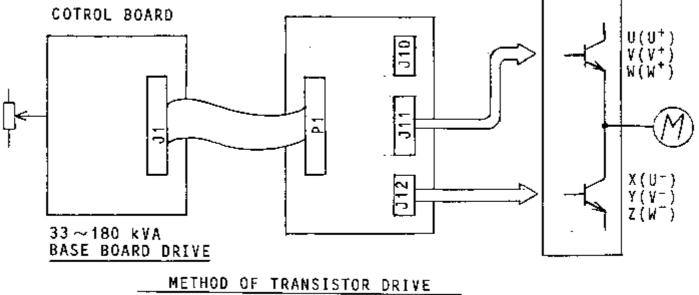
PCB	narre	for	WS3	WWS3E	and	WASSEH	

<u>Series</u>	<u>: VW</u>	\$3			VWS3EH		
Use	Control	Base drive /Buffer	Control	Base drive /Buffer	Control	Base drive /Buffer	
1.55	\sim		S3EL 1 SO	· /	GEILISO	\	
2. 55	X		S3EL2-3SO	/	GE1L2-3SO		
3. 55			¥	Ϋ́Ϋ́Υ΄ / Ι		\/	
IL	<u>\$3L1-1.5L0</u>		<u> </u>		\	<u> </u>	
1. 5L	4		∇				
2. SL	S3L2LO					<u> </u>	
3. 5L	53L3-5LO						
<u>5, 5L</u>	4	/					
6 L	\$3L8-11L0	<u>\$388-22LO</u>		Χ		X	
1 1L	¥	1	V	$-\Delta$	V		
16L	5 <u>3L16L0</u>		Δ	-/	Δ		
2 <u>2</u> L	\$3L22L0	· · · · · · · · · · · · · · · · · · ·		/ \		└ <u>/</u> ∖	
33L	\$3L33L0	<u>\$3833LO</u>			//		
40L	S3L40LO	\$3 <u>840LO</u>			/_	\downarrow / \rightarrow	
50L	\$3150-75LO	\$3850LO		\·		/	
60L		\$3860LO	<u>∕</u> ∖i	/	/\	/	
75L	4	\$3875LO	<u>/ \</u>	L	/	V	
				· · · · · ·		1	
2. 5H	\leq		S3EL2-3HO	\searrow	GE1L2-3HO	\searrow	
<u>3. 5H</u>	\leq		¥	$ \rightarrow $			
<u>5.5H</u>	S3L5HO		S3EL5HO		GEILSHO	$\vdash \nearrow$	
<u>8</u> H	<u>\$3</u> L8HO		S3EL8HO		GE1L8HO		
<u>11H</u>	53L11-16HO	\$3B11-22HO	<u>S3EL11-16HC</u>	53811-22HD	GE1L11-16HO	<u> \$3811-22H</u>	
16 H	¥	└──	•	·	¥		
	S3L22H0	<u>↓</u>	S3EL22HO	¥	GE1L22HO	¥	
<u>33H</u>	53L33-40HO	S3B33HO	GE1L33-40HO		GE1L33-40HO		
<u>40</u> H	¥	53840-50HO	¥	GE1840-50HC		<u>GE1840-50</u>	
50H	S3L50-7 <u>5HO</u>	↓ <u> </u>	GE1L50-75HO		GEIL50+75HO		
60H		<u>\$3860-75H0</u>	↓	GE1860-75HO	· · · · · · · · · · · · · · · · · · ·	GE1860-75	
<u>75</u> H		₩	*	↓ ♥		*	
<u>iaoh</u>			ļ. —	ļ		ļ <u> </u>	
120H			·		· · ·		
<u>150H</u>		↓ ··		}			
<u>180H</u>	· ·		ļ . <u> </u>			·	
	··· <u></u> -	 -	<u> </u>	├─── ───	 		
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Inv.	Japanese	version	Europear without	vesion	European version with GFP		

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BASE DRIVE PCB



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3 USE AND LEVEL OF CHECKPINS

Check pin	Use and level	Addres	s(Locati	on)
·	·	~22kVA	33~75kVA	100kvA~
P¥5	Power source for dig.circuit PV5-L:4.9~5.1 VDC	30	3E(L) 7G(B)	5E(L)
PV12	Power source for analogue circuit PV12-L:11.76~12.24 VDC	9 E	5B(L) 7G(B)	9D(L) 5G(B)
NV12	Power source for analogue circuit NV12-L:-11.76~12.24 VDC	3 A	5B(L) 7G(B)	7E(L) 6G(B)
L	Ground for analogue circuit	1A,10A	8A,2E(L) 7G(B)	9E,1E(L) 5G(B)
AP5	Power source for protection circuit AP5-AL:4.9~5.1 VDC	8E	5F(B)	6H(L)
AL	Ground for AP5	8E		6H(L)
VDC	Over voltage VDC-AL :3.25 V (Trip level)	85	6F(B)	6H(L)
P	DC voltage of the intermidiate circuit P-N:approx. 300VDC max. 400VDC	6H	6F(B)	6J(L)
N2	DC current of main circuit N2-N:1.3VDC (Trip level)	7 H		
N	Ground for P and N2	8H	6F(B)	7J(L) 5F(B)
UL	Ground for base circuit of U+ DP 700-UL: 6.5~9.5V *1) (1.5~75 kVA) DP3100-UL:-6.5~9.5V (33 ~75 kVA)	2F	1F(B)	
VL	Ground for base circuit of V+ DP 80-VL: 6.5~9.5V *1) (1.5~75 kVA) DP340-VL:-6.5~9.5V (33 ~75 kVA)	3E	2E(B)	
WL	Ground for base circuit of W+ DP 900-WL: 6.5~9.5V *1) (1.5~75 kVA) DP3700-WL:-6.5~9.5V (33 ~75 kVA)	46	3E(B)	
XL	Ground for base circuit of X-(U-,V-,W-) DP10(2-XL: 6.5~9.5V *1) (1.5~75 kVA) DP4 (A-XL:-6.5~9.5V (33 ~75 kVA)	3E	6A(B)	

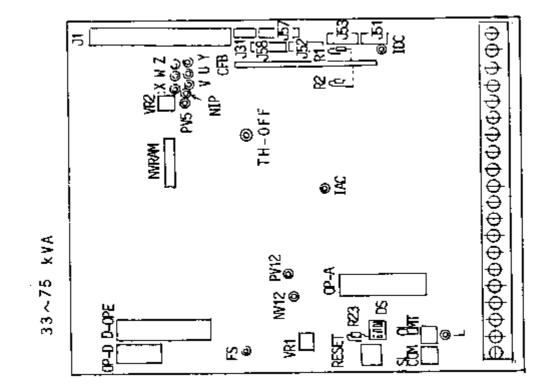
- *1) Power source of base circuit for 22kVA or less is positive voltage. Power source of base circuit for 33kVA or more is both positive and negative voltage.
 - and negative voltage. *2) L:PCB for control B:PCB for base drive

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 \boldsymbol{b} Check Address(Location) See Use and level pin page ~22kVA 33~75kVA 100kVA~ U PWM signal from control board 2D 3E(L) 1J(L)٧ 3D 3E(L) $U_{+} - L$, $X(U_{-}) - L$ 1J(L) W 2E(L) 2E(L) 3D 1J(L) V + - L, Y(V -) - LХ 1J(L) 1D W+ - L , Z(W-) - L ¥ 10 3E(L) 1J(L) Ζ 2E(L) 1D 1J(L) -5¥ V/F converter output signal FS 6A 4A (L) 6A(L) FS --- L $V_{0-L} = 10V (Dip. switch 10V)$ 5V (Dip. switch 5V) IDI~L^{= 20mA} U In case of the above FS-L : approx.390kHz TAC Motor current detecting signal 7B 24 5C(L) 7B(L) IAC-L ÍDC DC-current signal 9A 7E(L) 9A(L) IDC --L ŇIP Motor speed detecting signal 6A 5E(L) 3E(L) It is used for automatic restart NIP-L 个 **O** When it is shorted with (),electric thermal and over load limiter function would be stopped TH.OFF 6C(L) 6C 4E(L)

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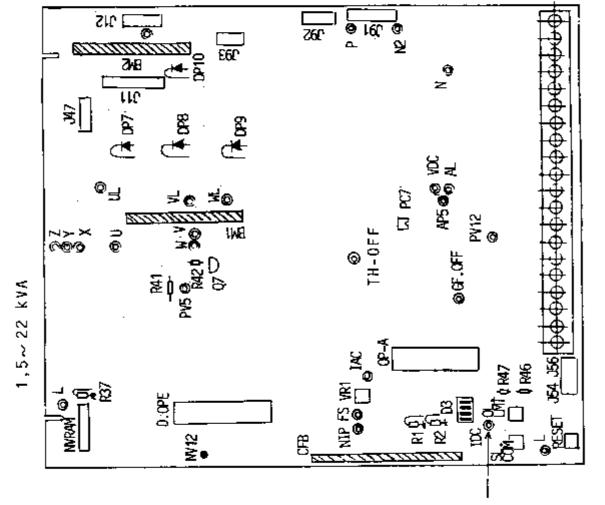


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PARTS LAYOUT OF CONTROL BOARD

CHECK PIN
CHECK LAND

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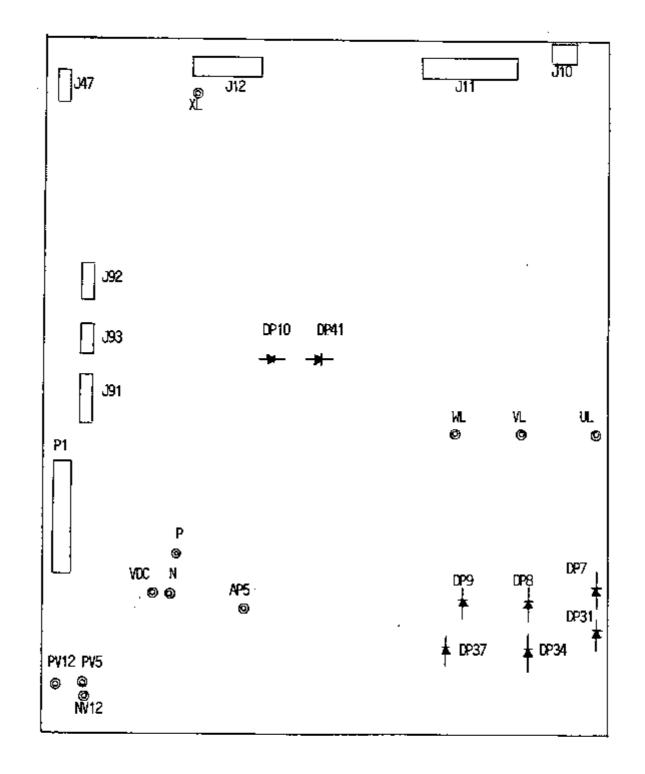
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 $33 \sim 75 k VA$

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PARTS LAYOUT OF BASE DRIVE BOARD

4 TROUBLE SHOOTING

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4-1 TROUBLE SHOOTING AND MESSAGE CONTENTS

The inverter will operate as shown in Table 10 below if abnormal. Locate the cause and take corrective measures promptly before restarting operation.

Т	a	b	1	e

Fault Message and Diagnosis

	Symp	ptom of	malfunction					
Circuit breaker MCB	Electronignetic contactor Mg	Thermal cuimy ther	Display on digital operation panel (figures)	Fault alara Fault state	Cause for fault (Message contents)	Rei	Check points	Suggested camedy
			Over.V	0	DC smoothing circuit - Overvaltage	•	Check for sudden deceleration.	Increase the decale-
					•		Check that the motor is not rotated from the load side.	The motor remost be applied to continuous regenerative load.
			OC.Accel	•	Overcurrent during Bothr acceleration (overcurrent at		Chuck for suiden sceeluration.	Increase the acceleration time.
					(overcarrent gr acceleration)		Chuck for output shortclrcuit or ground fault.	Check for the output ling (motor) and moto shortcircuit.
	1						Check that torque boost is not too high.	Reduce the torque boost.
							Check that the motor is not locked. Check that jogging frequency is too high.	Check the mator of load. Reduce the jogging frequency.
			OC.Decel	0	Overcurrent during motor deceleration (Overcurrent at	*	Chuck for suddem duceleration.	Increment the deceleration time.
					deceleration)	_	Check for output shortcircuit or ground fault.	Check the output line motor shortcircuited.
İ		-	QC.Drive	•	Overcorrent during constant operation of motor		Check for sudden chauge in load.	Eliminate sudden changes is load.
					(Overcurrent during operation)		Chack for output shortcircuit and ground fault.	Check the output line motor abortcircuit.
			Over.L	0	Inverter overload (Overloaded operation)	*	Chack that the load is not too beavy.	Reduce the load factor.
	ĺ						Chack then the electronic thermal level is correct (ndt changed).	Adjust to a proper level.

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		n of	Milfunction			-		· · · · · · · · · · · · · · · · · · ·
Clrudt Breeker Hek	Electronegueric currector Mg Thereat ralav	THKY	Display on digital operation panel ('ERROR	Fault alara Felay	Cause for fault (Message contents)	i letal	Check points	Suggested remedy
i			OH Fin	0	Temperature signifi- cancly increasing	۸	Check that the cooling fan is rotating.	Replace the cooling fan-
					(Fin overhest)		Check that the ambient temperature is not coo- high.	· · · ·
		İ	OVER C.	o	Overcuffent detection Just after power ON	*	Check that the detector current circuit is pormal.	Check abnormal conditions of current detector and PC board detector circuit.
			Under V.	0	Power supply abnormal (Vodervoltage)	•	Check that op voltage drops.	Review the power supply Aystem,
					(000010010488)		Chuck that no poor contact of MCB and Mg is found.	Replace MCB and Mg.
							Check that power has been turned OFF or instantaneous power failure has occurred during jogging.	Do not turn power OFF during jogging operation.
							Check that 100 mset or less instantaneous power failurs has occurred more than 10 times repeatedly for 10 minutes.	Re-chack the power supply system,
			Inst.P-F	•	Power supply Abnormal {Instantineous power	A	Check that no voltage drop is found.	Review the power supply system.
					failure)		Check that no poor contact of MCB and Mg is found.	Replace MC8 and Mg.
			NG FRS	a	Free-run stop Command stoormal	>	Check that the opera- tion command is given during motor free-run, and that no FRS is entered.	Do not enter operatio command, FRS during free run.
							With Free-run Stop applied, underwoltage or instantaneous power feilure has occurred.	Re-effect operation after reset.
							With Free-cun Stop appliad, power has been cut off.	le-staft operation after reset. With Fran-run Stop
							With Pres-run Stop Applied, power has been turned ON or reset operation has been performed.	applied, do not turn power CFF.

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		of maifunction	•				
Clevint breaker MCH	Electromognetic Contactor Ng Thermal rulay	; ; ; ; ; ; ; ; ; ; ; ; ; ;	. 22	Gause for (auto (Message contents)	Kesel -	Check points	Suggested rangdy
:		CPU	0	(CPV error)	Í •	Check that no large noise gource is found nearby.	Keep the noise source away from the unit.
		<u> </u>				Inverter abnormal	Repair
		DE 0 T	د 	(DC braking setting time over.)	*	Check that the DC braking external command input time does not exceed the time preset by F-22 T-DCB.	Re-set the T-DC8 tim or adjust DC braking external command inputime time to less than T-DCB.
		NG - JOG	0	(The jogging mode 15 used inadvertent 19)		Check that power has been turned ON with the jogging mode ON, commercial power supply voltage has been awitched or reser operation has been performed.	With the jogging mode ON, do not turn power ON, switch commercial power supply valtage or resat.
a :		-	-	· · ·	3	Power supply side shortcitcuit and ground fault.	Repair the short- circlif and ground fault.
i	i					insufficient HCB capacity	Encrease MCB capacity.
	 	-	; [!	Inverter module or converter module damaged.	Repair
	٩	-	-	Power failure	•	Check for the power failure.	Review the power supply system,
						Check that no poor contact of MCB and Mg is found.	Replace MCB and Mg.
ļ	a	-	-	-	c	Overload	Reduce the load factor.
						Thermal relay preset value faulty	Set the preset value to a proper one.
		NG . DB	a	OB terminal was used iosdvertently.	*	With DB ON, power has been turned ON or reast operation has been performed.	With DB ON, do not turn power ON or reset.
		UV WAIT	-	Supply voltage Jonarnai (Codervoltage)	-	When restart function was selected, supply voltage dropped to 100V or less.	Review the power supply system.
		OV. SRD	â	BRH cerminal is nor connected with 1 cerminal.	^	Check BRH-L shart- { circuited.	Connect 3RK with L.
		#0 OV.SEC	•	Overvoitage of Ioput, voitage not during dr- celeration,	^	Check input voltage dossn't enceed teted voltage +103,	Check the power supply system.

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*) 1# 220V:283VAC 3# 380V:565VAC

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	Symptom of malfunction							
Circuit breaker MCB	1100	Thermal selay Tan'	Display an digital opeation penei (?ERBOR	Fault alara relay	Cause for fault (Message contents)	Reset	Çheçk points	Suggested refiedy
			BOD Numeral		HYRAM Fellure	-	Check that no operation is performed after power on.	See page 21,22

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O: shows the equipment which seems to operate in general.

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when trouble happens.

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No motor rotates Check the wiring between inverter and motor. Chevk the input voltage whether it is rated voltage or not. Check the wiring between (ERS) and (L) on the circuit board *They should be shorted (FRS) normally close Check the wiring between (RS) and (L) on the circuit board *They should be open. -{RS}<u>-</u> - -(L} Check the operation mode in the monitor mode whether it is set according to application system. F-SET-M: OPE-key/Terminal F/R-SW : OPE-key/Terminal Check the referenc (freq.setting) signal Wh<u>en_F_SET</u>-M "OPE-key" is selected,check the FS[|| || || |Hz in the monitor mode. When F-SET-M "Terminal" is selected, check the voltage or current signal on the terminal of printed board. V₀₋₁ :0∼10VDC or 0 5VDC I_{OI-1}:4~20mA Check whether setting frequency is less than minimum frequency. *Set the frequency more than minimum frequency. Check whether LCD indication is in "Monitor" mode. *Select "Monitor" mode. In the function mode, the inverter cannot start. Check whether STOP key of Dig.Ope is pushed when F/R-SW in "Monitor" mode is selected with "terminal". *Once,run command(FW/RV) must be turned off,and then turned on again from the terminal. Check the output voltage of U-V,V-W and W-V whether they are balanced or not. Check whether setting frequency of "SPEED1"~"SPEED3" is proper value when you use multi stage speed terminal(CF1,CF2). * "SPEED1~3" must be set or multi stage speed command (CF1,CF2) must be removed. FW ON OFF OFF ON RY OFF OFF ON ON -Check whether $\begin{bmatrix} FWD\\ RUN \end{bmatrix}$ key and $\begin{bmatrix} REV\\ RUN \end{bmatrix}$ key of D-OPE are pushed together in "Ope-key" mode. -Check whether forward operation command and reverse operation command are input together in "Terminal" mode. * Only one signal should be input.

No motor accelerates U Check the referenc (freq.setting) signal Wh<u>en F-SET-M</u> "OPE-key" is selected, check the FS Hz in the monitor mode. When F-SET-M "Terminal" is selected, check the voltage or current signal on the terminal of printed board. V_{O-L} :0~10VDC or 0 5VDC I₀₁₋₁:4~20mA Check the F-05(frequency upper limiter). preset value of "F-END" in the function Check whether the mode is more than maximum frequency. Check wherther the wiring between (JG) and (L) on the circuit board is open. [JG)— · — (U)Check the load whether it is too heavy or not. *Reduce the load or adjust the overload limit level by "OL.LMT" (VR) clockwise. 100% 50% --150% OL.LMT Check whether setting frequency of "SPEED1"~"SPEED3" is proper value when you use multi stage speed terminal(CF1,CF2). * "SPEED1~3" must be set or multi stage speed command

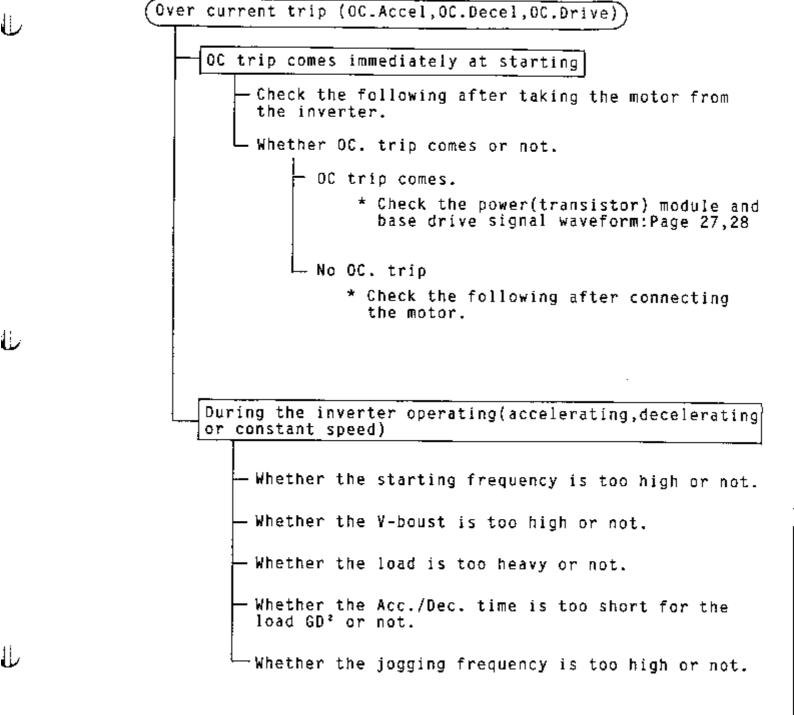
(CF1,CF2) must be removed.

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Over voltage trip

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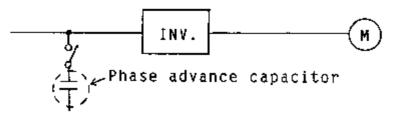
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 Check the deceleration time whether it is too short for the GD² of load or not.
 * Prolong the deceleration time.
 * Use the regenerative braking unit.

Check the power source network line whether there are phase advance capacitors on it and they are turned on/off during inverter operation or not.



* Change the wiring system with the phase advance capacitor.

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* Put the braking unit in order to suppress the over voltage.

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U Instantaneous power failure trip Check whether power source is turned on again before LCD display is turned off. * Power source should be turned on again after LCD display is turned off. Т -Power 0N 0N LCD /////ON// OFF T : 10 220V more than 4.0 sec. 3Ø 380V more than 2.0 sec. Check the magnetic contactor on the inverter primary side whether it has chattering or not. U Did the power failure occur? * If the automatic restart function after instantaneous power failure is allowed for the application system, use the automatic restart function in the function mode F-28. 00000101 F-28 switch 00: Not available restart 10: Available restart Under voltage trip Check the power source voltage whether they are less than protection level or not. 10 220V 1.5~3.5kVA : 150~160 VAC 30 380V 2.5~75kVA : 280~320 VAC U 38 380V 100~180kVA : 323 VAC Check the transient voltage drop by rush current into the smoothing condenser or starting current of the motor. * Increase the power source capacity. * Use the restart function on the F-28 F-28 switch 00000101 00: Not available restart 10: Available restart Check the magnetic contactor whether it has chattering or not.

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(Overheat trip)

- Whether cooling fan in the inverter is rotating or not.
- Whether air inlet and exhaust ports on the panel box is blocked or not.
- Whether the cooling air path is blocked or not.
- Whether the temperature in the panel box is less than specified value or not. * If it is too high,improve the cooling. :See page 59~62,selection of ventilation

(Overload trip)

L

- Check the electronic thermal level in the function made F-23 whether it is proper for the load condition or not.
- Check the overload limiter level whether it is proper for the load condition or not.
 * This level can change with "OL.LMT".

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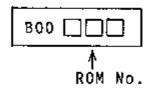
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<u>4-3 NVRAM (Non Volatile EEPROM)</u> failure

When the following phenomenon has been appeared, replace the NVRAM. LCD indication on the digital panel is:



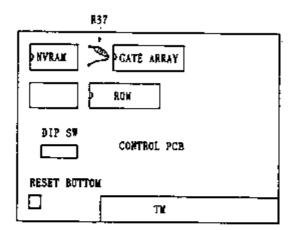
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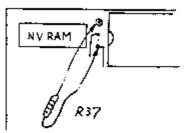
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And no operation is performed after power on. No operation is performed even forced reset or even when the initial setting is performed.





Solder a resistor R37(10 k Ω 1/3W) if it is not mounted on the PCB. After replacing the NVRAM, return the setting data to the initial (factory) setting according to "How to return the setting to the initial setting". After that, re-program the data according to customer's setting.

Note: When no data is stored in memory after various operations are performed although the data is set and the \boxed{STR} is depressed, it should be noted that this abnormality is due to the following reason.

Reason Set the data and press the STR, then press the Forced Reset (or short-circuit RS-L terminals) and cut off the power supply.

Countermeasures ... Set the data and press the STR to store it in memory, then turn power OFF once, and store the data in an element to save it even after power OFF.

21

4-4 HOW TO RETURN THE SETTING TO THE INITIAL SETTING

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When retuning the setting to the initial setting for some reason, flolow the steps below.

① Turn power on. ② Set the right side of DIP SW on PCB to "ON".

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	Turn this ON. ON OFF
3	With the MON FUN STR keys on the digital operation panel
	pressed at the same time, turn the forced reset button OX.
۹	After resetting , release these 3 keys pressed in 1 or 2 sec.
	At this time, BOOERE (ROM NO.) is displayed and operation steps.
	If FM 000.0Hz is displayed, it means that these 3 keys has
	been released too early. Repeat steps ② - ④ above again,
NOTE:	But XVRAM failure makes BOODER remain displayed even for the
	above steps.
	Good NVRAM : Displays FM 000.0Hz by forced reset
	Failed NVRAM : Displays still $BOO(Biff)$ by forced reset

- Turn power OFF or turn the forced reset buttom or switch ON.
- Turn DIP SW OFF.
- ⑦ Turn power ON again, and check that the data corresponds to the standard perset value(factory setting).

5 mearsurment

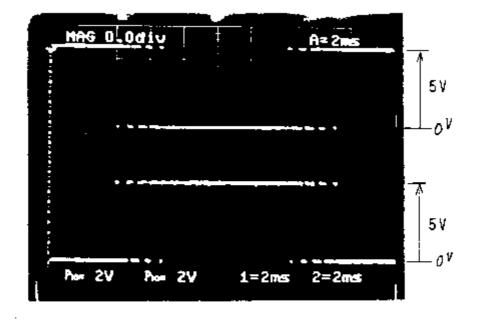
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5-1 PWM OUTPUT SIGNAL WAVEFORM FROM THE CONTROL BOARD

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- The PWM control signal can be checked with the check pins,U~Z, on the control board.
- Check pins and waveform

	Pin		Phase
U	`	L	υ÷
٧	<	L	¥+
W	<u><</u>	L	₩+
X		L	- U
Y		L	V -
Z	-	L	₩-



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The pulse number would be changed according to output frequency.
 When the PWM signal is not proper, the control board should be changed.

- 5-2 MOTOR CURRENT SIGNAL
- The motor current signal which is rectified can be checked with check pins on the control board.

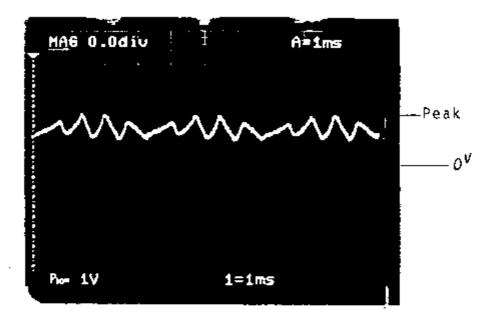
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- This signal is used for 0.C,0.L and stall prevention detection.
- The signal level is: Rated current of the inverter / 2y DC

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Checkpin and waveform

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Trip level

kVA	OC.Accel.	OC.Decel.	OC.Drive	Motor cirrent
1.5~3.5SF3	4.4 V	4.4 V	4.4 V	220%
2.5~5.5HF3	3.887	3.88V	3.88¥	180%
8~180HF3	3.6 V	3.6 V	3.6 V	180%

* THe trip level is the peak value of this signal.

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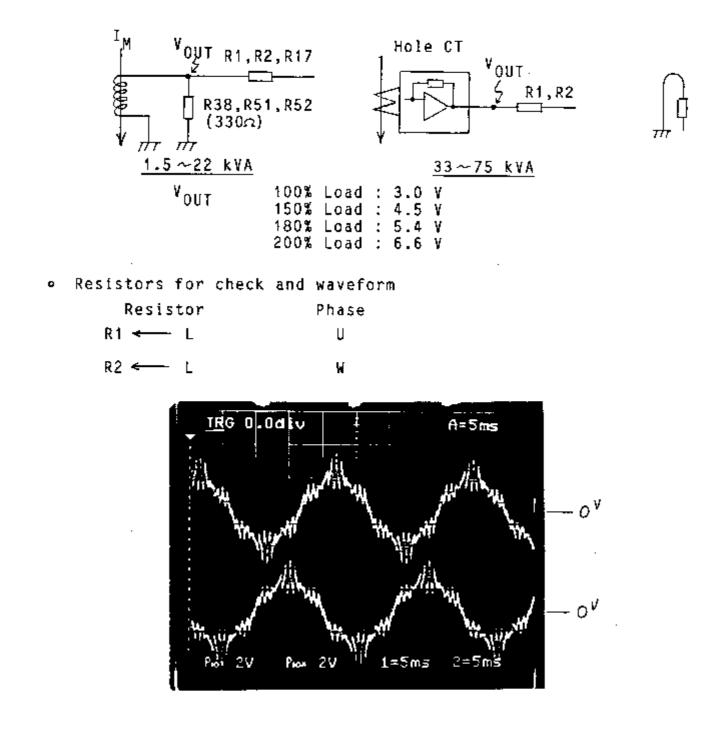
- The motor current waveform can be checked with resistors on the control board. The signals come from AC/CT of the output.
- AC/CT output

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* The waveform would be changed according to output frequency.

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5-4 DC-CURRENT SIGNAL

- The DC-current of the intermidiate circuit can be checked with the checkpin on the control board or base drive board.
- The signal is used for 0.C trip.
- Checkpin and waveform

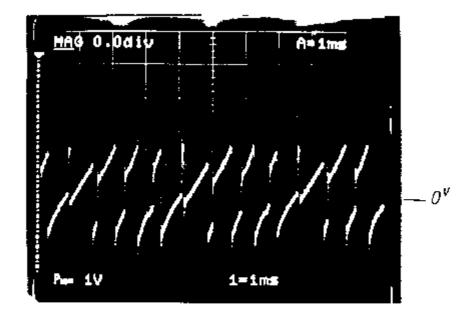
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N2 – N (on the control board) : 1.5 \sim 5.5kVA IDC – L (on the control board) : 8 \simeq 75 kVA



∘Trip level

Inv. Model	1.5~3.5SF3 E 2.5~5.5HF3 E	8~33LF3 8~40HF3 E 100~180HF3 E	40LF3	50~75LF3	50 ~ 75HF3 E
Trip level	1.3V	6.6V	7.9V	7.6V	7.17
Checkpin	N2 — N		IDC — L		

5-5 Output signal of base drive

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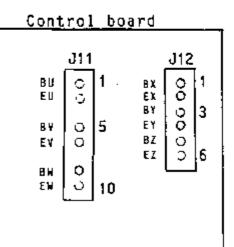
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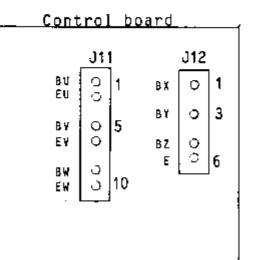
1 1.5,2.5kVA(SF3)

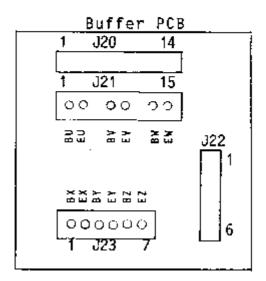
<u>2 3.5kVA(SF3),2.5~8kVA(HF3)</u>

Control board J11 J12 вU Ó 1 0 1 BΧ £υ Q, 0 3 В۲ 0 0 Β¥ 5 0 0 E۷ ВŹ 6 Ε 0 8W εW С. 10

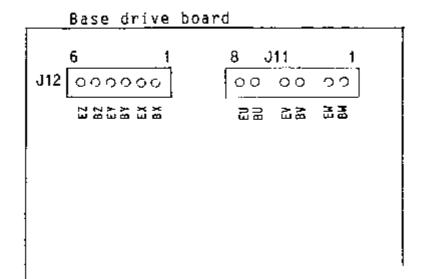


3 11~22 kVA





4 33~75 kVA



U <u>1 1.5,2.5kVA(SF3)</u> BU — Ευ (U+)G) (R) BV — EV (G) (¥+) V) (R) BW — EW (¥) **(₩+)** (BL) (R) 8X — E (U-) (BR) (W) BY — E (V-) (Y) (W) **BZ** — Ε (W-) (O) (W) 2 3.5kVA(SF3),2.5~8kVA(HF3)

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$$\begin{array}{c} \mathsf{BU} - \mathsf{EU} & (\mathsf{U}^{+}) \\ \mathsf{G} & (\mathsf{R}) \\ \mathsf{BV} - \mathsf{EV} & (\mathsf{V}^{+}) \\ (\mathsf{V}) & (\mathsf{R}) \\ \mathsf{BW} - \mathsf{EW} & (\mathsf{W}^{+}) \\ \mathsf{BU} & (\mathsf{R}) \\ \mathsf{BU} & - \mathsf{EV} & (\mathsf{W}^{-}) \\ (\mathsf{BL}) & (\mathsf{R}) \\ \mathsf{BZ} - \mathsf{EZ} & (\mathsf{U}^{-}) \\ (\mathsf{Y}) & (\mathsf{W}) \\ \mathsf{BZ} - \mathsf{EZ} & (\mathsf{W}^{-}) \\ (\mathsf{O}) & (\mathsf{W}) \end{array} \right] \mathsf{J}12$$

80 — EU (U+) (G) (R) ΒΫ — ΈΫ (¥¥) J 21 V) (R) BW — EW (V) (W+) (BL) (R) BX - EX (8-) (BR) (W) J 23 BY - EY (Y -)(W) (Y) BZ — EZ (W-) (0) (W)

BU — EU (U+) (G) (¥+) J11 (V) (R) BW — EW (W+) 0٧ (BL) (R) 8X - EX (U-) (BR) (W) -97 J12 ī BY - EY (V-) Ý (Y) (W) BZ - EZ (W-) No operating Operating (W) (0)

- White

Yellow

W

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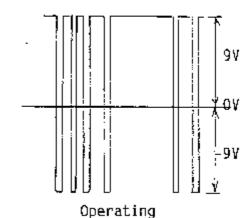
Wiring color

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No operating

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0.81

Operating

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5-6 How to check converter modules

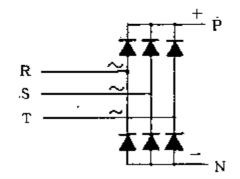
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The converter module can be checked to a certain extent at terminals.

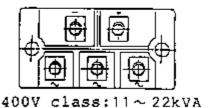
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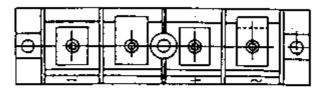


200V class:Less than 3.5kVA





400V class:33~100kVA



400V class:120~180kVA

Converter module circuit diagram and top views

Turning off power source,make sure that voltage between P and $^{\rm N}$ is below 15V before operation.

Remove the wirings connected to the converter module and check it alone.

Measure with the tester set to larange.

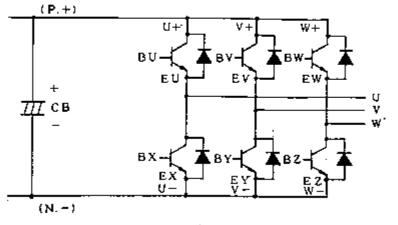
Colors of tester terminals BlackRed	Resistance value
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	50kp or more
$\begin{array}{c c} P(+) & \longrightarrow & R(\sim) \\ \hline P(+) & \longrightarrow & S(\sim) \\ P(+) & \longrightarrow & T(\sim) \end{array}$	50ka or more
$\begin{array}{c c} R(\sim) & \longrightarrow & P(+) \\ \hline S(\sim) & \longrightarrow & P(+) \\ \hline T(\sim) & \longrightarrow & P(+) \end{array}$	50g or less
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	50م or less
$\begin{array}{c c} R(\sim) & \longrightarrow & N(-) \\ \hline S(\sim) & \longrightarrow & N(-) \\ \hline T(\sim) & \longrightarrow & N(-) \\ \end{array}$	50kn or more

C

~:alternation terminal

If the resistance value is not proper,replace the diode module.
* Failure symptom : MCB trip (shortcircuit of Power module)

The inverter module can be checked to a certain extent at terminals.



Inverter module circuit diagram

Turning off power source,make sure that voltage between P and N is below 15V before operation. Measure with the tester set to 10 range

Measure with the tester set to 1Ω range.

(Easy method to check inverter module without disassembly)

Color of tester terminals BlackRed	Resistance value	Check spot
P> U		Ŭ+
P → V	50k A or more	V+
$P \longrightarrow W$	<u> </u>	W+
N U		U–
<u>N</u>	50 n or less	<u>y-</u>
<u>N</u>	1	W -
U> P		<u>U+</u>
V P	50 a or less	V+
W> P	1	W+
<u> </u>		U-
<u>v </u>	50kn or more	<u>V</u> -
N		W

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(Check after disassembly)

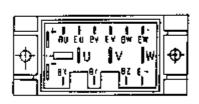
Color of tester termina BlackRed	ls Resistance value	Check spot
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	100 or less	<u> </u>
BW		<u>₩+</u> U-
BY V	100 p or less	<u>V</u> -
$\begin{array}{c c} BZ & \longrightarrow & W \\ \hline U & \longrightarrow & BU \end{array}$		W U+
$V \rightarrow BV$ W $\rightarrow BW$	50~200 <i>g</i> or more	V+ W+
U BX		Ŭ-
W> BZ	50~200Ω or more	<u>V-</u> W-

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* Failure symptom : Over current trip causes without connected to a motor.

Top views of inverter modules

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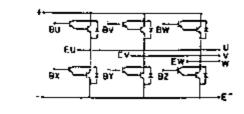


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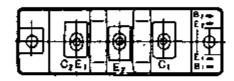
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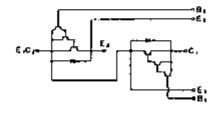
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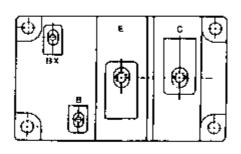


200V class:Less than 2.5kVA

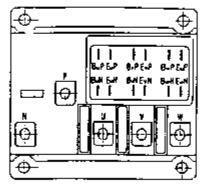


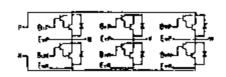


400V class:8~16kVA

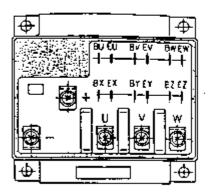


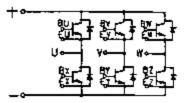
400V class:50~ 180kVA



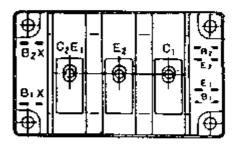


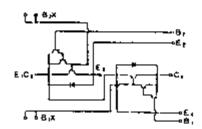
200V class:3.5kVA



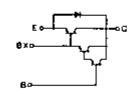


400V class:5.5kVA





400V class:22~40kVA



31

6 Appendix

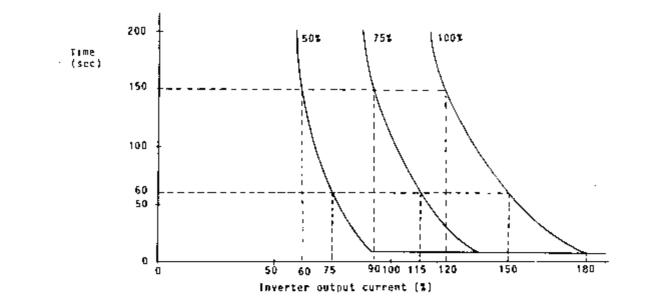


6-1 E-THERM FUNCTION (F-23)

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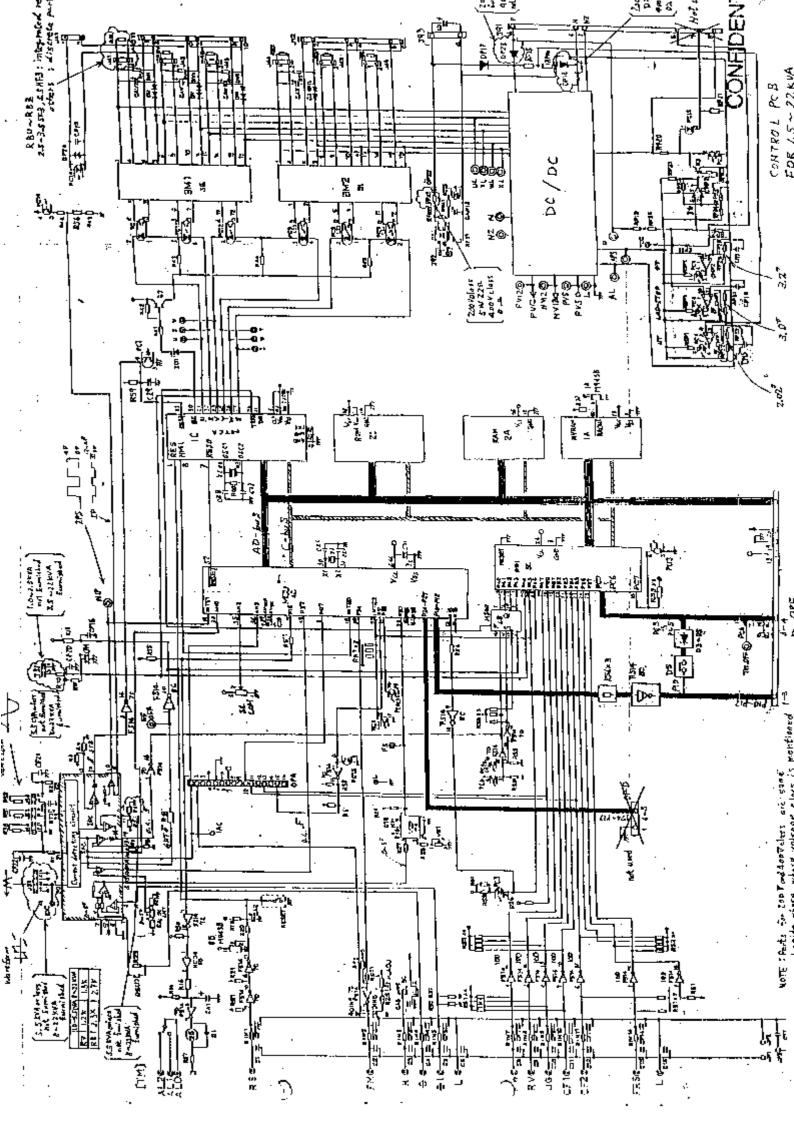
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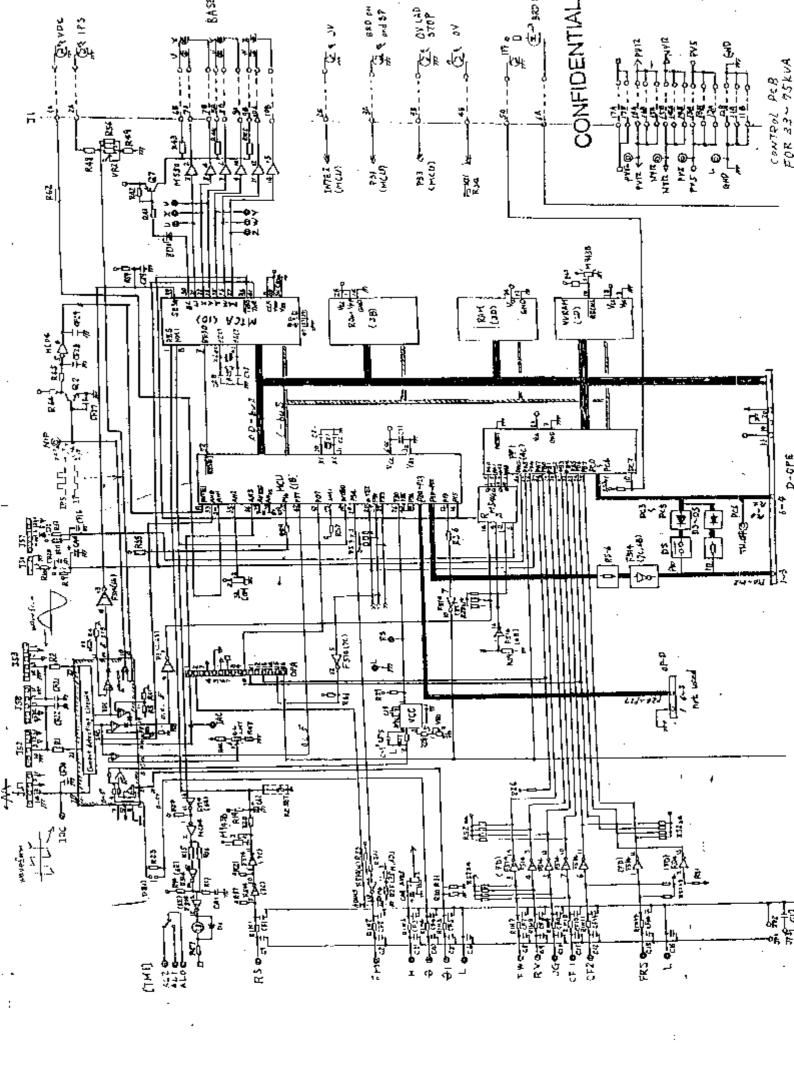
The protection characteristics of the electronic thermal can be changed by OPE-key. The characteristics is approximately as follows:



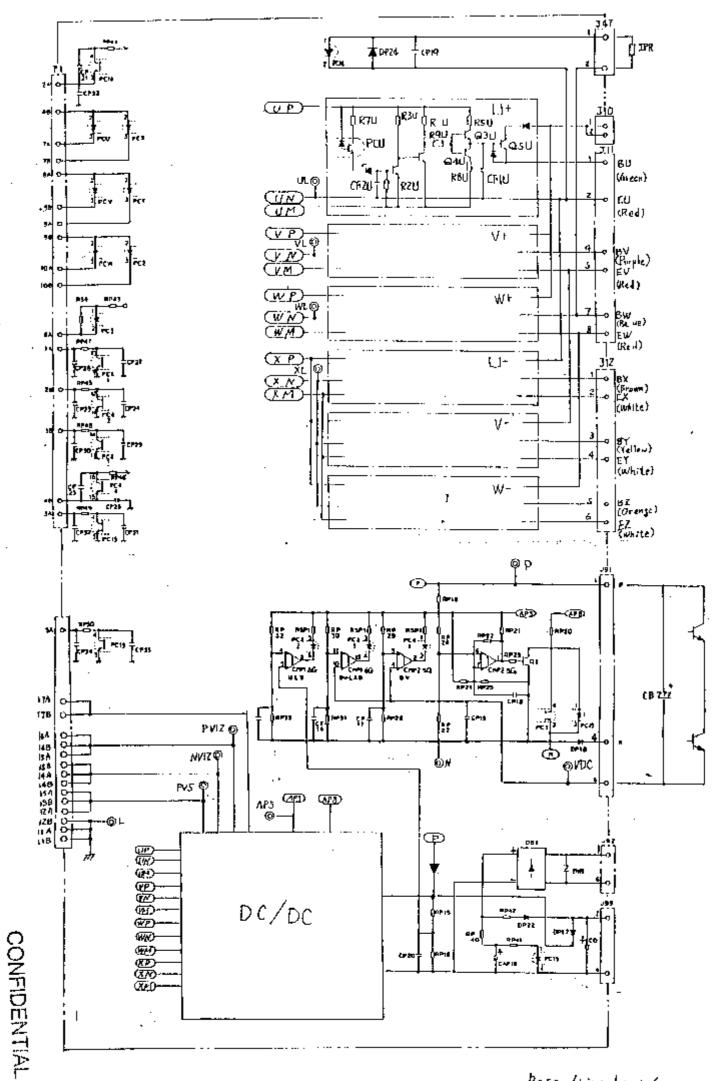
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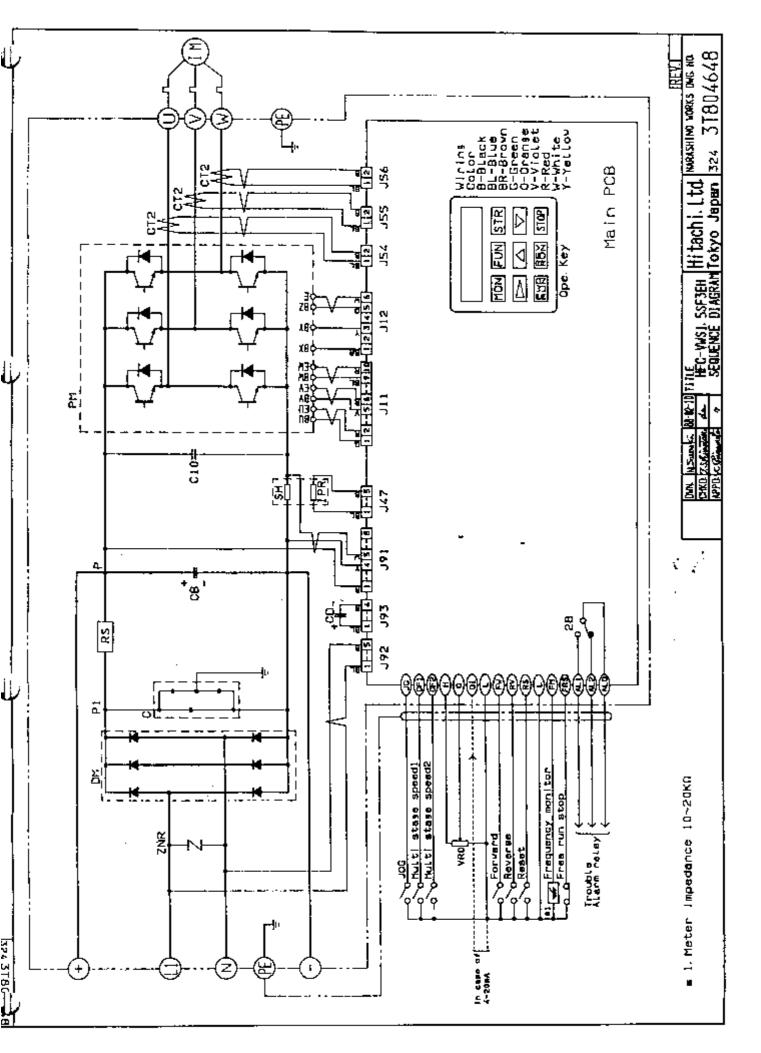


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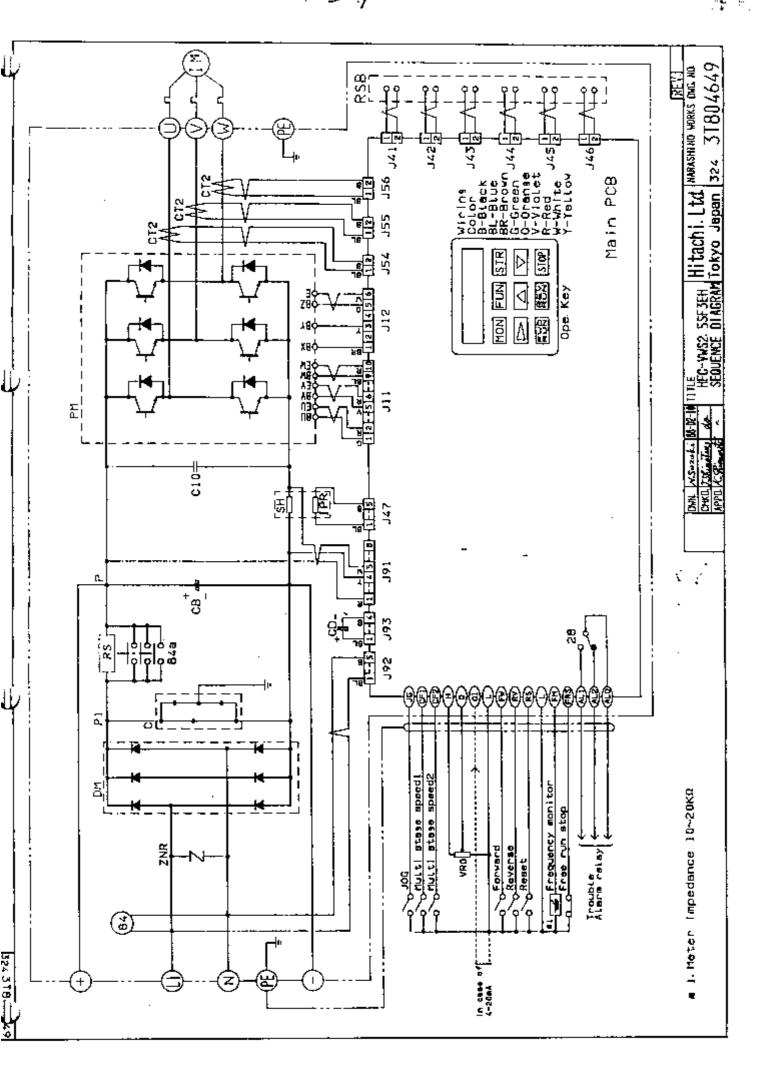


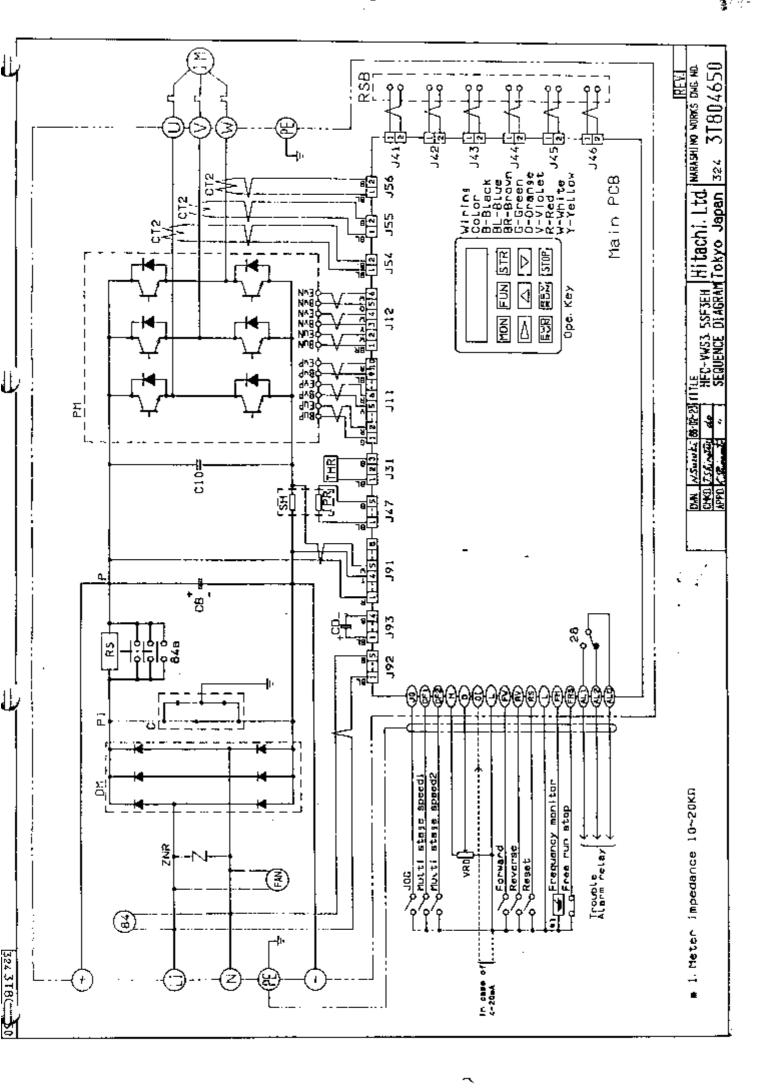
Base drive bourd 33 ~ 75 kvA

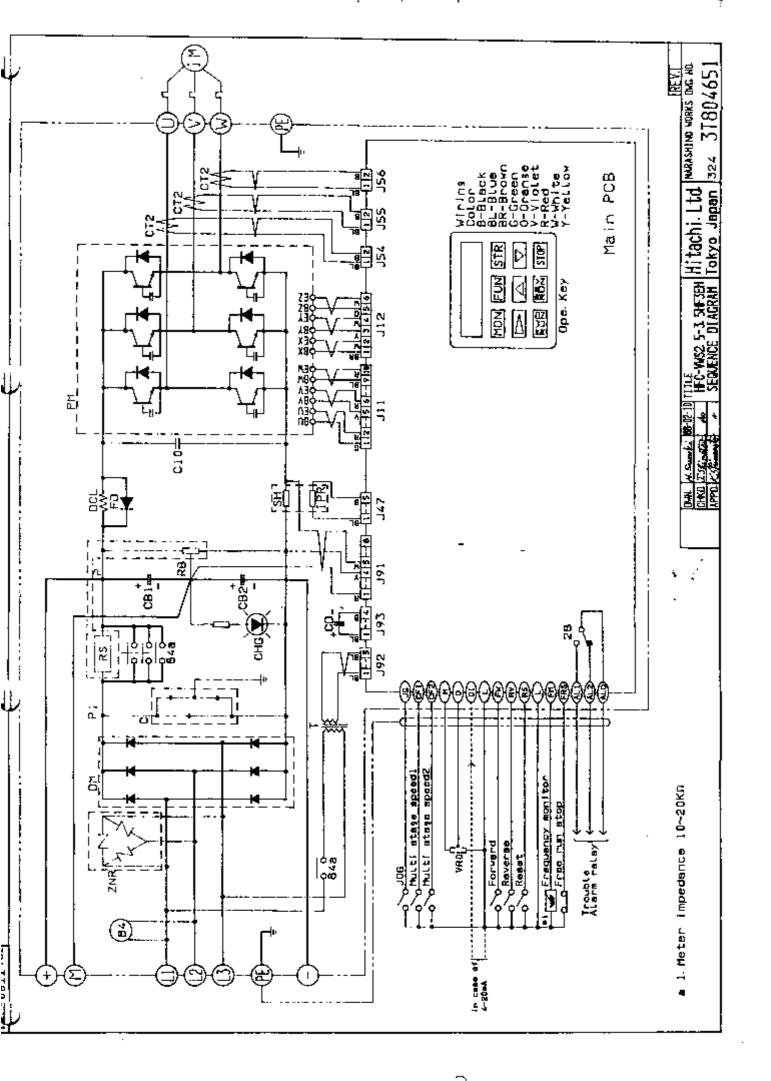




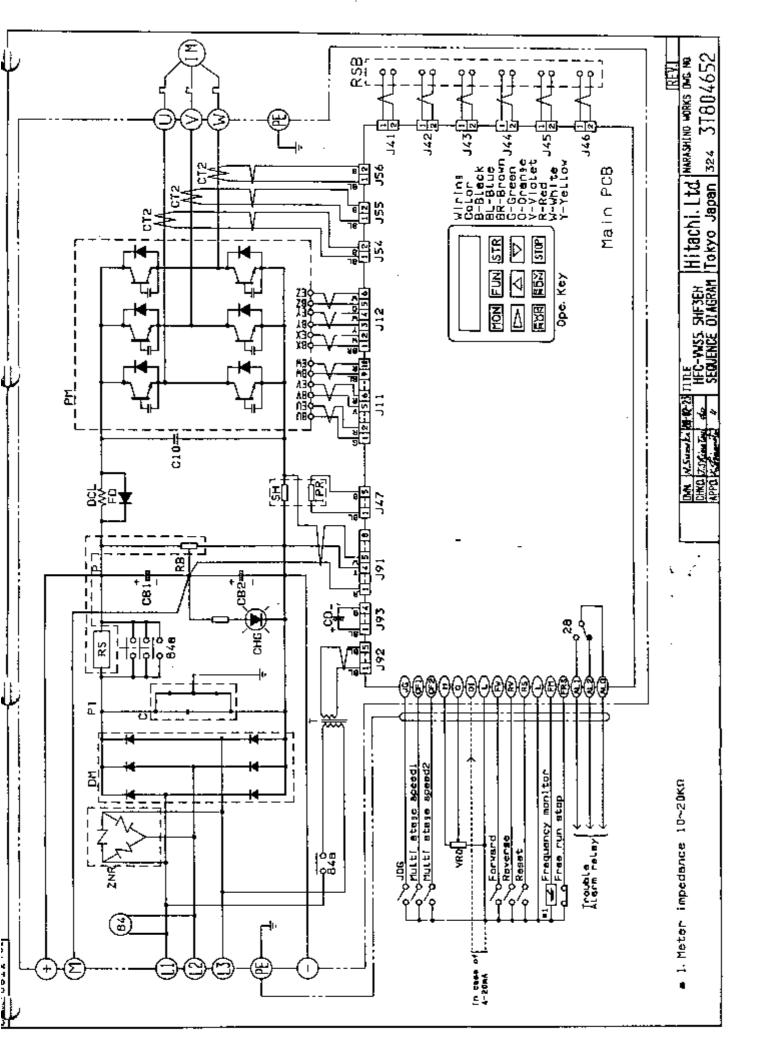
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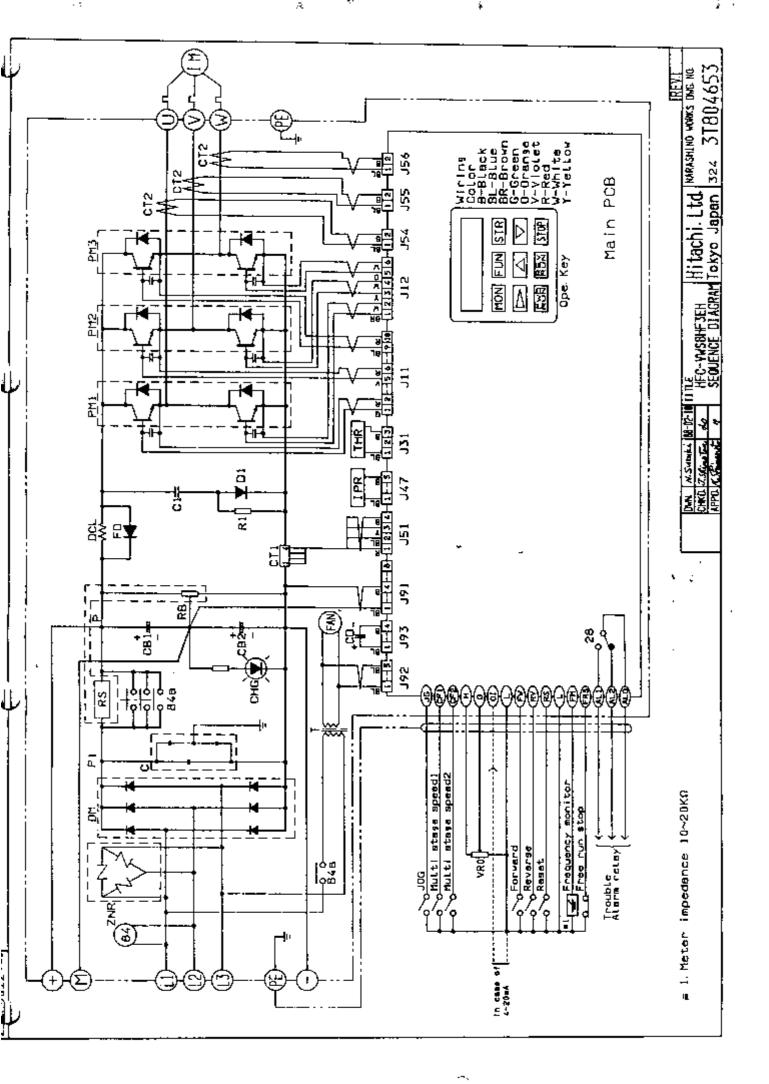


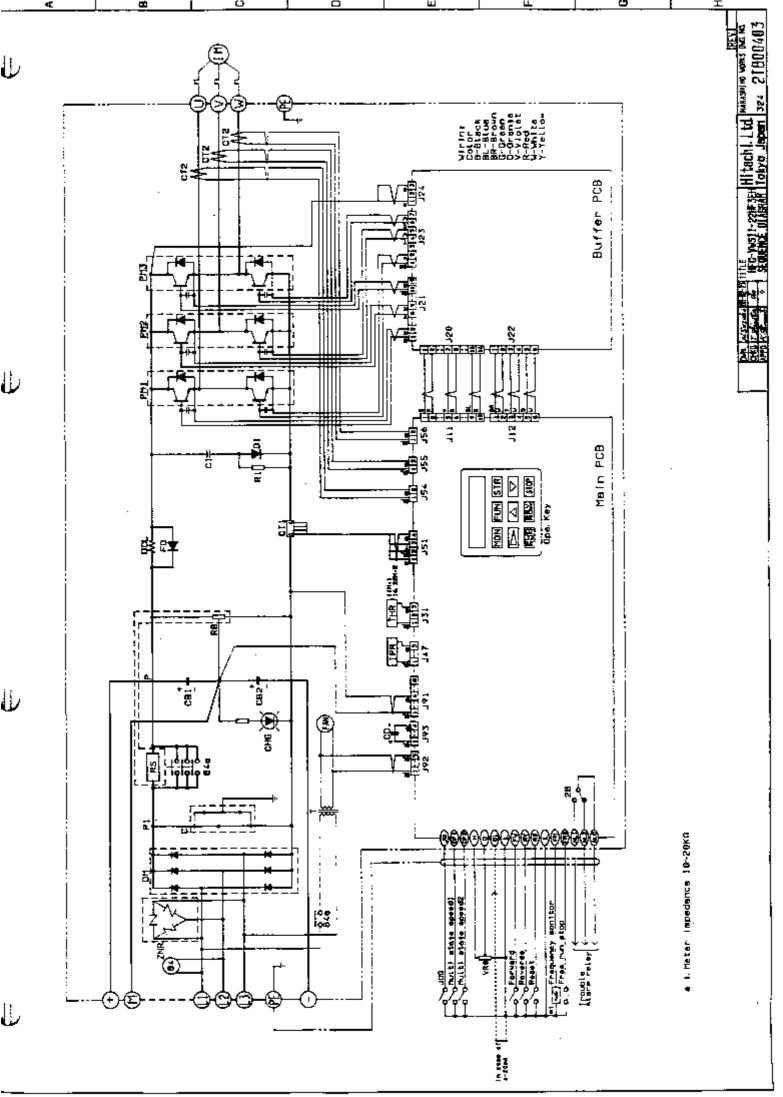


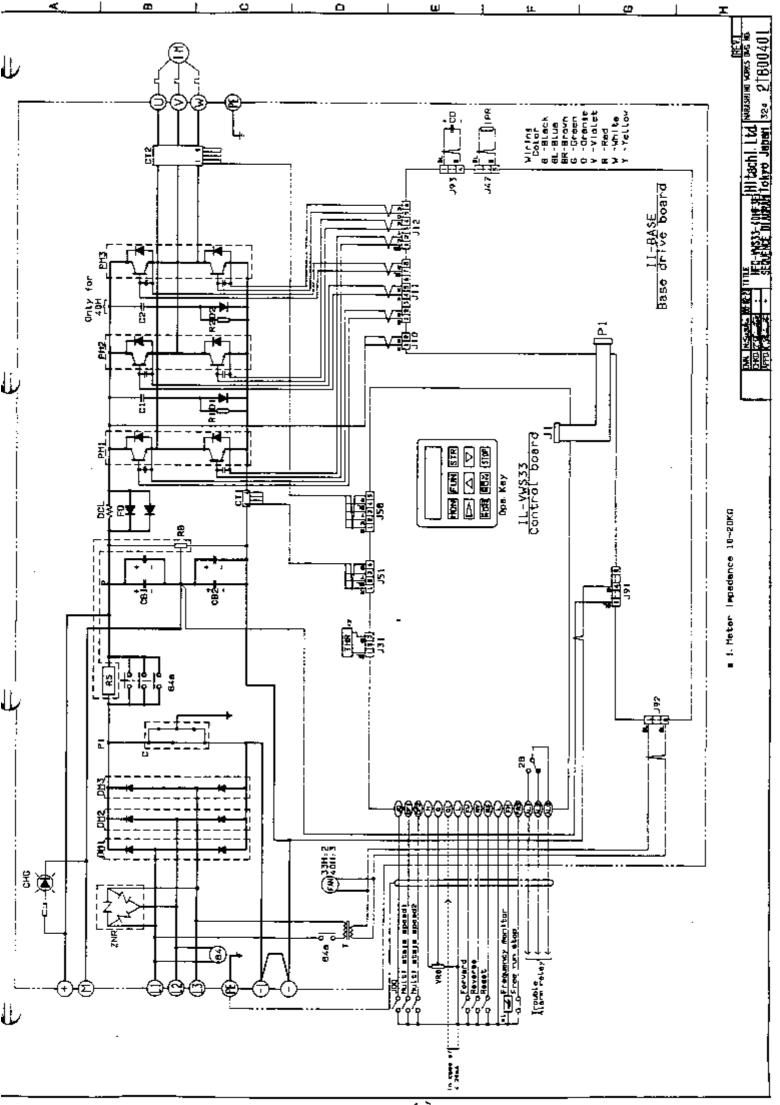


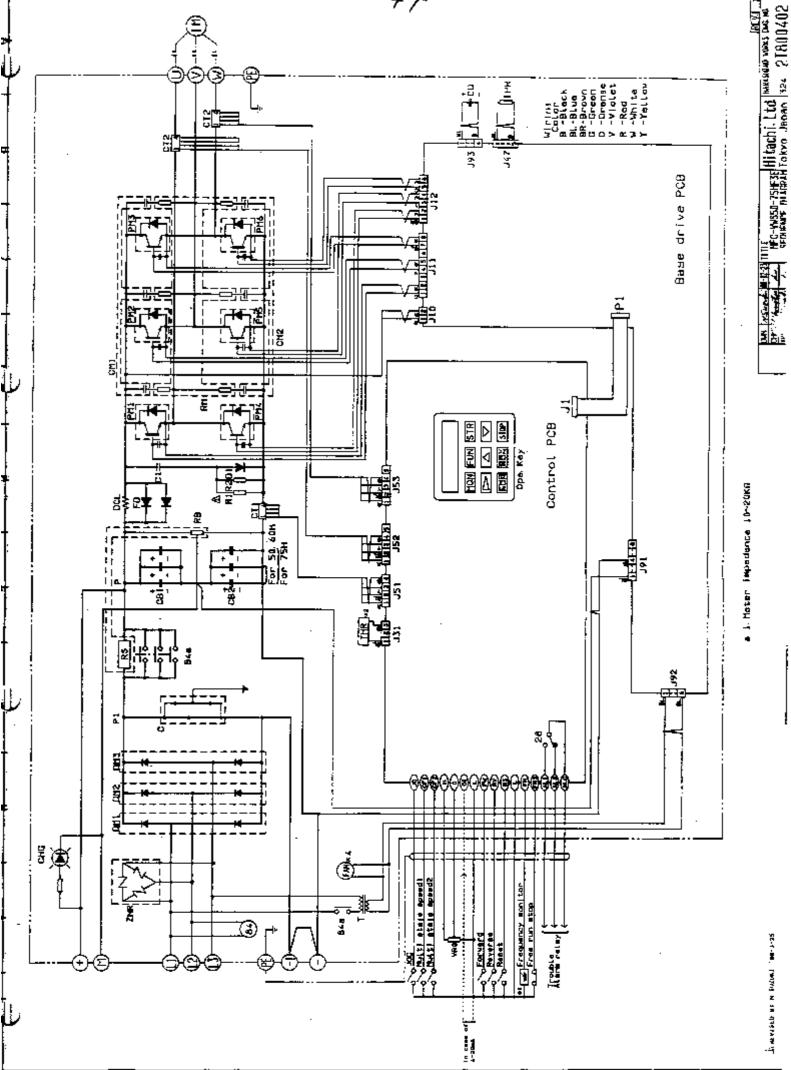


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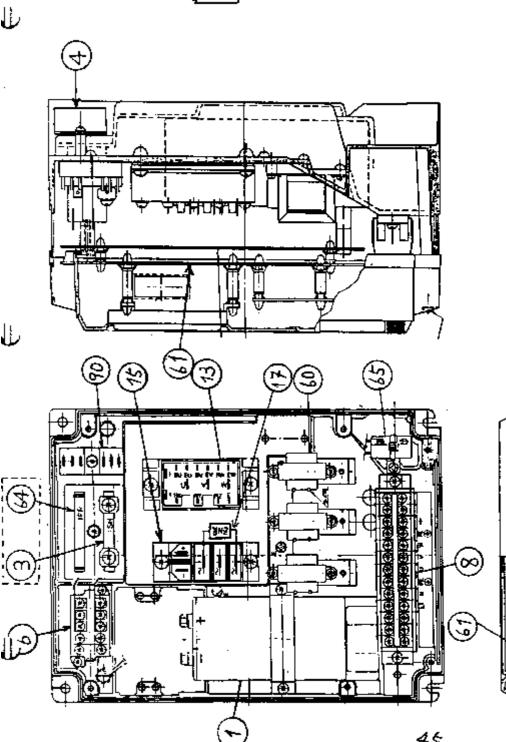


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0 N	MARK	PARTS NAME	Q'TY/UN
-	CB	SMOOTHING CONDENSER	-
		-	
÷	ЯH	SHUNT RESISTOR	¥.
\$	RŚ	CURRENT LIMITING RES,	+
æ	84	MAGNETIC CONTACTOR	*-
Ð	Ŧ	TERMINAL	
		(H) 3 E 1 2 . 2 . 7 M	
:			
Εt	μd	TRANSISTOR MODULE	-
15	MQ	DIDDE MODULE	*-
		Ŧ	
\$	ZNR	SURGE ABSOBBER	*
			-
+			
60	ст2	CURRENT TRANSFORMER	2 (3)
61	PCė	PRINTED BUARD (Control)	Ť
64	1 P.R	RESISTOR	1
65	CD	CONDENSER	1
\$	RS8	BASE DRIVE RESISTOR	۲
		- Only 2.5 SF3E(H)	



HEC-VWS 1.5, 2.5 SF3E (H)

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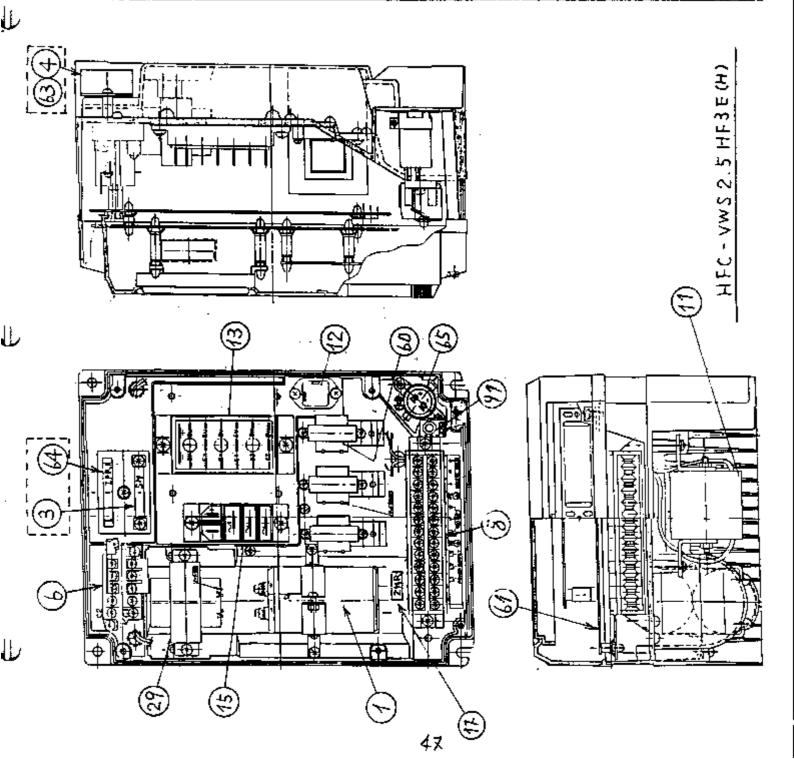
(1) (2) (3) (4) (4) (4) (5)
HFC-VWS3.5 SF3E(H)
HFC-WS3.5 SF3E (H)
HFC-VWS3.5 SF3E (H)
HFC-VWS 3.5 SF3E (H)

d,1 (/ GN () U 2(3) Ν ~ * 5 7 7 Ś 7 ~ 1 7 CURRENT LIMITING RES. SMOOTHING CONDENSER PRINTED BOARD (Control) CURRENT LRANSEORNER MAGNETIC CONTACTOR SHUNT RESIGTOR TRANSISCOR MODULE BALANCE RESISTOR FLY NHEEL DIODE PARTS NAME SURSE ABSOBBER CHARGING LAMP DIODE MODULE TRANSFORMER DC REACTOR CONDENSER TERMINAL RESISTOR N A A N CT 2 CHG 3 N 2 PCB RB Зd I 001 £ с) Ц) ž I 2 ž H М 9 ⊢ 07 £3 ---6 2 2 ŝ 읤 5 ŝ

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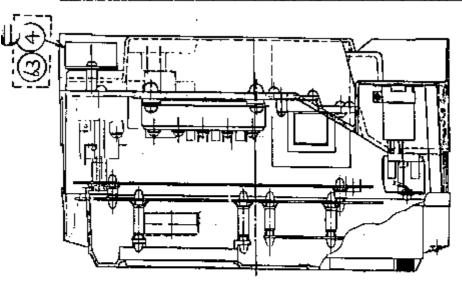
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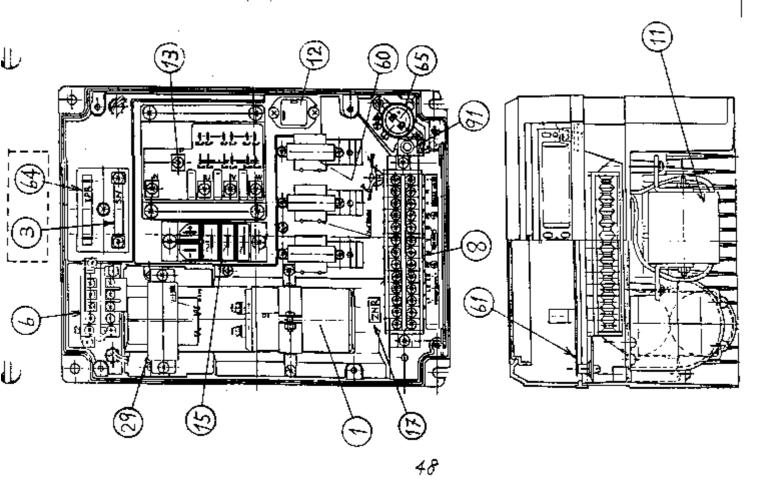


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1110/110	N		-	4	4	Ł		*	-	ł	.	ł		~			2 (3)	*-	~	4	~-	1		' Ţ	
PARTS NAME	SMOOTHING CONDENSER		SHUNT RESISTOR	CURRENT LIMITING RES.	C CONTACTOR	TERMINAL		DC REACTOR	FLY WHEEL DIODE	TRANSISTOR MODULE	DIODE MODULE	SURGE ABSOBBER		I RAN SFORMER			CURRENT TRANSFORMER	PRINTED BOARD (GALFOL)	BAIANCE RESISTOR	RESISTOR	CONDENSER	CHARGING LAMP			
MARK	80 U		ŞН	RS	84	I.M		БСL	FD	Md	MQ	ZNR		-			ст 2	PC3	RB	1 P.R	65	C X G	:		
0 ž	-		÷	4	2	-	1	=	12	£1 .	15	17		29		<u> </u>	50	51	67	54	55	5			



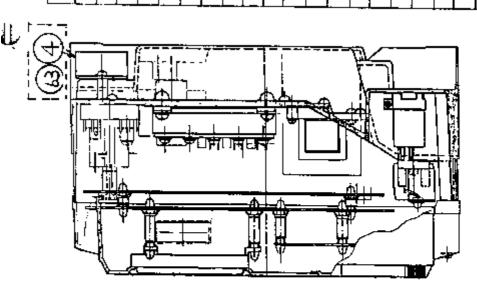
HFC - VWS 3.5 HF3E(H)



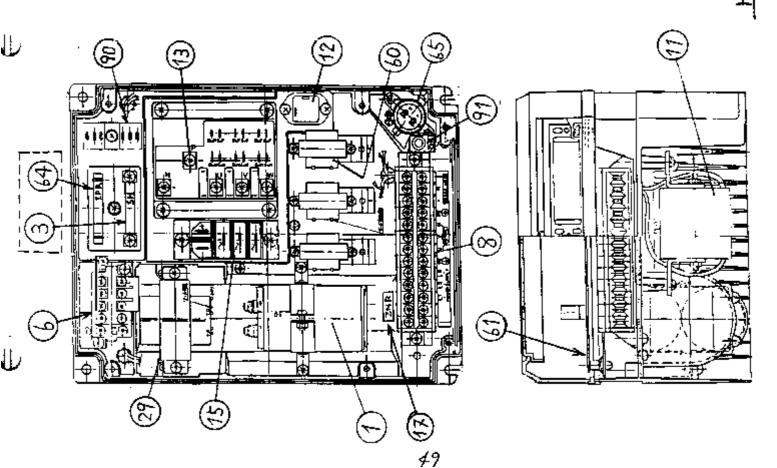
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0.1.1/181	~		•		-	~-	-	-	-	-	1		₹			2(3)	**		1	4	1	-		
PARTS NAME	SMOOTHING CONDENSES		SHUNT RESISTOR	CURRENT LIMITING RES	MAGRETIC CONTACTOR	TERMINAL	DC REACTOR	FLY WHEEL DIODE	TRANSISTOR MODULE	DIODE MODULE	SURGE ABSOBER		TRANSFORMER			CURRENT TRANSFORMER	PRINTED BOARD (Control)	BALANCE RESISTOR	RESISTOR .	CONDENSER	CHARSING LAMP	BASE RESISTOR		
MARK	C.B.		ऊ	RS	84	TM	 0CL	F0	PM	NO	ZNR	 	г			CT 2	PCB	RB		CD	CHG	RSB	 	
9	-		m	a .	9	8	-	2	13	12	-		29			<u>б</u> П	61	63	64	65	91	90		

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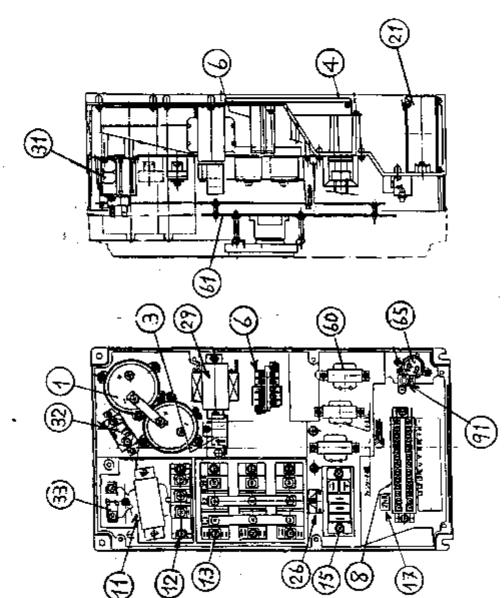
HFC - VWS 5. 5 HF3E (H)

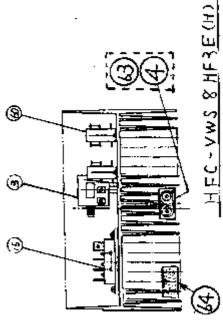


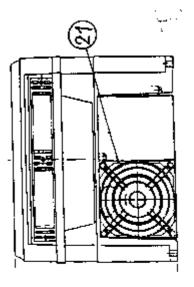
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PARTS NAME	SMODTHING CONDENSER		CURRENT TRANSFORMER	CURRENT LIMITING RES	MAGNETIC CONTACTOR	TERMINAL	DC REACTOR	FLY WHEEL DIODE	TRANSISTOR MODULE	DIODE MODULE	SURGE ABSOBBER	COOLING FAN	THERMAL RELAT	TRANSFORMER	SNUGBER CONDENSES	SRUBBER DIDDE	SNURGER RESISTOR		URRENT TRANSFORMER	PRINTED BOARD(Caller)	BALANCE RESISTOR	RESISTOR	CONDENSER	CHARGING LAMP		
MARK	CB	- 	 CT 1	RS	84	MT	DCL	۶D	μų	нO	ZNR	FAN	THR	-	C1	10	ę 1		CT 2	PCB	R B	1 P.R	8	CHG		
NG	-		Ē	4	. un	8	11	12	13	51	17	21	26	29	11	20	33	ļ	50	61	Eŷ	64	55	91		

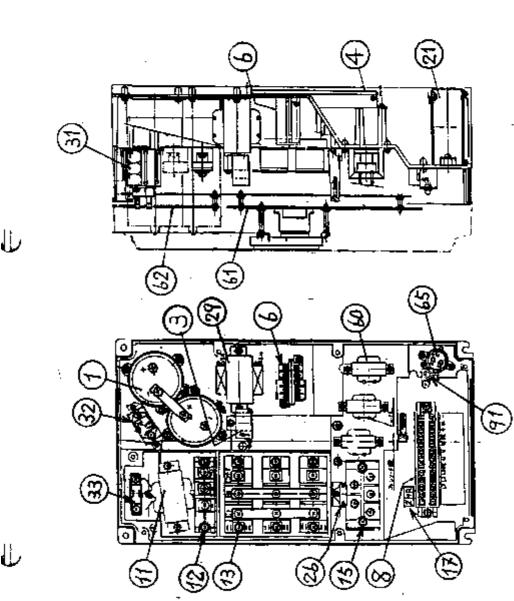


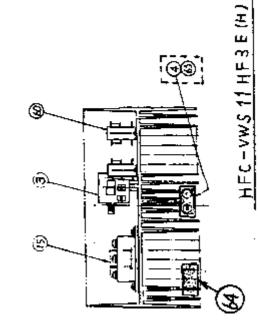


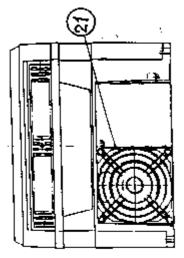


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PARIS NAME	SMOOTHING CONDENSER	r	CURRENT TRANSFORMER	CURRENT LIMITING RES	MAGNETIC CONTACTOR	TERMENAL	DC REACTOR	FLY WHEEL DIDDE	TRANSISTOR MODULE	DIDDE MODULE	SURGE ABSOBBER	COOLING FAN	THERMAL RELAY		TRANSFORMER	SAUBBER CONDENSER	SAUBBER DIODE	SHUBBER RESISTOR		LUXKERI IKANJ <u>rukaca</u> Dointen Daada <i>ta</i>	2	KE3131UK	<u>م</u> اً	CHARGING LAMP	BALANCE RESISTOR
****	CB		cr1	RS	84	H	0CL	£0	Md	M	ZNR	FAN	ТНЯ		F	10	10	R 1		2 0.00	80 A	¥	0	снG	83
e e	_		Ē	- -	œ	8	-	12	13	15	17	21	26	i	29	16	32	33			2		65	<u>5</u>	63

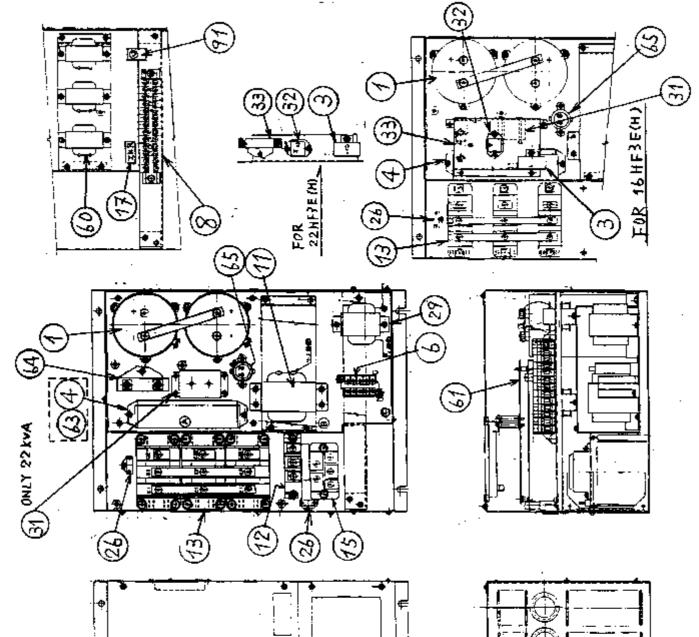
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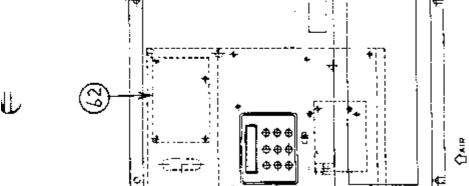




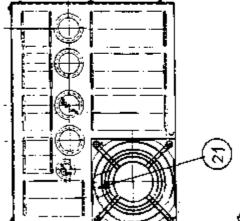


~	CHASSING LAMP	ςΗG	16
~	CONDENSER	CD.	65
	RESISTOR	[PR	64
4	BUFFER PCB	PCB	23
*	PRINTED BOARD (CONCONT)	PC3	61
2 (3)	CURRENT TRANSFORMES	c12	60
4	BALANCE RESISTOR	92	£9
1	SNUBBER REALSTOR	j ji li	
4	SQUID ESHONKS	10	2
1	SNUBBER CONDERSER	5	91
4	TRANSFORMER	-	53
	i		
2	THERMAL RELAY	H H	26
1	COOLING FAN	FAN	21
1	SURGE ABSOBER	2 M R	17
	_		
1	DIDDE WOONTE	٣O	5
3	TRANSISTOR MODULE	Ыđ	13
1	FLY WHEEL DIODE	FO	12
4	DC PEACTJR	001	1
		· ·	
1	TERMINAL	τM	æ
1	MAGNETIC CONTACTOR	84	ę
1	CURRENT LIMITING RES.	Sa	4
_1	CURRENT TRANSFORMER	c1 -	-
2	SMOOTHING CONDENSER	CB	-
2500	PAGTS MAME	MARK	0*
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HFC - VWS 16, 22 HF3E(H)

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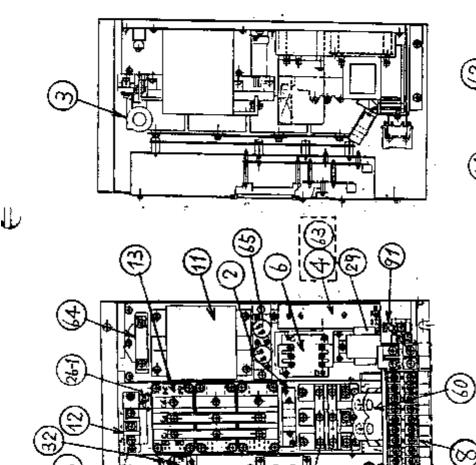
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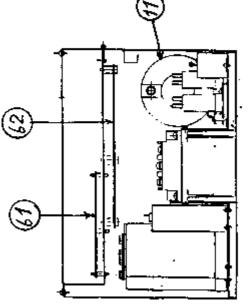
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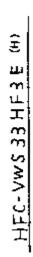
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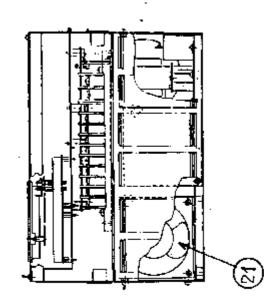
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PARTS NAME	SMOOTHING CONDENSER	L ONLY 33HF3EH	CT FOR G.F.P	CURRENT TRANSFORMER	CURRENT LIMITING RES.	MAGNETIC CONTACTOR	TERMINAL	DC REACTOR	FLY WHEEL DIGDE	TRANSISTOR MODULE	DIDDE MODULE	SURGE ABSOBBER	COOLING FAN	THERMAL RELAY (100 C)	THEMAL RELAY (80%)	TRANSFORMER	SAUBBER CONDENSER	30010 a3601w3	SNUBBER RESISTOR	BALANCE RESISTER	CURRENT TRANSFORMER	PRINTED BOARD (control)	BASE DRIVE PCB	RESISTOR	CONDENSER	CHARGING LAMP			
MARK	68		ХСТ	CT 1	5 X	84	MT	סכר	FD	Hd	M	ZMR	F AN	THR	THR	1	5	61	- ¥	RĜ	ст 2	PCB	PCB	1P8	5D -	СНG			
9N	-		2	E	4	6	. 8	11	12	13	15	17	121	26-1	26-2	29	11	32	33	63	60	61	62 '	64	65	16			



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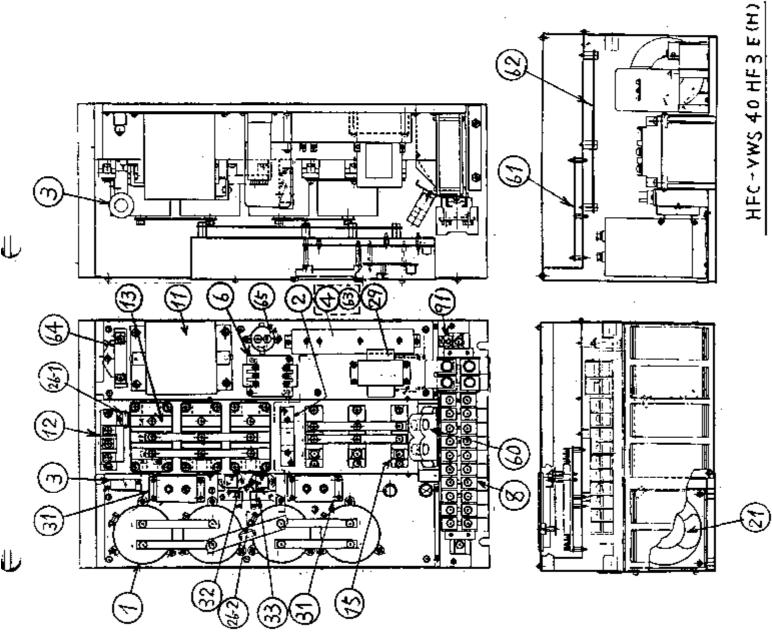




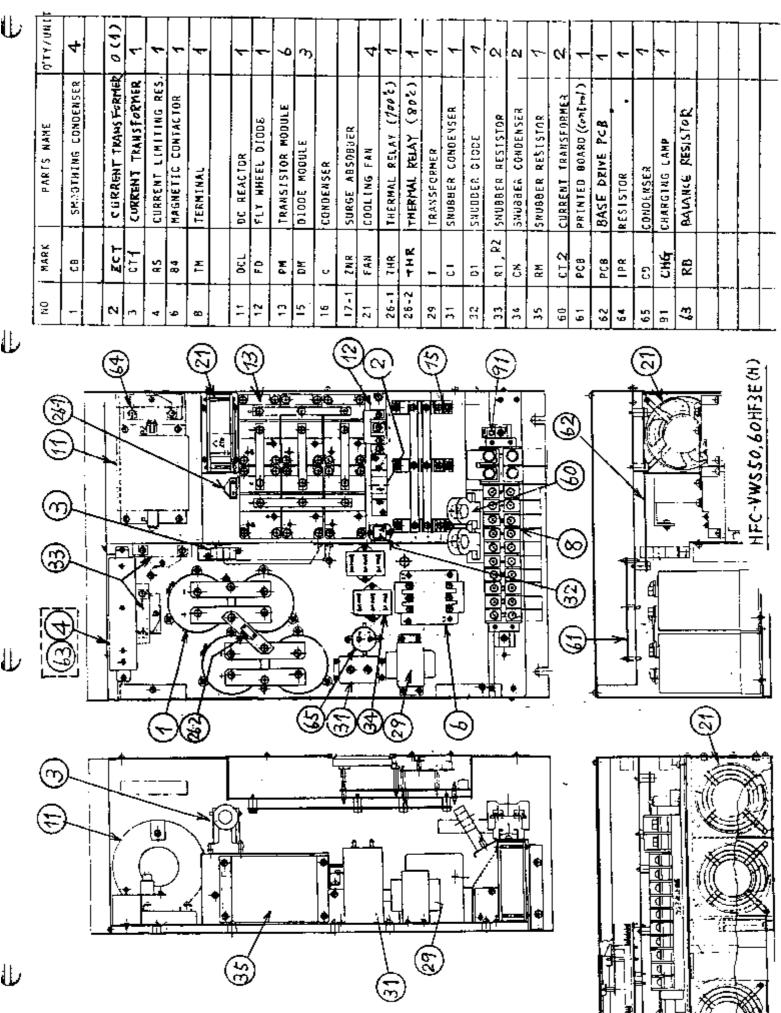


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PARTS RAME	SMODTHING CONDENSER	CONTY 40HE3EH	CURRENT TRANSFORMER	CURRENT TRANSFORMER	LIMITING RES	C CONTACTO	TERMINAL	DC REACTOR	FLY WHEEL DIDDE	TRANSISTOR MODULE	DIQUE MODULE	SURGE ABSOBBER	COOLING FAN	THERMAL RELAY (JOP &)	THERMAL RELAY (80 %)	I RANSFORMER	SNUBBER CONDENSER	SNUGAFD DIDDE	SAUDALM RESISTUR		BARANCE REUSTOR	ICURRENT TRANSFORMER	PRINTED BOARD (CONLINA)	BASE DRIVE PCB	RESISTOR	CONDENSER	CHARGING LAMP	
MARK	6.0		201	CT 1	RS	84	Ŧ	OCL	f D	Wđ	MO	ZNR	FAN	THR	THR	L	C1, C2	01, DZ	k⊥, R2		R.B	CT 2	PCB	PCB	JPR	5	CH6F	
N C			~	~	-	G		-	12	13	15	-	21	26-1	26-2	29	ŧE	32	33	,	63	60	61	62	49	55	5	

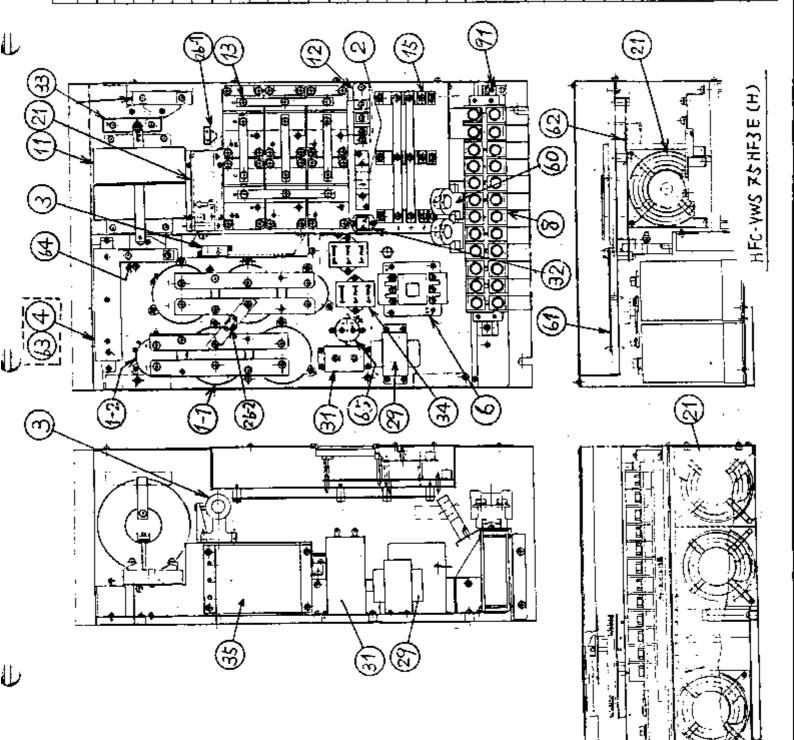


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Comparison of function of terminals

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1/0 signal	Terminal symbols	VWS3 series	Terminal symbols	VWS2,VWS1 series
Start/stop operation command Forward operation command(FW) Reverse operation command(RV)	Fx	Frequency is set in "Monitor mode" and START/STOP command is selected in "Terminal mode" by D-OPE.	H Ó L FR	
		SWF JON .Forward rotation [DFF :Reverse rotation SWR [ON :Reverse rotation [OFF :Stop When SWF and SWR are ON at the same time.output turns off.		SW1 {ON :Forward rotation {OFF :Stop SW2 {ON :Reverse rotation {Off :forward rotation
frequency setting command {Voltage input}	D L	 When the voltage between D and L is 10V.frequency becomes maximum. The voltage between H and L is regulated as 10V (AVR). 500~2k∝resistor is available for VRO because of AVR. When the analogue command(0-L) is 	0 Ľ	When the voltage between 0 and is 10V.frequency becomes maximum (a) The voltage between H and 1 is 10v. (b) When the value of VRO is 500 the voltage(H-L) is 10V. (c) When the value of VRO is 1kg., the voltage becomes as follow
		applied,the gain and bias of frequency can be adjusted by means of D-OPE(F-26(F-START),F-27(F-END)) Fmax can be adjusted by F-3(+fmax)		1000_x 12 ⁴ = 11 ⁴ 1082 x 12 ⁴ = 11 ⁴ Vk0 mustn't be set as more than 90% because the voltage exceeds normal voltage by 10% when 1kΩused.
Frequency setting command (current input)	01 i.	f-]\$we ●	01 Ľ	
		Input impedance : 250 A reading the start (F.START) and end (F.START) and (F.START)	Input impedance : 500 A BI-NVI2 shortcircuited : 4~20 open : 0~16	
Frequency manitof signs] (Current input)	FM	The inverse mode can be set. The frequency monitor signal(FM) can be transmitted by selecting 2 types of signals.Selection is done by D-OPE(F-28,switch 3) Monitor for analogue meter (100 Full scale (Load resistance: 10~22km IMA max (1) This monitor outputs the duty (t/T) proportional to the output	AI L	Analogue meter is available.
 		frequency. (Adjust the variable resistor {M.ADJ} and the variable resistor of frequency counter itself so that the meter is maximum at the highest frequency. Digital monitor for frequency counter The monitor output is as follows		D~10¥ Full scale (Load resistance:10~22kA 1mA
Fault reset	R5 L	Reset is possible after 1.5 10sec have passed since power supply turns off. (The time depends on models.) RS-L isclosed.	ŘS Ĺ	Reset is possible after 0.5.2 have passed since power supply turns off. (The time depends on models.) RS-1 isclosed.

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CABINET VOLUME/SURFACE AREA TO HOUSE HFC-VWS UNITS
 6-6
(IP55)
(CONDITIONS)
1.Ambient Temp. of OUTSIDE
                                          ;max.40°C
2.Ambient Temp, of INSIDE
                                           ;max.50°C
3.Heat radiation efficiency
                                           ; E = 0.92
4.Ratio of dimensions of cabinet
                                             9
                                                         6
                                                                  16
                                           (Wldth) (Depth) (Hight)
5.INVERTER generation loss
                                         (P = 0.05 \times INV(kVA) \times 10^{3}(W)
6.Location of cabinet(Worst case)
                                          ; IN AIR
(FORMULA)
Heat loss by CONVECTION: Pc = 1.85 \times \Delta Ts^{1.25} \times Sc(W)
Heat loss by RADIATION ; Pr = 5.67 \times 10^{-8} \times E \times ((T + dT_5)^4 - T^4)) \times Sr(W)
    P = Pc + Pr
where to:
d Ts
       ;Temp.rise on the surface of cabinet(°C)
  T
         ;Ambient Temp.(°X)
Sc,Sr : ;Effective surface area(m<sup>2</sup>)
Then,
        T = 273 + 40 = 313(°K)
       4Ts = (50-40)/2 = 5(°C)
Pc = 13.9 \times Sc, Pr = 32.8 \times Sr
if 5c = 5r.
  P = 46.7 \times Sc
(RESULT)
                                SURFACE(m<sup>2</sup>)
               INV.LOSS(W)
                                                   CABINET DIMENSIONS(m)
INV.(KVA)
                                                     W x D x H
                                    Sc
                    P
                                                   0.47 x 0.31 x 0.84
                   75
                                  1.61
 1.5
2.5
                  125
                                 2.68
                                                   0.61 x 0.41 x 1.08
3.5
                  175
                                 3.75
                                                   0.72 x 0.48 x 1.28
                                                   0.90 x 0.60 x 1.60
 5.5
                                 5.89
                  275
                                                   1.05 x 0.70 x 1.87
7.5
                                8.03
                 375
                                                   1.28 x0.85 x 2.27
                                11.8
11
                 550
                                                   1.49 x 1.00 x 2.64
                 750
                                16.1
15
                                                   1.80 x 1.20 x 3.20
                 1100
                                23.6
22
                                                   2.21 x 1.47 x 3.92
                 1650
                                35.3
33
                                                   2.43 x 1.62 x 4.32
40
                 2000
                                 42.8
                                                   2.97 x 1.98 x 5.28
                 3000
                                 64.2
60
                                                    3.21 x 2.14 x 5.71
                                 74.9
70
                 3500
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NOTE : After building cabinet, Temp.rise should be tested. If cooling fins are put on cabinet , dimensions have to be smaller.

This CALUCULATION is only for REFERENCE at your own DESIGHN WITHOUT Hitachi GUARANTEE.

(FOR YOUR REFERENCE) (IP23)

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5-7 SELECTION OF VENTILATING FAN OF INVERTER BOX

When the inverter unit shall be received in the box, it is necessary to keep the ambient temperature as follows:

Enclosed wall mount type(A,& B type) Not exceed 40°C Open wall mount type(C type) Not exceed 50°C

Then please install ventilating fan to ventilate well.

- 1 Inverter capacity, necessary ventilation and ventilating hole area
 - The calculation examples are given in the list below.
 [Q is in case of 10°C at temperature (ΔT=10°C)]

		Н	G	S
Inverter	Inverter	Inverter	Necessary	Ventilating
capacity	generation	calorific	ventilatión	hole area
	loss(approx.	value	T=10 C	(minimum)
(k∪A)	value)(KW)	(Kca <u>l/hr</u>)		<u>(m2)</u>
1.5	0.075	64.5	0.37	0,004
2.5	0.13	108	0.62	0.005
3.5	0.18	151	0.87	0.010
5.5	0.28	237	1.37	0.015
7.5	0.38	322	1.87	0.02
11	0.55	473	2.74	0.03
15	0.75	645	3,73	0.04
22	1.1	946	5.47	0.06
33	1.7	1419	8.21	0.09
40	2.0	1720	9.95	0.11
50	2,5	2150	12.4	0.14
60	3.0	2580	14.9	0.16
70	3.5	3010	17.4	0.29
100	5.0	4300	24.9	0.28
120	6.0	5160	29.9	0.33
150	7.5	6450	37.3	0.42

2. Calculation formula

Q=___

K X AT X 60

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G: Necessary ventilation (m³/min)

- H: Inverter calorific value (Kcal/hr)
- Total value if having other heating power K: Constant
- F.Cp=0.29(Kcal/m³C) T: Specific gravity of air=1.2(kg/m³)
- (Cp: Specific heat of air=0.24(Kcal/kg "C)
- AT: Allowable temperature rise("C)

Remarks: 1KW=860Kcal/hr

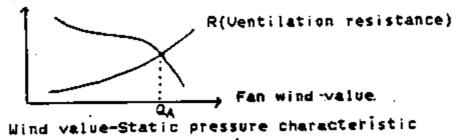
2 Consideration of fan selection

Necessary ventilation Q shall be calculated in the way above mentioned. Fan shall be chosen considering the following matters.

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1. In case of mounting the filter at the ventilating entrance, operating point GA shall be calculated according to G-H curve of the fan.

Wind pressure



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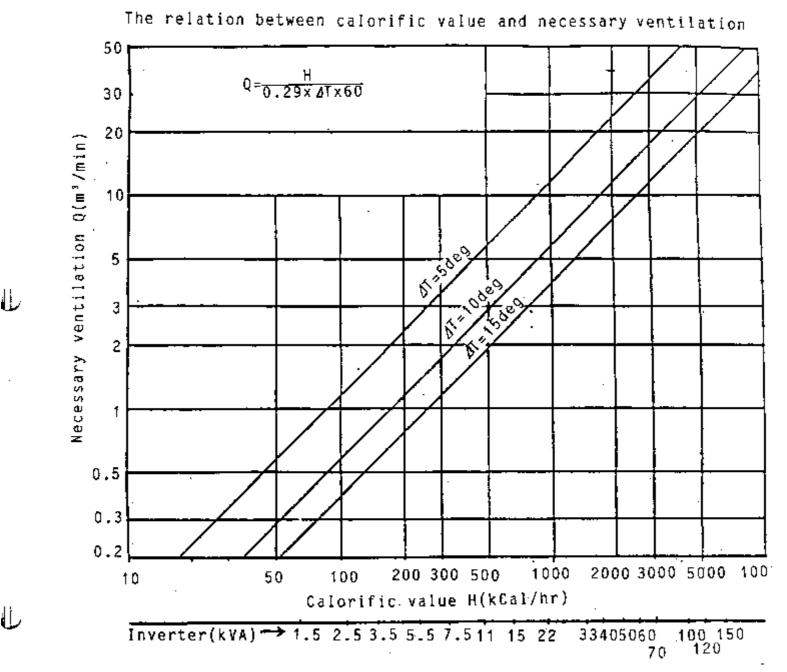
 In case of bad ventilation because of fully mounting in the box, it is also the same as the mentioned above.

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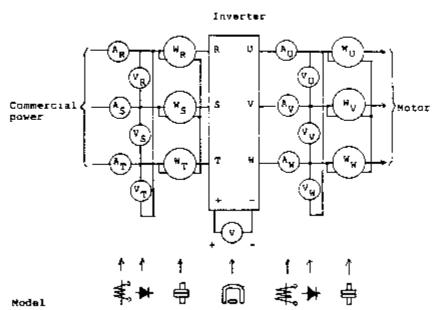




<u>6-8 HOW TO MEASURE THE VOLTAGE,</u> <u>CURRENT AND POWER</u> <u>MEASURING INSTRUMENTS AND MEASURING POINTS</u>

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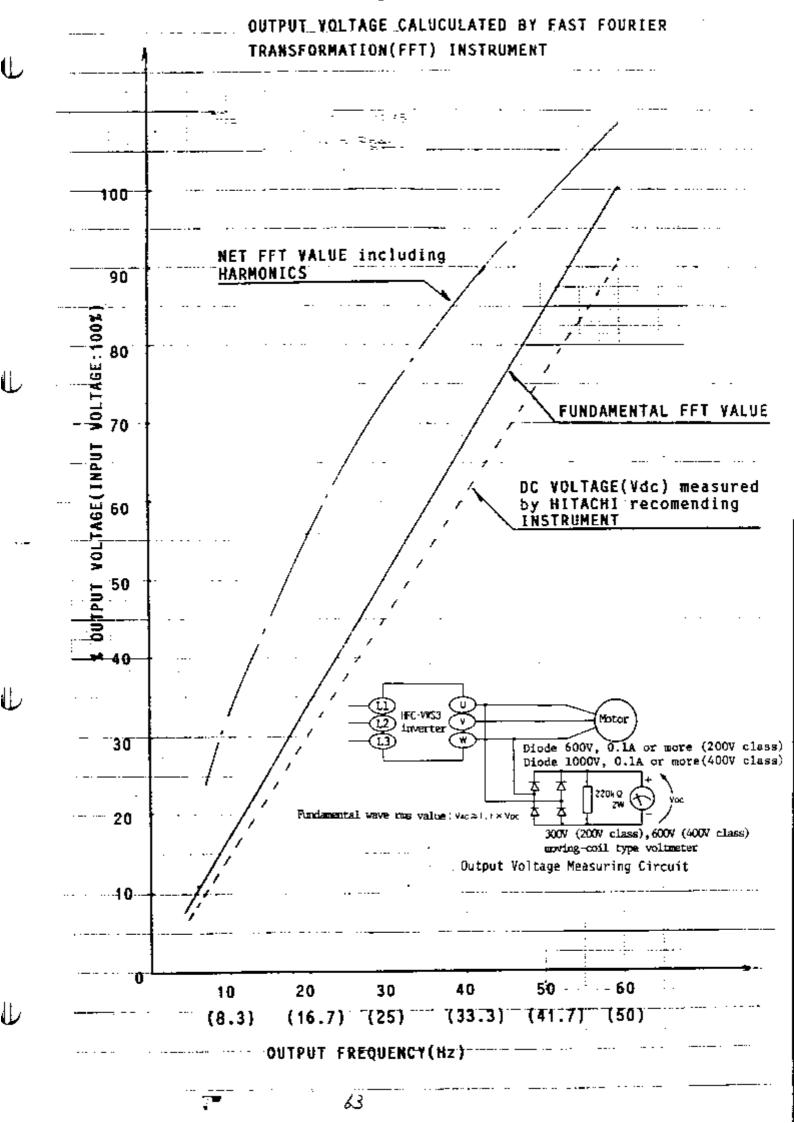
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Measuring items	Measuring points	Measuring Remarks instruments (Measuring value)
Input voltage V1	Between R-S,S-T, T-R	Moving Commercial iron-type power or Rectifier- 50Hz 180~230V type
Input current I1	R,S,T(Line current)	Moving iron-type
Input power P1	R,S,T or R-S,S-T, T-R	Electro- $P1 = W_R + W_V + W_T$ dynamic- (Use 3 same type type units)
Input power factor ^p f1		P1 x 100 (%) V1 - I1
Output voltage V2	Between U-V,V-W W-U	Rectifier- type (Not moving iron- iron-type)
Output current 12	U,V,W	Hoving iron-
Output power P2	U,V,W U-V,V-W; W-U	Electro- $P^{1=W}U^{+W}V^{+W}W$ dynamic- (Use 3 same U type type units)
Output power factor ^P f2	$P_{f2} =$	well as input power factor. <u>P2</u> 3V1 · I1
Converter output ^V CB	Between (+) and (-)	Moving iron- type (Tester is O.K.)

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Output voltage

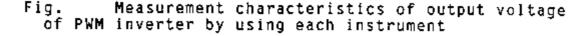
When you measure the fundamental harmonic effective value of output voltage, you can use a rectifier type voltmeter. There are many type voltmeters such as moving-iron type and thermoelectric type. The rectifier type voltmeter indicates the nearest value of the fundamental harmonic effective value.

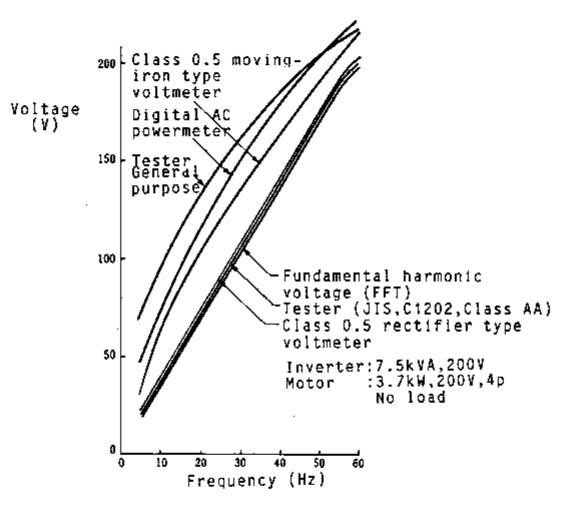
Fig. shows the measurement characteristics of output voltage of PWM inverter by using each instrument and Fig. shows those of PAM inverter. The indication of the rectifier type shows a good lineality against the operating frequency and an approximate value of the fundamental harmonic effective value (FFT).

You can get more approximate value of it by using a rectifier type voltmeter with connecting a filter to output terminals like Fig. when you measure the output voltage of PWM inverter which generates, reverse voltage between output terminals eachtime PWM switches.

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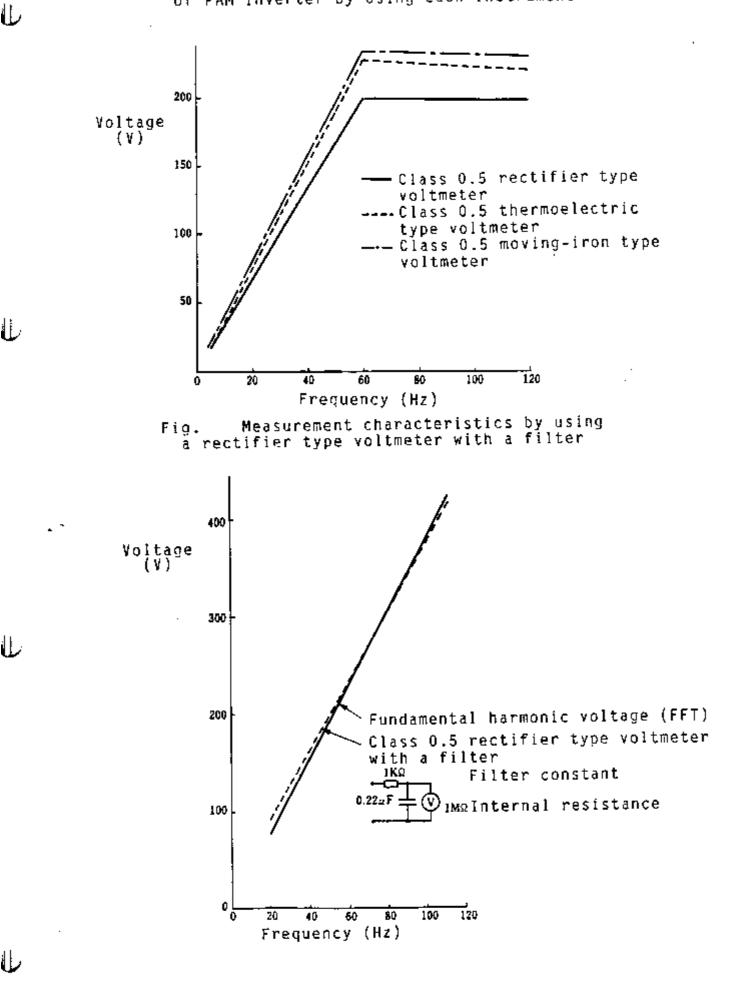
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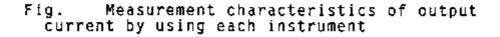
Fig. Measurement characteristics of output voltage of PAM inverter by using each instrument

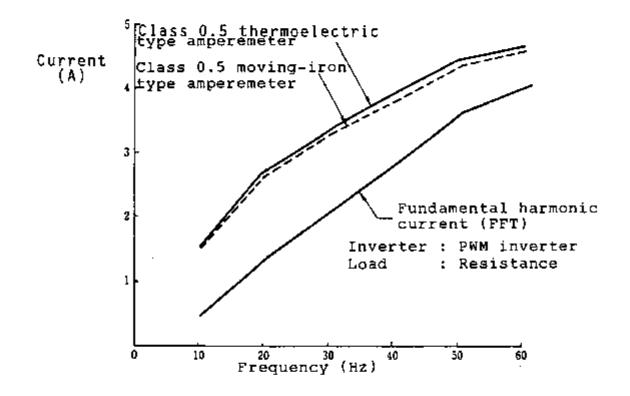


(2) Output current When you measure the output current, you can use a moving-iron amperemeter because of necessity for the measurement of total effective current. In case of the measurement of the effective current a thermoelectric type amperemeter is also available, but in many cases a moving-iron amperemeter is used due to ease to treat. Fig shows the comparison betwen measurement characteristics of the thermoelectric type amperemeter with resistance load and that of the moving-iron type amperemeter. (There is a little difference between the fundamental harmonic current and total effective current in case of an actual motor load.)

It is necessary to check the capacity of the current transformer when you use it because some current transformer saturate themselves in low frequency.

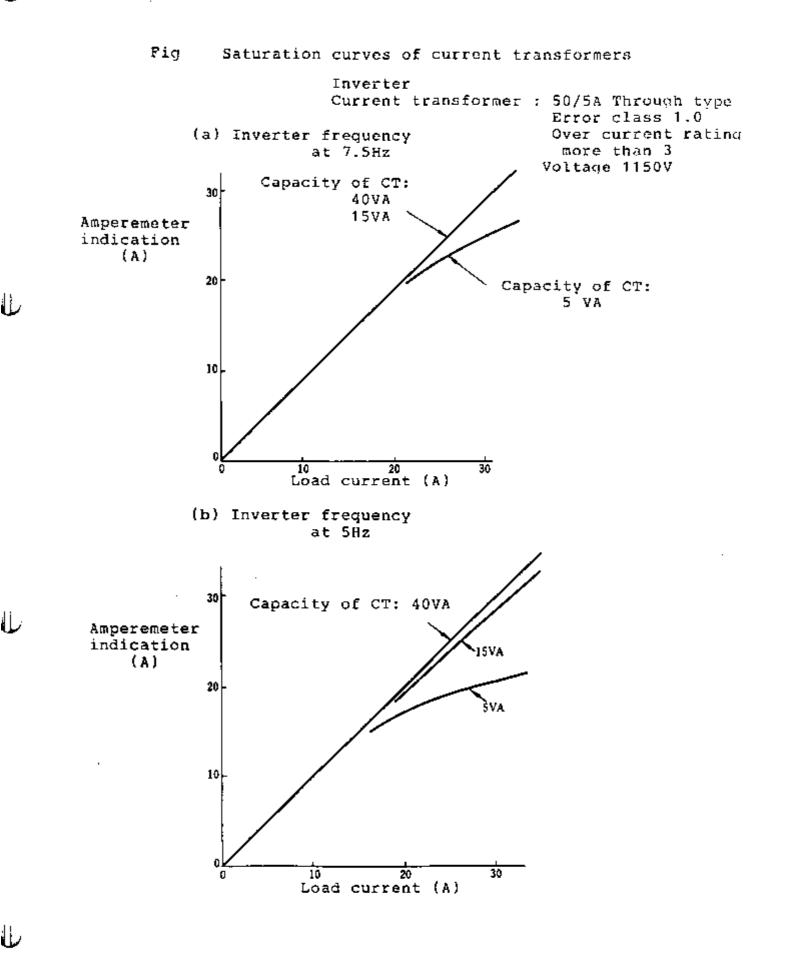
Fig. shows the saturation curves of current transformers in low frequency.

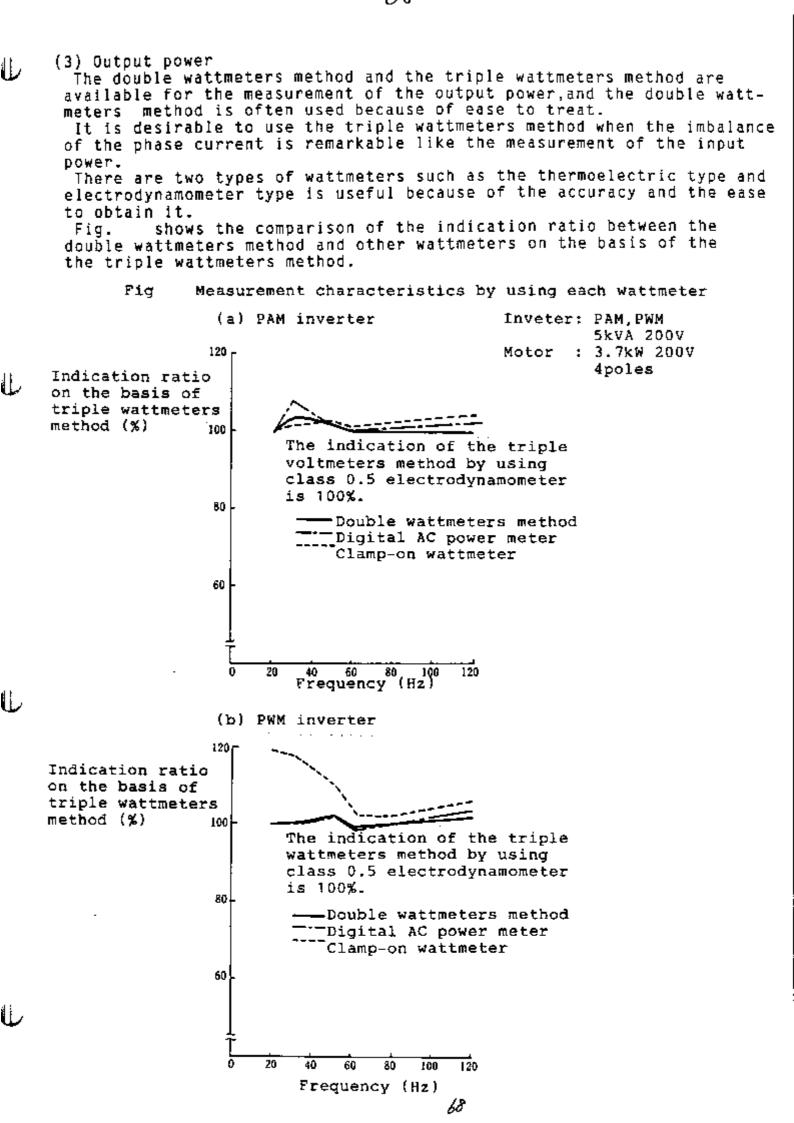




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NOTE : Both (a) and (B) show the indication ratio as the indication of the triple wattmeters method is 100% while the torque is constant from OHz to 60Hz and the power is constant for more than 60Hz.

- (4) Power factor of inverter It is impossible to measure the power factor of the inverter by a power factor meter because the output frequency changes.
- NOTE: It is possible to calculate the power factor through the output voltage, the output current and the output power. But there is difference between the power factor as is usually expressed and that which is obtained by calculation because of the difference of the measurement of higher harmonics. So the power factor of the inverter isn't ordinarily measured.
 - (5) Measured efficiency of inverter The measured efficiency of the inverter is defined as the ratio of the output active power and the input active power of the inverter.

Measured efficiency (%) = <u>Output active power</u> x 100 (%)

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(6) Output frequency In many cases the output frequency of the inverter is output from the inverter as the analogeue voltage or the pulse signal of frequency control. So the output frequency is not measured directly by the output voltage but measured by the frequency control signal. The pulse signal is measured by a counter. The ratio of the pulse signal and the output frequency is different among the manufacture. When you measure it, it is necessary to ask the manufacturter.

6-9 RUSHING CURRENT WHEN POWER SUPPLY IS TURNED ON

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Model	Rushing current	Charging time	
HFC-VWS3 1.5 SF3E			
2.5 SF3E	404	3.78	
3.5 SF3E	404	5.67	
2.5 HF3E	283	3.36	
3.5 HF3E	283	4.92	
5.5 HF3E	283	6.00	
8 HF3E	283	6.60	
11 HF3E	435	5.28	
16 HF3E	435	9.18	
22 HF3E	808	5.88	
33 HF3E	1414	4.68	
40 HF3E	1414	5_64	
50 HF3E	1414	5.64	
60 HF3E	1414	6.72	
75 HF3E	1414	9.96	
RS	curr	V class:Vo=200V V class:Vo=400V) ing ent(A)	Condens voltage A
₽v₀	Св	IMax.	0.95
$I = \frac{\sqrt{2}V}{RS}OEXP(-CB-R)$	5.)	5% 0 0 Time(S	37
7=CB⋅RS(time co	nstant)		, ,

ENGINEERI	NG SHEET	备号 SEND.	ES0459X	頁 SHEET	1/4
約 先 CUSTOMER				が正回数 REV. No.	<u></u>
品名				2	11. Mar. '96
EQUIPMENT	HFC-VWS100 to 15	OHF3EA		3	
题 名 SUBJECT	Strustual Drawin	g			
	nering sheet is at to 150HF3EA	tached the	structual d	rawin	gs for
Deset	4.				
Drawing nu 3T816113	mber; : for VWS100HF3EA				
	: for VWS120HF3EA				
	: for VWS150HF3EA				
▲ 37816479	1 : for VWS180HF3EA	4			
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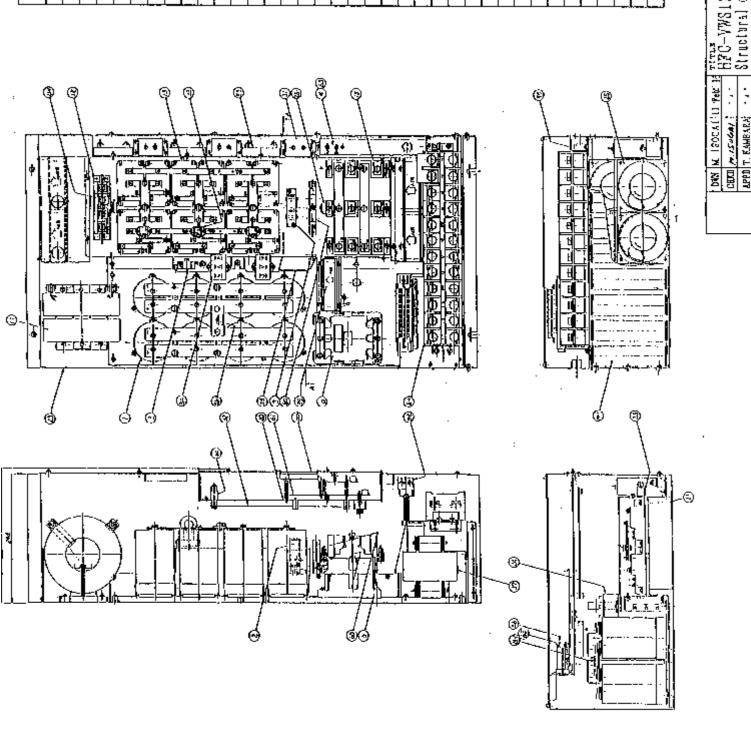
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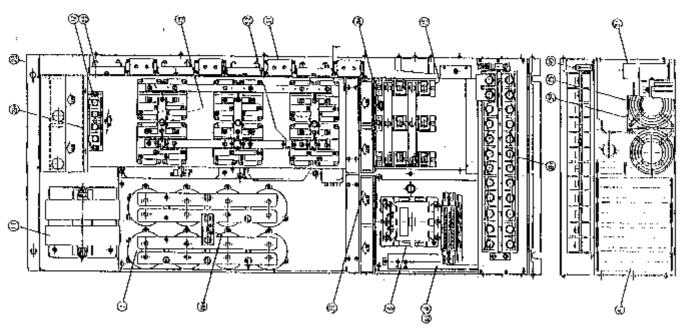
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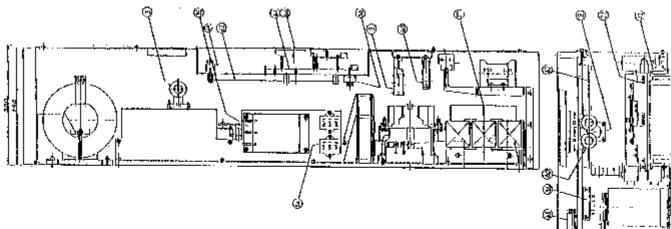
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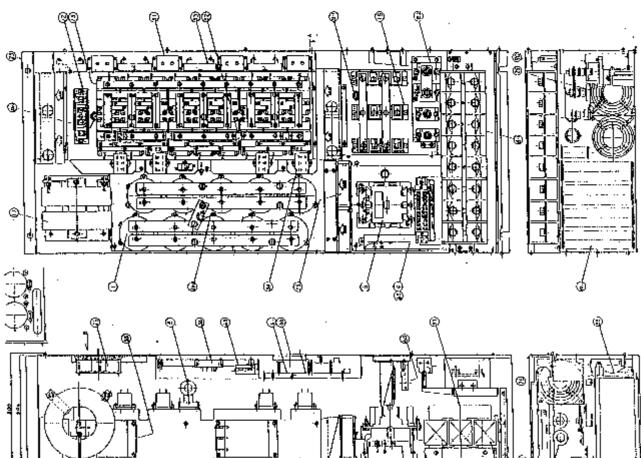
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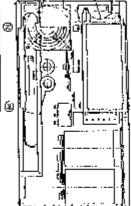
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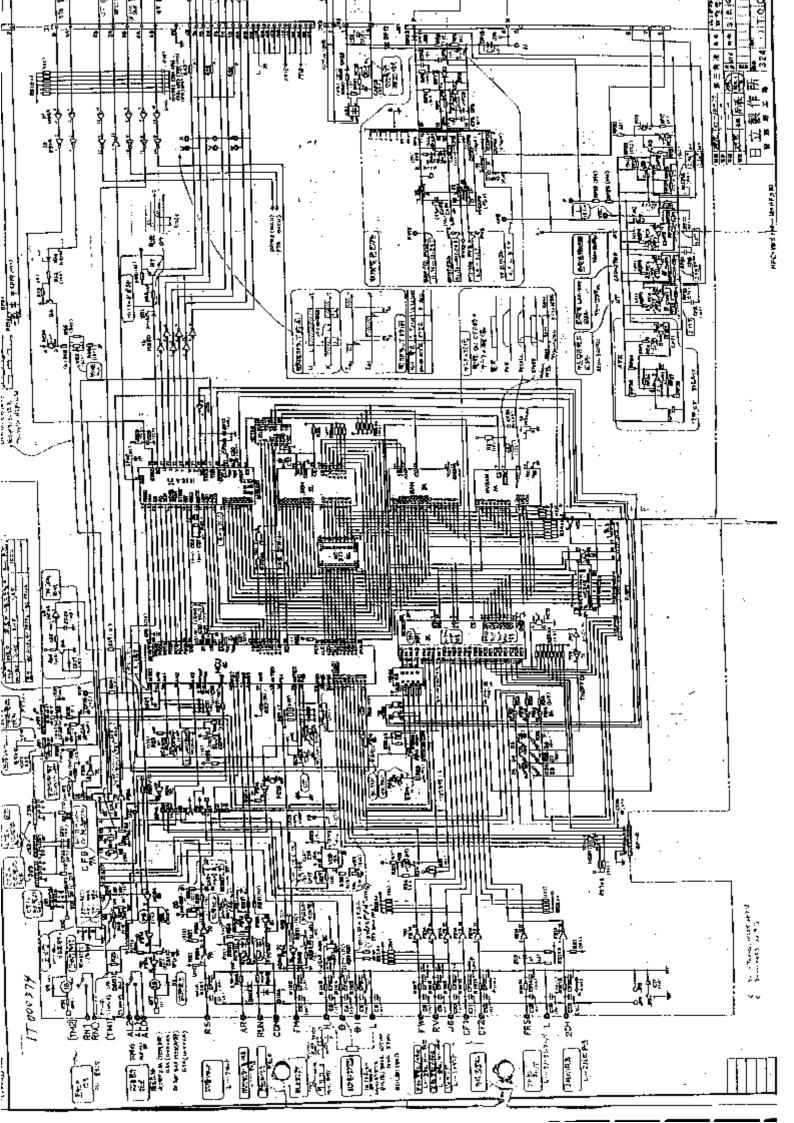
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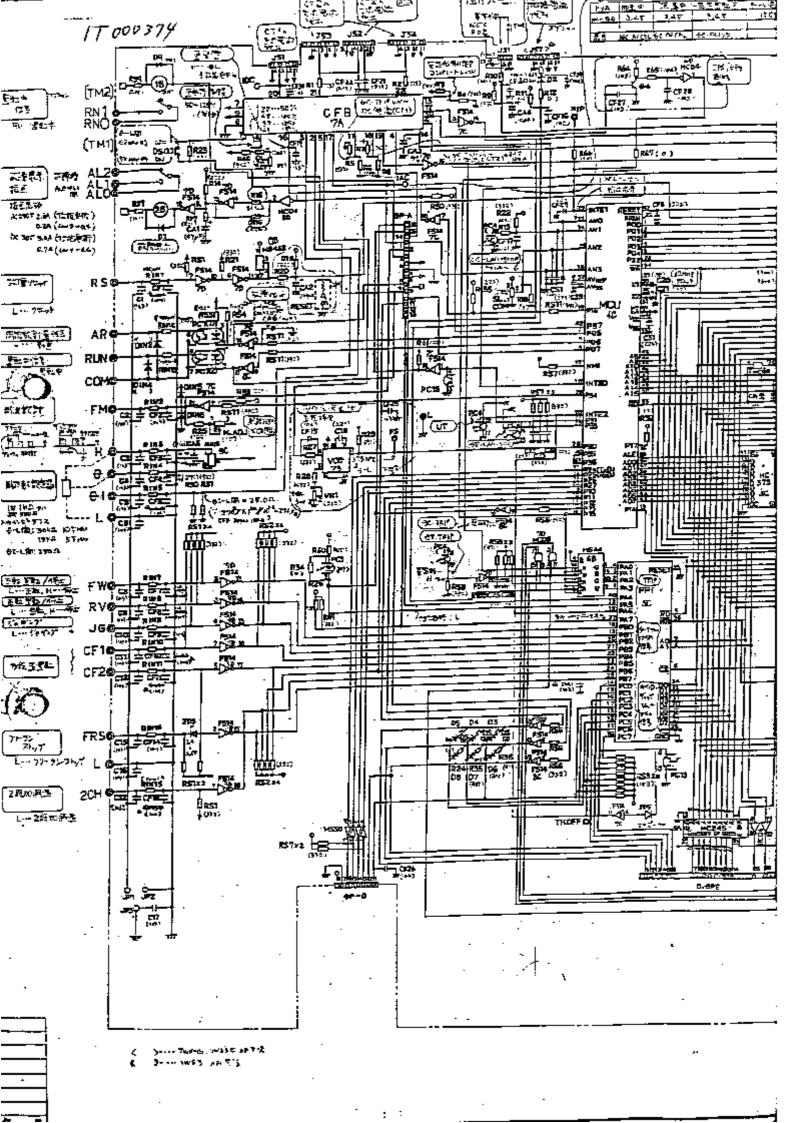
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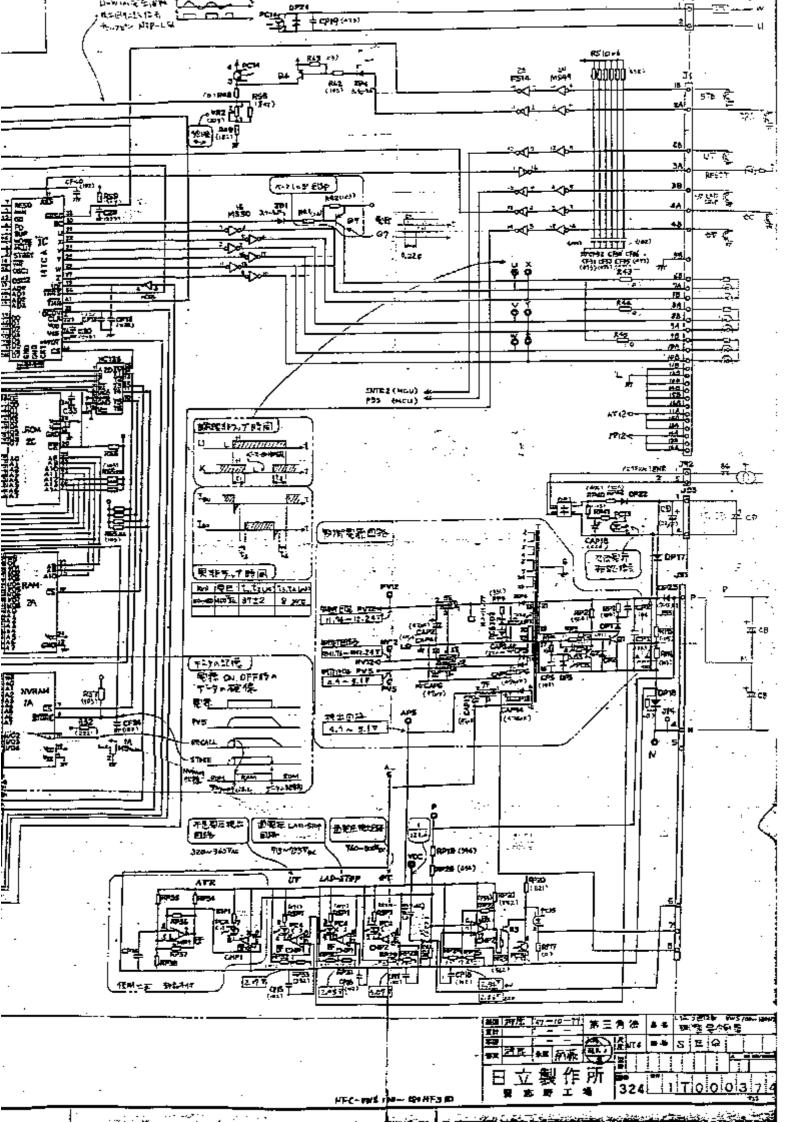
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