## HITACHI INVERTER

# HFC-VWS3U(H) SERIES

SERVICE MANUAL FOR USA-VERSION



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- 4. Trouble Shooting
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  - 4.3. How to return the setting to the initial setting

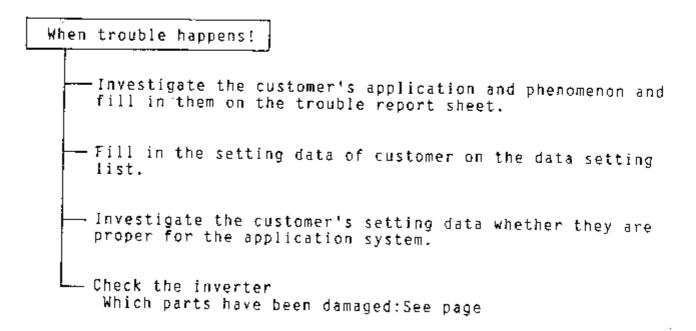
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#### 1 INVESTIGATION



\* The reason for the trouble is not always inverter's failure. We must check the system and inverter both of them.

#### TROUBLE REPORT

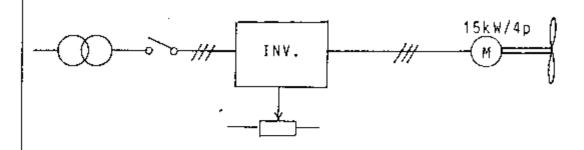
Customer			•				- <del>-</del>
Model Type	]		<del></del> -				- <del>-</del>
Serial No.(MFG.No.)			. <del></del>	_			
Date of Purchase			_	-		- <u>-</u> -	<u>-</u>
Date of Installation						-	
Date of Failure	<del>                                     </del>				<del></del>	·	
APPLICATION							<del></del> -
						•	
	<del></del>	_					
DETAILS OF FAILURE						•	
BROKEN COMPONENTS		<u> </u>					
·							
REMARKS		.,			<u>-</u> .		

#### TROUBLE REPORT (Example)

Customer	
Model Type	HFC-VWS 22 HF3UH
Serial No.(MFG.No.)	SU22HF 3H89A
Date of Purchase	SEPT. 88
Date of Installation	OCT. 88
Date of Failure	NOV. 88

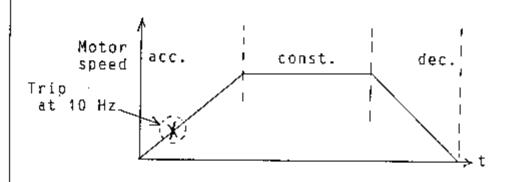
APPLICATION

Fan drive



#### DETAILS OF FAILURE

When the reference signal (0-10V) is applied to the inverter, over current trip comes.



#### BROKEN COMPONENTS

Power module

REMARKS

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# HFC-VWS<sub>3</sub> Series DATA SETTING LIST

RFC-VVS; inverser has many function so that the setting data can be changed by customera.

It is recommended to fill the setting data out the following data sheet for service, maintenent and investigation of trouble.

KPC-WPS	
	.e. ₩o.
4	ģ

Described on spac. Label on top cover

# \* Monitor Mode

				,	, <b>-</b>			,	·	, ^
Satting										l
Standard	ı	ı	ş	Pa. Ag	-3	. ,	7.	Ş	1.0	ı
Inicial Dispiny	±M 000 M±	E3 000.0H.	E-SETHM OPE119	1. c 40 W2-R-1	MANOGOO A) MAN	¥0 '000 = 1 Y 1	(16) *P*3 15*P#-A	¥901 ":•⊅-Ā	1+2£fb3 01.0H.	*
Mobitor Name	Output frequency display	Treavency artitog commed	Fraquency command mathod	Operation commend method	Notor apend display	Cutpet terrent display	Manuel corque boost adjustment	Quepet voltage gate adjestment	Jogging frequency perting	Fault display
(a ) de Till	-		F	-	2		f-	ϝ .		- 01

Table 1

·	
Hode	
Function	
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-				KI LINE	
-	לון לייונים אינונים אינוים אינ		3 <b>-</b> - 1 <b>4</b> 5	90-99	
~	Acceleration time secting	10-1	1-11137	Ŕ	1
_	Dadelmenting time sections	<u>r</u> v 0 2	1-13030	R	
,	Maniaum frequency (100 adjustment	£ . 0 .	. F . R .	-	
~	Schriff frequency adjustment	£ - 0 4	. 7 = 1 h .	?	
•	Martines frequency binding secular	40-1	H - E - J - E	-	
-	Misieum (requency limiter spicing	9 D - 1	1-11K-F	•	
<b>-</b> .	Jum (Talwency ) secting	1-07	28187	P	
4	Jump fraquency 1 ecting	10-1	ZJ-JKOF	۰	
٠	Jump trequency 3 mersing	10-1	JUN7-73		
-	Matte mains adjustment	01-7	5 F - c d d c	•	
	Adjustment of frequency prop	. <u>.</u>		2	
<u>-</u>	Haltlacage speed 1 setting	1 1 - 7	1-13115		
9	Multistate apart 2 perting	(   - ]	2 - 7 - 2 - 4 9	-	1
15	Huleistage speed 1 parting	11-1	3 7	-	
2	f-stude septementer ties secting	1 - 1	1-11004	8	
11	Payabe daja walincejesep elica-j	1 - 1 1	2-14-10	2	
₽.	K benblug frequency adjustment	2 - 2 0	F - D C S	-	
ęs	IC braktop power adjustment	- 1 - 2	V - BC1	8	•
۳ ا	DC brieting cim idjustment	<u>f</u> - 2 1	τ.μίε	8	•
- <u>-</u>	Electric thermal level adjustment	[-2]	8 . t h . c .	8	
	Limear/Sacharactar curved Aceelaration pelection	11.3	456114.	114mar	
13	Libear/3-chereeter curend decemparation selection	61-1	0 2 6 1 1 0 0	Linear	
24	Start polas frequency of actornal	E - 1 B	F-START		
25	Est point frequency of external frequency secting	- 1 - 1	7 - 2 # b	-	
36	Suites malaction	11-1	SWITCHI	11100000	
	Overload timit time constant	1.30	**	-	
	Overload unraing lovel edjuiceens	16-2	0	8	
67	Automatic torque boost pdjustmant	11-31	, v	8	
2	Allowable instrumenteders form (allower times than	<u>t</u> - 1 1	1 - 8 - 1	-	
=	Stand-by they secting for restart	F - 3 A	I P S • 1 • 7	-  - [	[

Wescription of MFG. NE

Note our arrangement of MFG, No.

In case of AF-150502-0480 (Rev. Mo. =A and NFGD in 1988, Sep. ),

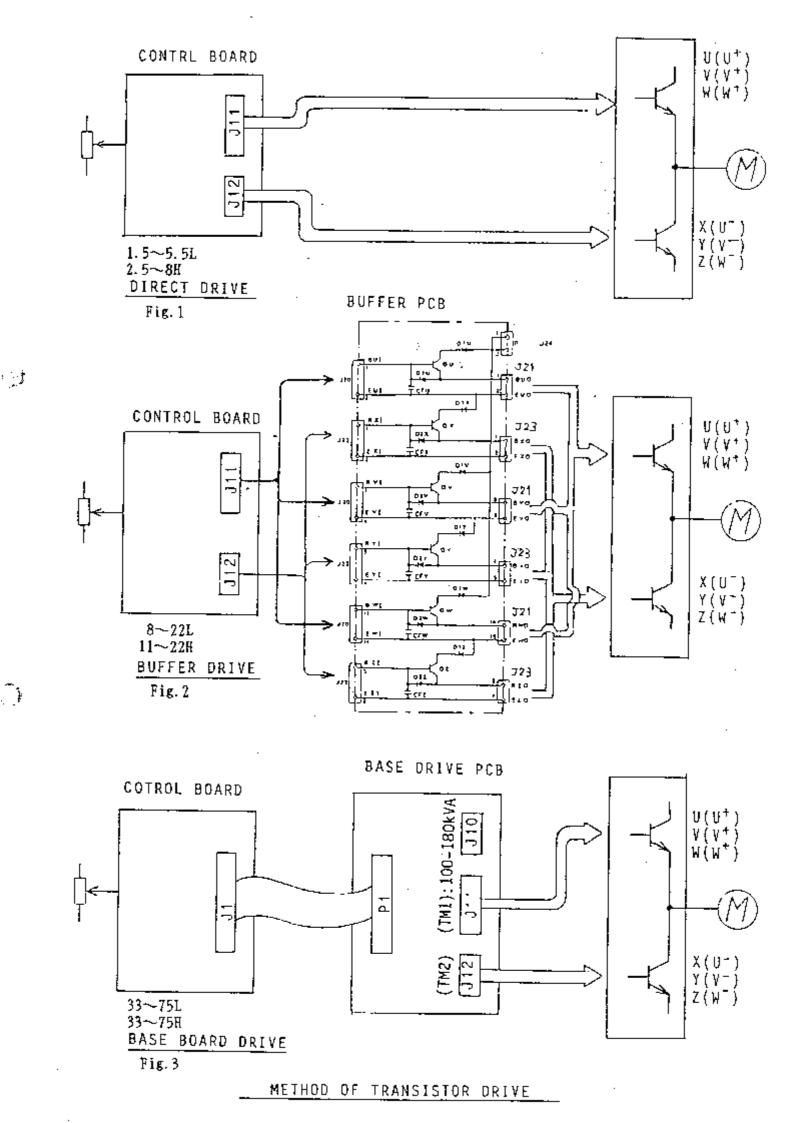
MFG. No. SUSHF3H89A

<pre></pre>	⊕:MFG. Year 8 →1988	9 → 1989 0 → 1990 1 → 1991 :	₩	Feb. : : Oct. ion Mov.	Dec. →K
<pre>(D : Inverter series name SU→USA MODEL</pre>	(2): Inverter capacity 1.5KVA $\rightarrow$ 1.5 2.5KVA $\rightarrow$ 2	5. 5KVA $\rightarrow$ 5 8 KVA $\rightarrow$ 8 11 KVA $\rightarrow$ 11	(3): Input power H: 400V and three phase class L: 200V and three phase class	<ul> <li>(4): Inverter construction</li> <li>D: Enclosed type with disital</li> <li>operator station</li> <li>F: With disital operator station</li> </ul>	⑤ : Series number 3 → Same as VWS3 series

<del></del>		<u> </u>
Series	VWS	30 (H)
Use	Control	Base drive Buffer
1. 5L	SU3L1. 5L0	
2. 5L		
3. 5L		
5. 5L		
8L	SU3L8-11L0	SU3B8-22L0
111		
16L	SU3L16-22LC	
22L	<b>1</b>	<u> </u>
_33L	SU3L33L0	SU3B33LO
40L	SU3L40LO	SU3B40LO
50L	SU3L50-75L0	
60L		SU3B60LO
75L	<b>.</b>	SU3B75LO
2. 5H	SU3L1-3H0	
3. 5H		
5. 5H	SU3L5HO	
<u>8</u> H	SU3L8HO	$\angle$
11H	<u> SU</u> 3L11-16H0	SU3B11-22HO
<u>1</u> 6H		
22H	SU3L22HO	
<u>3</u> 3H	SU3L33-40HO	SU3B33HO
40H	↓	SU3B40-50HO
50H	<u>_\$U3L50_75H0</u>	Ψ
60H		SU3B60-75HO
75H	↓	
	· · · · · · · · · · · · · · · · · · ·	

Table 2

O:Rev. No.



#### After disconnecting Sub. PCB.

	Check	Use and level	Addres	s(Location)
	pin		~22kVA	33~75kVA
	PV5	Power source for dig.circuít PV5-L:4.9~5.1 VDC (RC245-20pin-L)←upt=22kvA	5 A	3E(L)k Løgic 7G(B)←Base
	PV12	Power source for analogue circuit PV12-L:11.76~12.24 VDC	9E	5B(L) .7G(B)
316	NV12	Power source for analogue circuit NV12-L:-11.76~12.24 VDC	AE	76(B)
21507→ <del> </del>	ι	Ground for analogue circuit	1A,10A	8A,2E(L) 7G(B)
	AP5	Power source for protection circuit AP5-AL:4.9~5.1 VDC	8E	5f(B)
VULTAGE)	AL	Ground for AP5	38	
HIGH	VDC	Over voltage VDC-AL :3.25 V (Trip level)	8 E	6F(B)
BR FOR	Þ	DC voltage of the intermidiate circuit P-N:max. 400VDC	6 <b>H</b>	6F(B)
(DANGER	N2	DC current of main circuit N2-N:1.3VDC (Trip level) (up to 5.5kVA)	7 H	
MALN	N	Ground for P and N2	8H	6F(B)
	UL.	Ground for base circuit of U+ DP 7(0-UL: 6.5~9.5V *1) (1.5~75 kVA) DP31(0-UL:-6.5~9.5V (33 ~75 kVA)	2F	1F(B)
[	٧L	Ground for base circuit of V+ DP 80-VL: 6.5~9.5V *1) (1.5~75 kVA) DP340-VL:-6.5~9.5V (33 ~75 kVA)	3E	2E(B)
•	WL .	Ground for base circuit of W+ DP 900-WL: 6.5~9.5V *1) (1.5~75 kVA) DP3700-WL:-6.5~9.5V (33 ~75 kVA)	4 E	3E(B)
	ΧL	Ground for base circuit of X (U-, Y-, W-) DP1C(R)-XL: 6.5~9.5V *1) (1.5~75 kVA) DP4(A)-XL:-6.5~9.5V (33 ~75 kVA)	3.H	6A(B)
	After con	necting Sub. PCB.		Table 3
	PV12	Power source for Sub. PCB PV12-L:11.76~12.24	1B	1B

PV12	Power source for Sub. PCB PV12-L :11.76~12.24	1B	1B
NV12	Power source for Sub. PCB NV12-L: 11.76~12.24	1A	1.4

Table 4

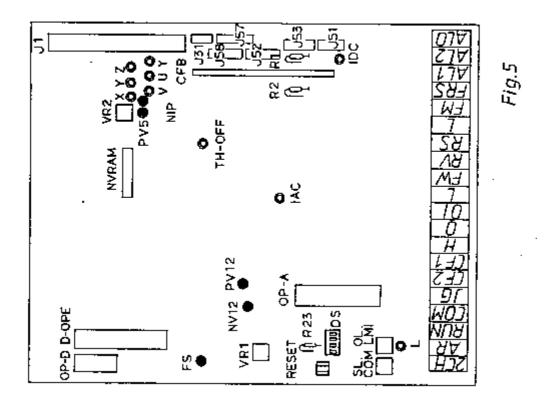
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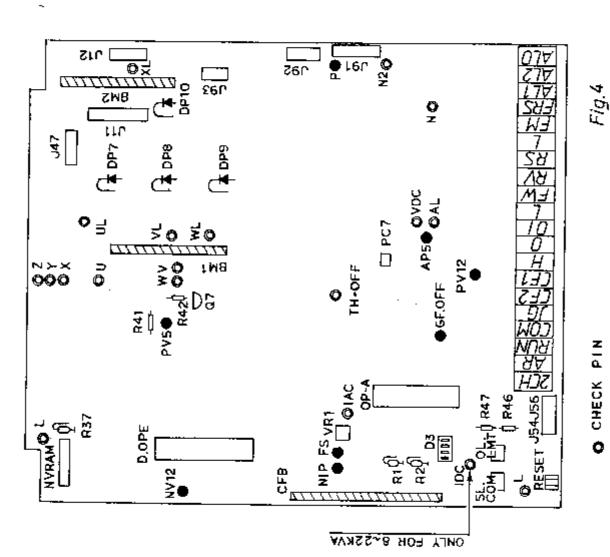
<sup>\*1)</sup> Power source of base circuit for 22kVA or less is positive voltage. Power source of base circuit for 33kVA or more is both positive and negative voltage.

<sup>\*2)</sup> L:PCB for control B:PCB for base drive

heck in	Use and level	Addres	s(Locat	ion)	See
<del></del> -		~5.5KVA	8 ~- 22k VA	33~75kVA	þag
U V W X Y Z	PWM signal from control board	2D 2D 3D 1D 1D 1D	20 3D 30 1D 1D 1D	3E(L) 3E(L) 2E(L) 2E(L) 3E(L) 2E(L)	
FS	V/F converter output signal FS — L FS-L	6A	6A	4A (L)	
	FS — L 0-L = 10V (Dip. switch 10V) 5V (Dip. switch 5V)	į			
IAC	In case of the above FS-L : approx.390kHz  Motor current detecting signal  IAC-L	7B	7B	5C(L)	24
100	DC-current signal IDC-L		AQ	7E(L)	<u> </u>
N1Þ	Motor speed detecting signal It is used for automatic restart  NIP-L	6A	6A	5E(L)	
				ļ	
1.OFF	When it is shorted with ([) ,electric thermal and over load limiter function would be stopped!	- 6C	6C	4E(L)	<u></u>
ો <u>'</u>					

Table 5





PARTS LAYOUT OF CONTROL BOARD

CHECK LAND

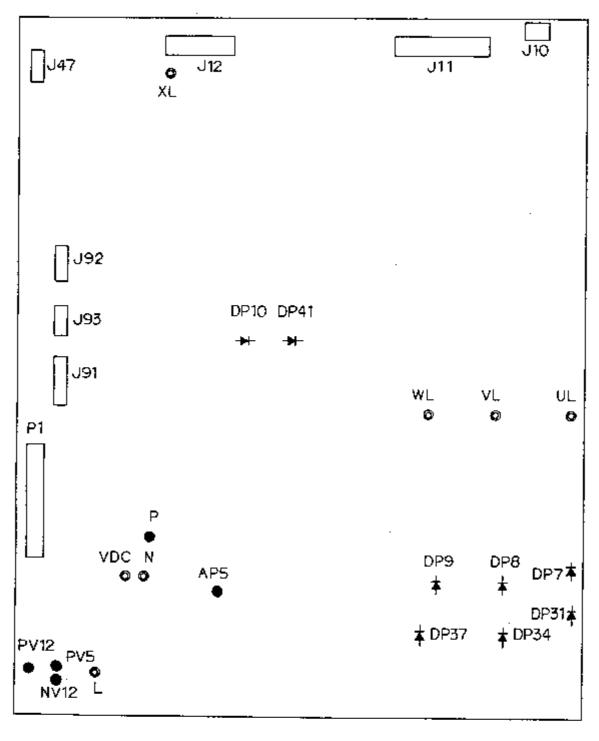


Fig.6

#### 4 TROUBLE SHOOTING

#### 4-1 TROUBLE SHOOTING AND MESSAGE CONTENTS

The inverter will operate as shown in Table 6 below if abnormal. Locate the cause and take corrective measures promptly before restarting operation.

Table 6 Fault Message and Diagnosis

	Symp	to mose	MA][unction					
Circuit breaker	Electromagnetic	Thermal relay	Display on digital operation panel (!ERROR	Pault elarm relay	Cause for fault (Massage contents)	Reset	Check points	Suggested remady
			Over.V	o	BC smoothing circuit - Overvoltage	٨	Check for sudden deceleration.	Increase the docs s- tation time.
							Check that the motor is not rotated from the load side.	The motor compot be applied to continuous regenerative load.
			OC.Accel	0	Overcurrent during motor acceleration (overcutrent at	٨	Check for sudden acceleration.	Increase the acceleration time.
					acceleration)		Check for output shorseirevet or ground fault.	Check for the output line (motor) and motor shortcircuit.
							Check that torque boost is not too high.	Reduce the torque boost.
			[	ļ		Check that the motor is not locked. Check that jogging frequency is too high.	Check the motor or load. Reduce the jossins frequency.	
	_		OC.Becel	٥	Overcurrent during motor deceleration (Overcurrent at	^	Check for mudden deceleration.	Increase the deceleration time.
					deceleration)		Check for output shortcfrouit or ground fault.	Check the output line motor shortcircvited.
			OC.Drive	٥	Overcurrent during constant operation of motor	^	Check for sudden change in load.	Eliminate pudden changes in load.
					(Overcurrent during operation)		Check for output shortcircult and ground [au]t.	Check the output line motor shortcircuit,
			Over.L	٥	Inverter overload (Overloaded operation)	^	Check that the load is not too heavy.	Reduce the load factor.
	.						Check that the electronic thermal level is correct (not changed).	Adjust to a proper level.

	5ym	plan c	f maifunction		<u> </u>	7		
Circuit Breaker	Electionagnetic	Thermal relay	Display on digital operation panel (?ERROR	fault alarm relay	Ceuse for (sult (Hossage contents)	Reset	Check paints	Suggested remedy
i			Olt F1a	5	Temperature eignili- cantly increasing (Fin overheat)	- 1	fan is rotating.  Check that the ambien temperature is not to	ten.
	<u>.</u>		OVER C.	0	Overcurrent detection just witer power OH	^	Check that the detector current circuit is normal.	Check abnormal conditions of current detector and PC board detector circuit.
	İ		Under V.	P	Power supply abnormal (Undervoltage)	^	Check that no voltage drops.	Review the power supply system.
							Check that no poor contact of MCB and Mg is found.	Replace HCB and Mg.
	į	İ					Check that power has been turned OFF or instantaneous power failure has occurred during jogging.	Do not turn power OFF during logging operation.
	_	_					Check that 100 mser or leas increnteneous power failure has occurred more than 10 times repeatedly for 10 minutes.	Re-check the power supply system.
			Inst.?-?	D	Power supply abnormal (Instantaneous power	٨	Check that no voltage drop is found.	Review the power supply system.
	_				(ailure)		Check that no pour contact of MCB and Mg is found.	Replace MCB and Mg.
			NC-FRS	٩	Pres-run stop command abnormal	٨	Check that the opera- tion command is given during motor free-run, and that no FRS is entered.	Do not enter operation command, FRS during free run.
							With Free-run Stop applied, undervoltage or instantaneous power failure has occurred.	Re-start operation after reset.
							With Free-tun Stop applied, power has been cut off.	Re-start operation after react. With Free-run Stap applied, do not turn
							With Free-run Stop applied, power has been turned ON or reset operation has been performed.	power OFF.

:\_\_\_\_;

DB OT O (DC braking setting A line source is found massly.)  Inverter shootmel Repair  A Check that the DC braking external command input time does not exceed the time press by F-22 T-DCB to or adjust DC braking command input time does not exceed the time press by F-22 T-DCB.  NG-JOC O (The jogging mode is used inadvertent)  NG-J					_		_		<del></del>
CPU O (CPU prior)  A Check that no large noise source is found sawy from the unit.  DB OT O CDC broking setting Inverter shnormal  Check that the DC braking external command input time does not exceed the time press by F-27 T-DCB.  NG-JOG O (The jogging mode is used inadvertent)  NG-JOG O (The jogging mode is used inadvertent)  DB OT O (The jogging mode is used inadvertent)  A Check that the DC braking external command input time does not exceed the time press by F-27 T-DCB.  NG-JOG O (The jogging mode is used inadvertent)  A Check that power has been switched or reset operation has been turned ON in do not turn power ON, switch commercial power supply voltage has been switched or reset operation has been preformed.  B Power supply side short-circuit and ground facious fault.  Insufficient MCB capacity.  Inverter module or converter module or converter module of samply system.  Check that no poor contact of MCB and Mg is found.  Check that no poor contact of MCB and Mg is found.  Thermal relay preset samply system.  Check that no poor contact of MCB and Mg is found.  Thermal relay preset samply system.  NG.DB O DE terminal was used inadvertently.  A Walt Supply voltage who from power ON or reset operation has been performed.  Which DR ON, do not turn power ON or reset operation has been performed.  With DR ON, do not turn power ON or reset operation has been performed.  Review the power supply system.			epton :	of malfunction				İ	
DB OT O (DC brebing setting account in found maxify.  DB OT O (DC brebing setting account in found maxify.  A Check that the DC braking external command input time does not exceed the time over.)  NG-JDO O (The jogging mode is used inadvertent)  NG-JDO O (The jogging mode is used i	Circuit breaker	. Electromagnetic	Thersal relay	digital operation panel (TERROR,	Fault alarm relay		Raser	Check points	Suggested Tempdy
DB OT  O (DC breking setting alternal command input tine does not exceed the time over.)  NG-JDG  O (The jogging mode is used insdvertent)  O (The jogging is used insdvertent)  O (The jogging mode is used insdvertent)  O (The jogging mode i		!		СРИ	۰	(CPU peror)	^	noise source la found	Keep the noise source sway from the unit.
time over.)    Containing external command input time does not exceed the time present by F-22 T-DCB.    NG-JOG   Containing mode is used inadvertent-live line to less than time to less than time to less than time to less than T-DCB.    NG-JOG   Containing mode is used inadvertent-live line to less than time to less than time to less than T-DCB.    NG-JOG   Containing mode is used inadvertent-live line to less than time to less than the time to less than the time to less than time to less than time to less than the time to less				<u></u>		1		Inverter abnormal	Repair
a sued inservented been turned ON with the jogging mode ON, do not turn commercial power supply voltage has been turned on with the jogging mode ON, do not turn power ON, switch commercial power supply voltage has been switched or reset operation has been performed.  B Power supply mide shortcytcuit and ground fault.  Insufficient MCB circuit and ground fault.  Insufficient MCB capacity.  Inverter module or converter module or converter module damaged.  Chack for the power failure.  Chack that no poor contact of MCB and Mg.  Check that no poor contact of MCB and Mg.  Check that no poor contact of MCB and Mg.  Thermal relay preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Thermal relay preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Thermal relay preset value factor.  Set the preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Set the preset value factor.  Set the preset value factor.  Thermal relay preset value factor.  Set the preset value factor, supply values depond to value factor, supply system.				DB QT		(DC broking merting time over.)	^	braking external command input time does not exceed the time preset by F-22	
abortectes and ground fault.  Insufficient MCE capacity.  Inverter module or content and ground fault.  Insufficient MCE capacity.  Inverter module or content module or content and module demaged.  Power failure  B Chack for the power failure.  Check that no poor content of MCB and Mg.  Check that no poor content of MCB and Mg.  Check that no poor content of MCB and Mg.  Replace MCB and Mg.  Coverload  Reduce the load factor.  Thermal relay preset value to a proper one.  RG. BB  D B terminal was used insovertently.  A With DB DM, power has been turned ON or reset operation has been performed.  GV WAIT  Supply voltage abootmal (Undervoltage)  When restart function was supply system.				DOC - DM	a	is used insovertent-		been turned ON with the jogging mode ON, commercial power supply voltage has been switched or reset operation has been	power ON, switch commercial power supply voltage or
D	0			-	-	-	В	shortelreuit and	circuit and ground
Converter module demaged.  Power failure  B Chack for the power supply system.  Check that no poor contact of MCB and Mg is found.  C Overload  Reduce the load factor.  Thermal relay preset value faulty  RG. DB  DB terminal was used inadvertently.  A With DB DM, power has been performed.  But DB voltage abootmal (Undervoltage)  A When remart function may selected, supply system.						ļ			
Check that no poor contact of MCB and Mg is found.  C Overload Reduce the load factor.  Thermal relay preset value faulty  DB terminal was used insolvertently.  OU WAIT  Supply voltage abnormal (Undervoltage)  A When restart function was supply aystem.				-				converter module	Repair
contact of MCB and Mg is found.  O	ļ	•		-	-	Power failure	•		
Thermal relay preset value factor.  Thermal relay preset value faulty  DE terminal was used insolvertently.  A With DE DN, power has been turned ON or reset operation has been performed.  OV WAIT  Supply voltage absormal (Undervoltage)  A When restart function Review the power supply system.	1				_			contact of MCB and Mg	Replace MCB and Mg.
NG. 88 O DE terminal was used inadvertently.  OF WAIT  OF WAIT  OF WAIT  OF DE terminal was used inadvertently.  A With DE DM, power has been turned ON or reset operation has been performed.  When restart function Review the power shootmal (Undervoltage)  OF WAIT  OF WAIT  OF DE terminal was been turned ON or reset.  When restart function was selected, supply system.			0	-	-	-	С	Overload	
used insovertently.    Deen turned ON or reset operation has been performed.		•	;						Set the preset value to a proper one.
abnormal uar selected, supply system.  (Undervoltage) voltage dropped to				NC.DB	0		٨	been turned ON or reset operation has	turn power ON or
<u>                                    </u>	.			TIAW VD		ebnormal .	٨	was selected, supply	

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	:	Sympton	of matfunction	ЭП				] <u> </u>
Circuit breaker	Electromagnetic	2 -	Display on digital opestion panel (JERBOR	Fault elara relay	Cause for (sult (Message contents)	Reset	Check points	Suggested (exect)
			ADJUST 0.5\$		Supply voltage absorted	۸	Re-start function was selected without connecting Ro and To, and instantaneous power failure and underwollage UC, UV cripped (200v class).	Connect Ro and To.
_	i		BOO Nymeral		Refer to para. 12.2 on the following page.	b	Refer to para. 12.2 on the following page.	Refer to pars, 12.2. on the following page.

· : .}

O: allows the equipment which seems to operate in general.

when trouble happens. No motor rotates Check the wiring between inverter and motor. Check the input voltage whether it is rated voltage or not. Check the wiring between (FRS) and (1) on the circuit board \*They should be open. ---(FRS) (normally open ) Check the wiring between (RS) and (L) on the circuit board \*They should be open. Check the operation mode in the monitor mode whether it is set according to application system. F-SET-M: OPE-key/Terminal F/R-SW : OPE-key/Terminal Check the reference (freq.setting) signal Wh<u>en F-SET-M "OPE-key" is selected, check the</u> FS Hz in the monitor mode. When F-SET-M "Terminal" is selected, check the voltage or current signal on the terminal of printed board. (V<sub>O-1</sub> :0~10VDC or 0 5VDC) Also check the FS□□□. □□Hz [I<sub>OI-L</sub>:4~20mA in the monitor mode. dash Check whether setting frequency is less than minimum frequency \*Set the frequency more than minimum frequency. - Check whether LCD indication is in "Monitor" mode. \*Select "Monitor" mode. In the function mode, the inverter cannot start. Check whether  $\fbox{STOP}$  key of Dig.Ope is pushed when F/R-SW in "Monitor" mode is selected with "terminal". \*Once,run command(FW/RY) must be turned off,and then turned on again from the terminal. Check the output voltage of U-V,V-W and W-V whether they are balanced or not. Check whether setting frequency of "SPEED1"~"SPEED3" is proper value when you use multi stage speed terminal(CF1,CF2). \* "SPEED1~3" must be set or multi\_stage\_speed\_command (CF1,CF2) must be removed. Formard Bergrat \$Tor OFF DFF DN -Check whether RUN key and RUN key of D-OPE are pushed togethe in "Ope-key" mode. Check whether forward operation command and reverse operation command are input together in "Terminal" mode. \* Only one signal should be input.

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#### No motor accelerates

Check the reference((freq.setting) signal

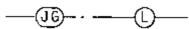
When F-SET-M "OPE-key" is selected, check the FS[  $\ \ \$  ]. Hz in the monitor mode.

When F-SET-M "Terminal" is selected, check the voltage or current signal on the terminal of printed board.

 $V_{O-L}$  :0~10VDC or 0 5VDC  $I_{OL-1}$ :4~20mA

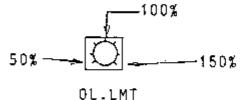
Check the F-05(frequency upper limiter).

Check whether the preset value of "F-END" in the function mode is more than maximum frequency.



Check the load whether it is too heavy or not.

\*Reduce the load or adjust the overload limit level by "OL.LMT" (VR) clockwise.



Check whether setting frequency of "SPEED1"~"SPEED3" is prope value when you use multi stage speed terminal(CF1,CF2).

\* "SPEED1 $\sim$ 3" must be set or multi stage speed command (CF1,CF2) must be removed.

# Over current trip (OC.Accel, OC.Decel, OC.Drive) OC trip comes immediately at starting ·Check the following after taking the motor from the inverter. - Whether OC. trip comes or not. OC trip comes. \* Check the power(transistor) module and base drive signal waveform:Page 27,28 - No OC, trip \* Check the following after connecting the motor. During the inverter operating(accelerating, decelerating or constant speed) - Whether the starting frequency is too high or not. — Whether the V-boust is too high or not. -Whether the load is too heavy or not.

- Whether the Acc./Dec. time is too short for the

Whether the jogging frequency is too high or not.

load GD' or not.

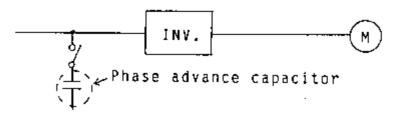
#### Over voltage trip

Check the deceleration time whether it is too short for the  $\mbox{\rm GD}^{\,2}$  of load or not.

\* Prolong the deceleration time.

\* Use the regenerative braking unit.

Check the power source network line whether there are phase advance capacitors on it and they are turned on/off during inverter operation or not.



- \* Change the wiring system with the phase advance capacitor.
- \* Put the braking unit in order to suppress the over voltage.

#### Instantaneous power failure trip

Check whether power source is turned on again before LCO display is turned off.

\* Power source should be turned on again after LCD display is turned off.

Power	ON <	1 > 0.3 sec.
LCD	//// ON	0FF

Check the magnetic contactor on the inverter primary side whether it has chattering or not.

Did the power failure occur?

\* If the automatic restart function after instantaneous power failure is allowed for the application system, use the automatic restart function in the function mode F-28.

F-28 switch 00000101

00: Not available restart 10: Available restart

#### Under voltage trip

Check the power source voltage whether they are less than protection level or not.

200Vclass 1.5~ 75 kVA : 150~160 VAC 400Vclass 2.5~75kVA : 280~320 VAC

Check the transient voltage drop by rush current into the smoothing condenser or starting current of the motor,

\* Increase the power source capacity.

\* Use the restart function on the F-28

F-28 switch 00000101

00: Not available restart 10: Available restart

Check the magnetic contactor whether it has chattering or not.

#### Overheat trip

Whether cooling fan in the inverter is rotating or not.

Whether air inlet and exhaust ports on the panel box is blocked or not.

Whether the cooling air path is blocked or not.

Whether the temperature in the panel box is less than specified value or not.

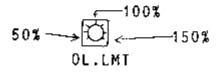
\* If it is too high, improve the cooling. :See page 59-62, selection of ventilation

#### Overload trip

Check the electronic thermal level in the function made F-23 whether it is proper for the load condition or not.

Check the overload limiter level whether it is proper for the load condition or not.

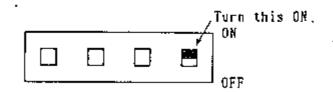
\* This level can change with "OL.LMT".



#### 4-3 HOW TO RETURN THE SETTING TO THE INITIAL SETTING

When retuning the setting to the initial setting for some reason, flolow the steps below.

- ① Turn power on.
- ② Set the right side of DIP SW on PCB to "ON".



- 3 With the MON FUN STR keys on the digital operation panel pressed at the same time turn the forced reset button ON.
- After resetting release these 3 keys pressed in 1 or 2 sec.

  At this time, BOOTHILL (ROM NO.) is displayed and operation steps.

If FM 000.0Hz is displayed, it means that these 3 keys has been released too early. Repeat steps ② - ④ above again.

NOTE: But NVRAM failure makes BOOCHITT remain displayed even for the above steps.

Good NVRAM : Displays FM 000. OHz by forced reset

Failed NVRAM : Displays still BOO[[0][0]] by forced reset

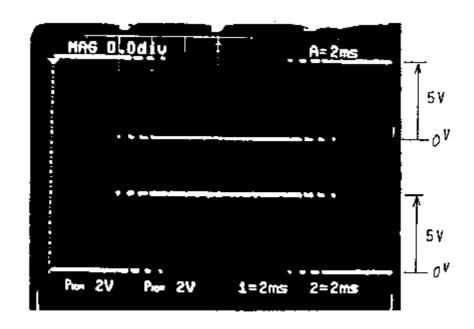
- ⑤ Turn power OFF or turn the forced reset buttom or switch ON.
- 6 Turn DIP SW OFF.
- Turn power ON again, and check that the data corresponds to the standard perset value (factory setting).

#### 5 mearsurment

#### 5.1 PWM OUTPUT SIGNAL WAVEFORM FROM THE CONTROL BOARD

- $\circ$  The PWM control signal can be checked with the check pins,U~Z, on the control board.
- Check pins and waveform

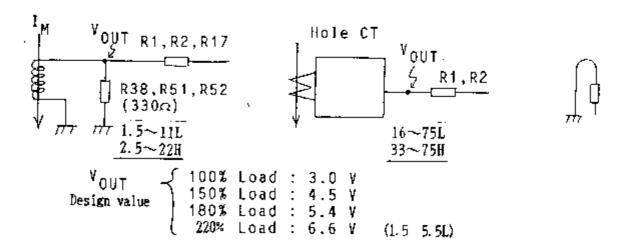
	Pin		Phase
U	←	L	V+
٧	<b>←</b>	L	٧+
W	<del>&lt;</del>	L	₩+
χ	<	L	U -
Υ	<del></del>	L	<b>V</b> –
Z.	<del></del>	L	W -



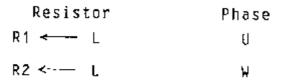
The pulse number would be changed according to output frequency.
 When the PWM signal is not proper, the control board should be changed.

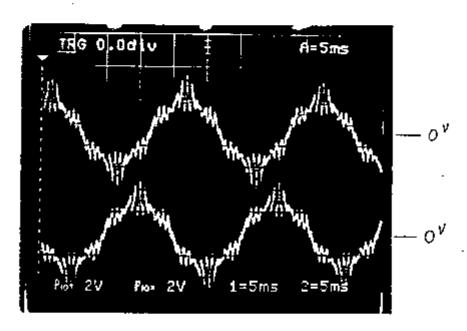
- The motor current waveform can be checked with resistors on the control board. The signals come from AC/CT of the output.
- AC/CT output

. 1



Resistors for check and waveform



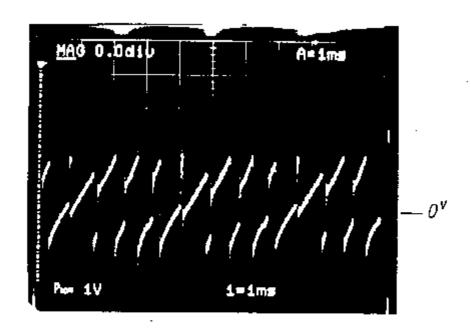


The waveform would be changed according to output frequency.

#### 5.3 DC-CURRENT SIGNAL

- The DC-current of the intermidiate circuit can be checked with the checkpin on the control board or base drive board.
- The signal is used for 0.0 trip.
- o Checkpin and waveform

N2 —N (on the control board) : 1.5~5.5kVA IDC—L (on the control board) : 8  $\sim$  75 kVA



#### • Trip level

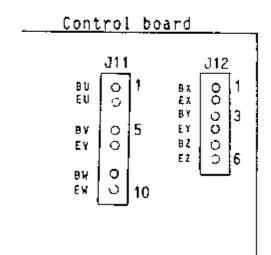
Inv. Model	1.5 ~ 5.5L 2.5 ~ 5.5H	8 ~ 33L 8 ~ 40H	401	50~75L	50 ~ 75H
Trip level (Design value)	1.37	6.67	7.97	7.60	7.18
Checkpin	N2 — N		IDC — L	<del> 1</del>	<del></del>

#### 5.4 Output signal of base drive

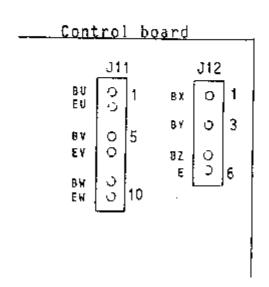
#### 1.5, 2.5L

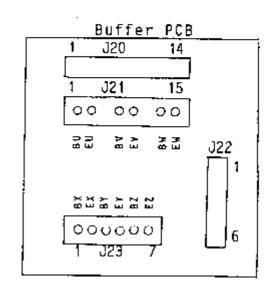
#### Control board J11 J12 80 Bx | 0 | 1 BY 0 3 B٧ o |5 E۷ 006 ΒZ В₩ 0 E₩ ০ [10

#### ②3.5,5.5L, 2.5~8H

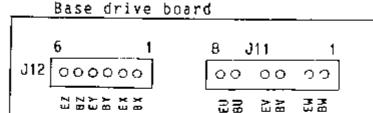


#### ③8~22L, 11~22H

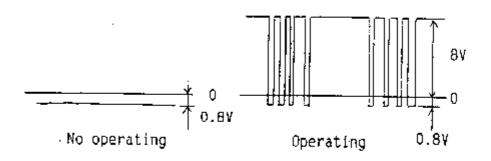




#### @33~75KVA



#### Q1. 5, 2, 5L



#### 23.5.5.5L 2.5<u>∼8</u>H

#### Ø8~22L, 11~22H

### Wiring color

B - Black BL- Blue

BR- Brown

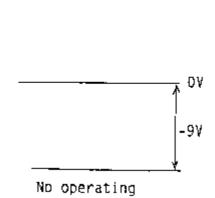
Green

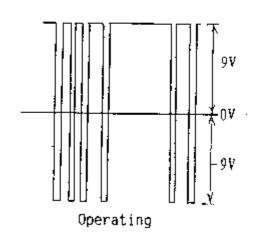
Orange ٧ Violet

Ř Red

W White Yellow

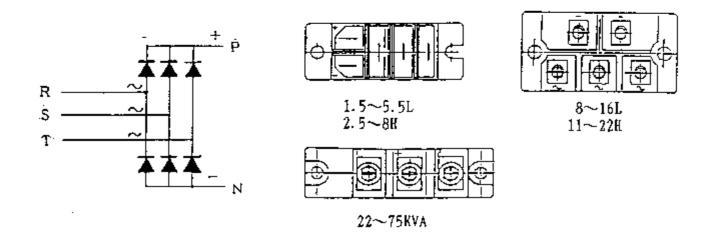
#### @33~75KVA





#### 5.5 How to check converter modules

The converter module can be checked to a certain extent at terminals.



#### Converter module circuit diagram and top views

Turning off power source, make sure that voltage between P and  $^{\rm N}$  is below 15V before operation.

Remove the wirings connected to the converter module and check it alone.

Measure with the tester set to 1 nrange.

Colors of tester terminals BlackRed	Resistance value
$\begin{array}{ccc} R(\sim) & \longrightarrow & S(\sim) \\ S(\sim) & \longrightarrow & T(\sim) \\ R(\sim) & \longrightarrow & T(\sim) \end{array}$	50kn or more
P(+) → R(~) P(+) → S(~) P(+) → T(~)	50ks or more
$\begin{array}{ccc} R(\sim) & \longrightarrow & P(+) \\ S(\sim) & \longrightarrow & P(+) \\ T(\sim) & \longrightarrow & P(+) \end{array}$	50a or less
$N(-) \longrightarrow R(\sim)$ $N(-) \longrightarrow S(\sim)$ $N(-) \longrightarrow T(\sim)$	50s. or less
$\begin{array}{ccc} R(\sim) & \longrightarrow & N(-) \\ S(\sim) & \longrightarrow & N(-) \\ T(\sim) & \longrightarrow & N(-) \end{array}$	50ka or more

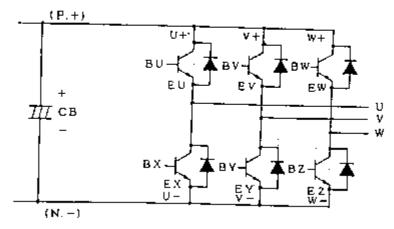
~:alternation terminal

If the resistance value is not proper, replace the diode module.

\* Failure symptom : MCB trip (shortcircuit of Power module)

#### 5.6 How to check inverter modules

The inverter module can be checked to a certain extent at terminals



Inverter module circuit diagram

Turning off power source, make sure that voltage between P and N is below 15V before operation. Measure with the tester set to  $1\Omega$  range.

(Easy method to check inverter module without disassembly)

Color of tester terminal. BlackRed	s Resistance value	Check spot
P → U	50k A or more	<u>U+</u>
₽ → ₩	30K12 or more	V+ W+
N U	50,0 or less	U- V-
N → W U → P		. W-
V -> P	50 A or less	<u>U</u> + V+
U - 2 N		₩+ U-
	_ 50kΩ or more	V - W -

(Check after disassembly)

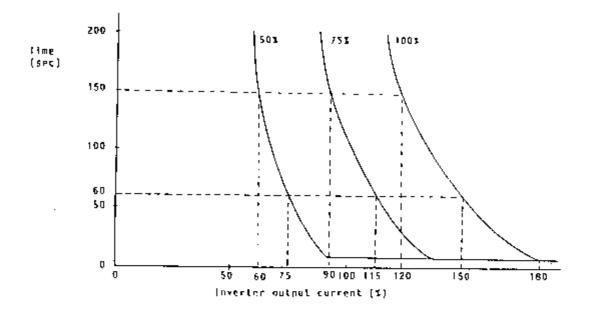
Color of tester terminals BlackRed	Resistance value	Check spot
BU -> U BV -> W	100 $_\Omega$ or less	U+ V+ W+
BY -> U BY -> V BZ -> W	100 p or less	U - V - W -
U → BU V → BV W → BW	50 ~ 200 n or more	U+ V+ W+
U         →         BX           V         →         BV           W         →         BZ	$50\sim200\Omega$ or more	U- V- W-

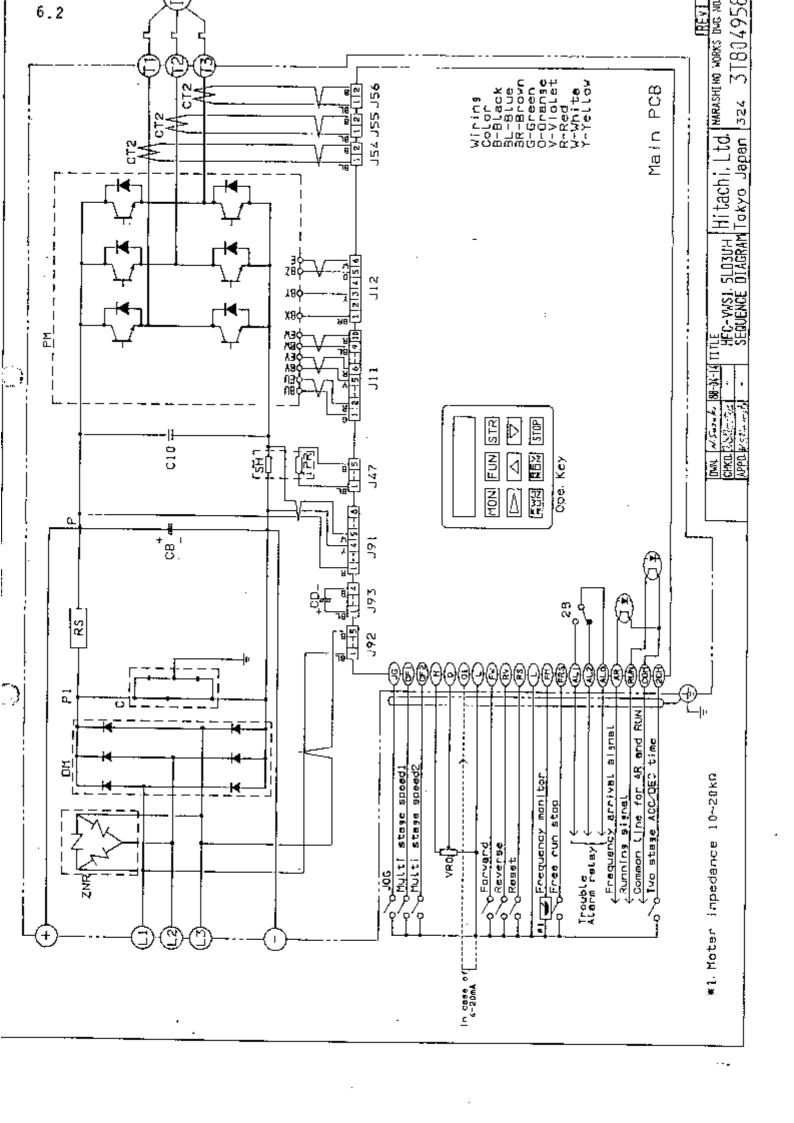
<sup>\*</sup> Failure symptom : Over current trip causes without connected to a motor.

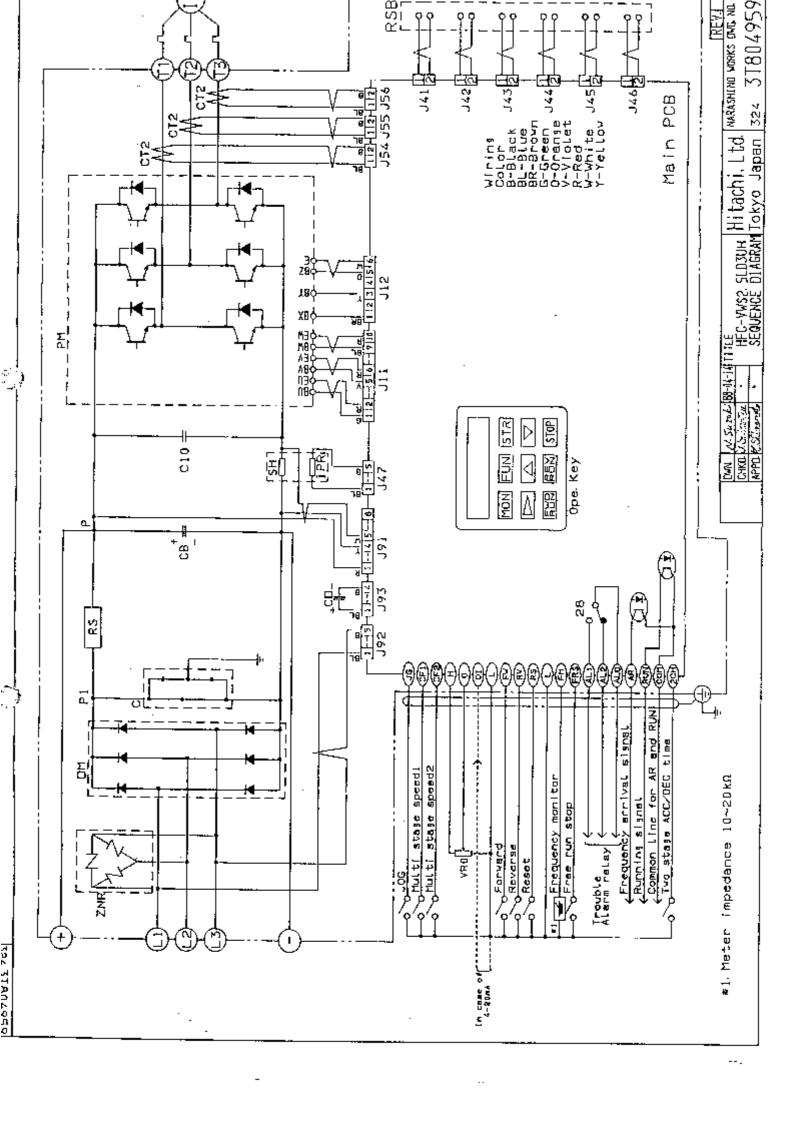
E-THERM FUNCTION ( F-23 ) 6-1

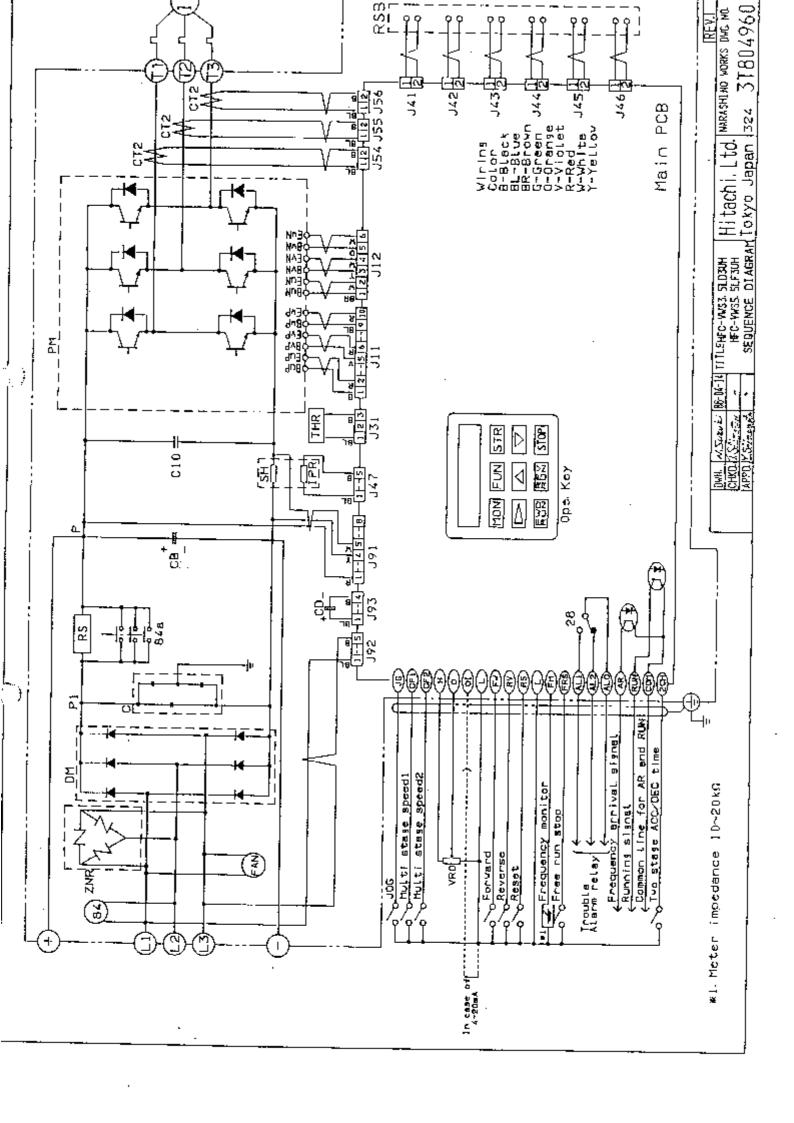
The protection characteristics of the electronic thermal can be changed by OPE-key.

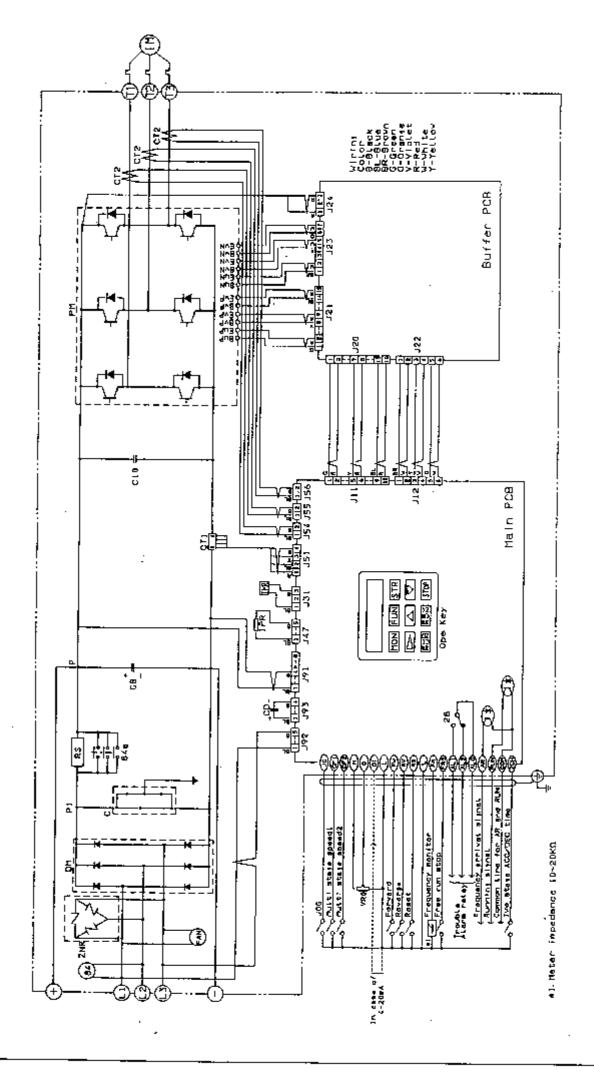
The characteristics is approximately as follows:



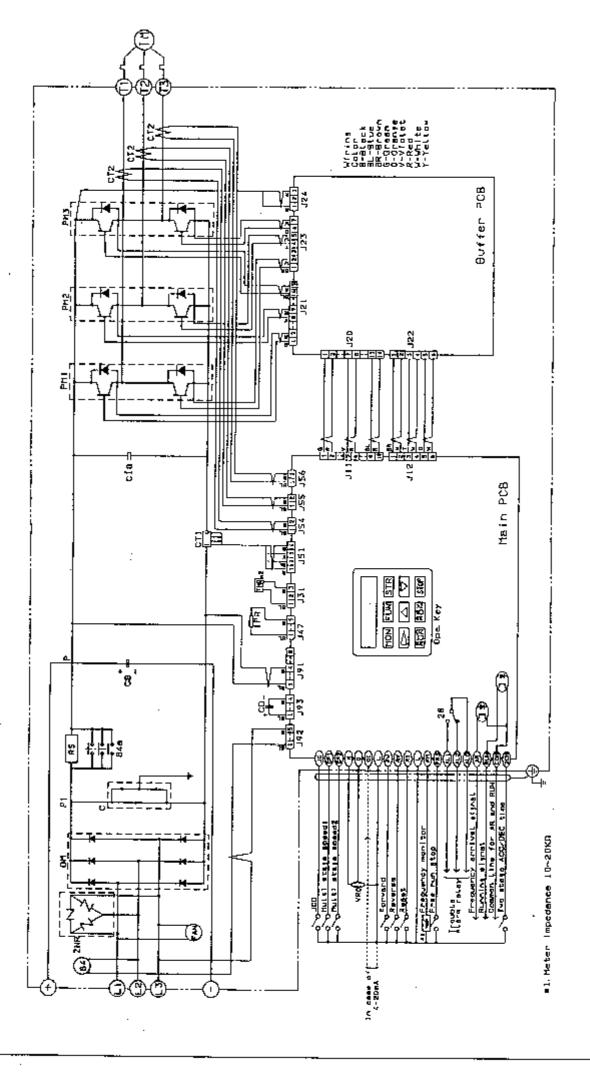




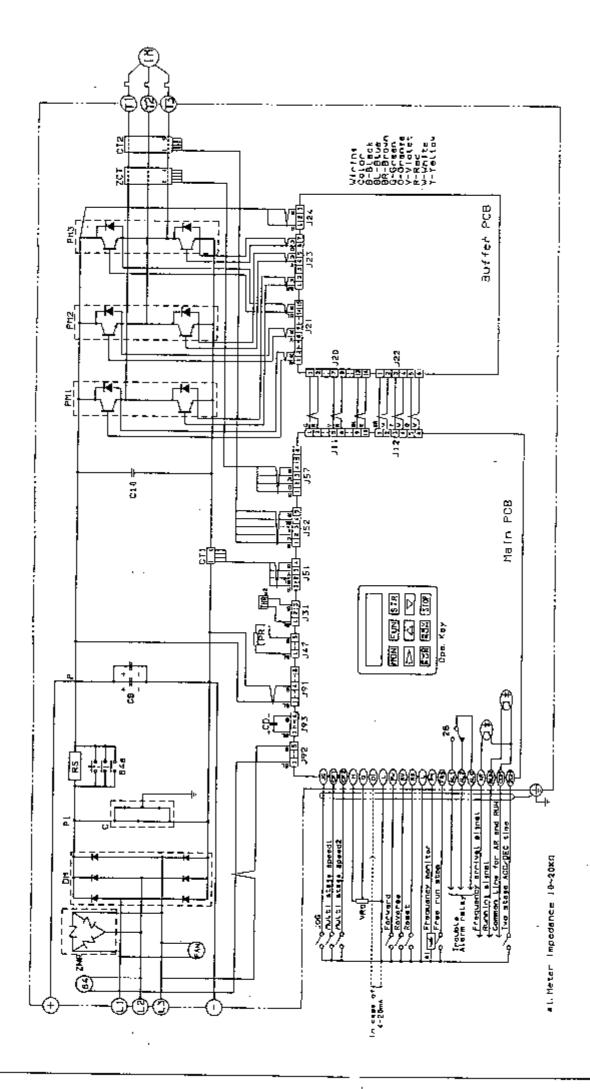


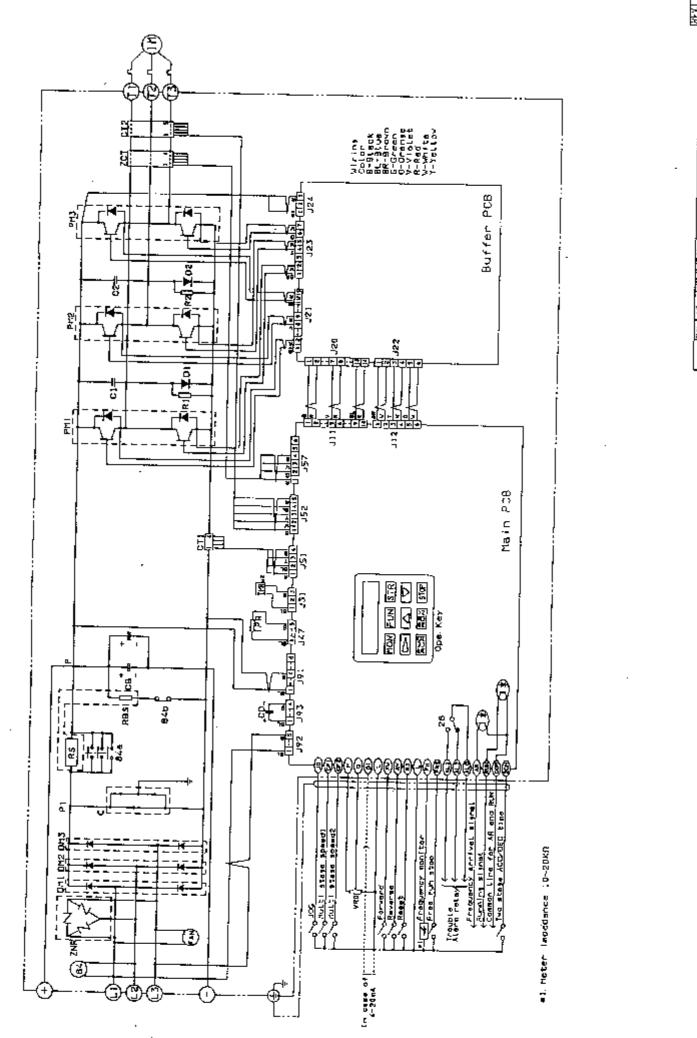


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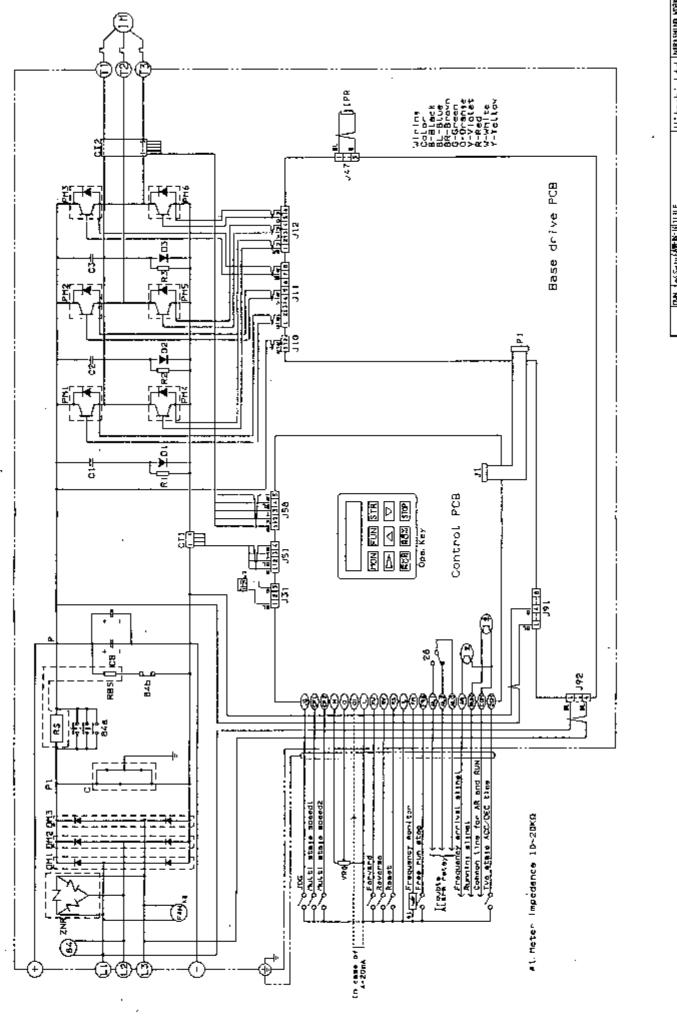




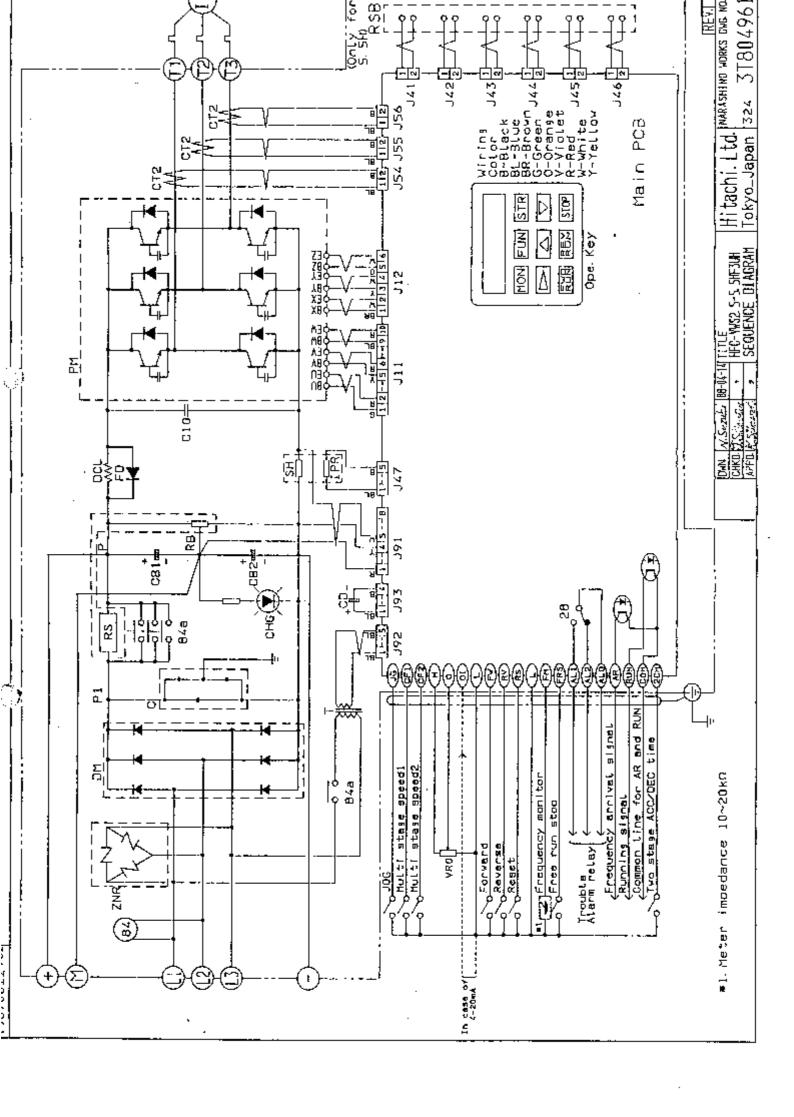
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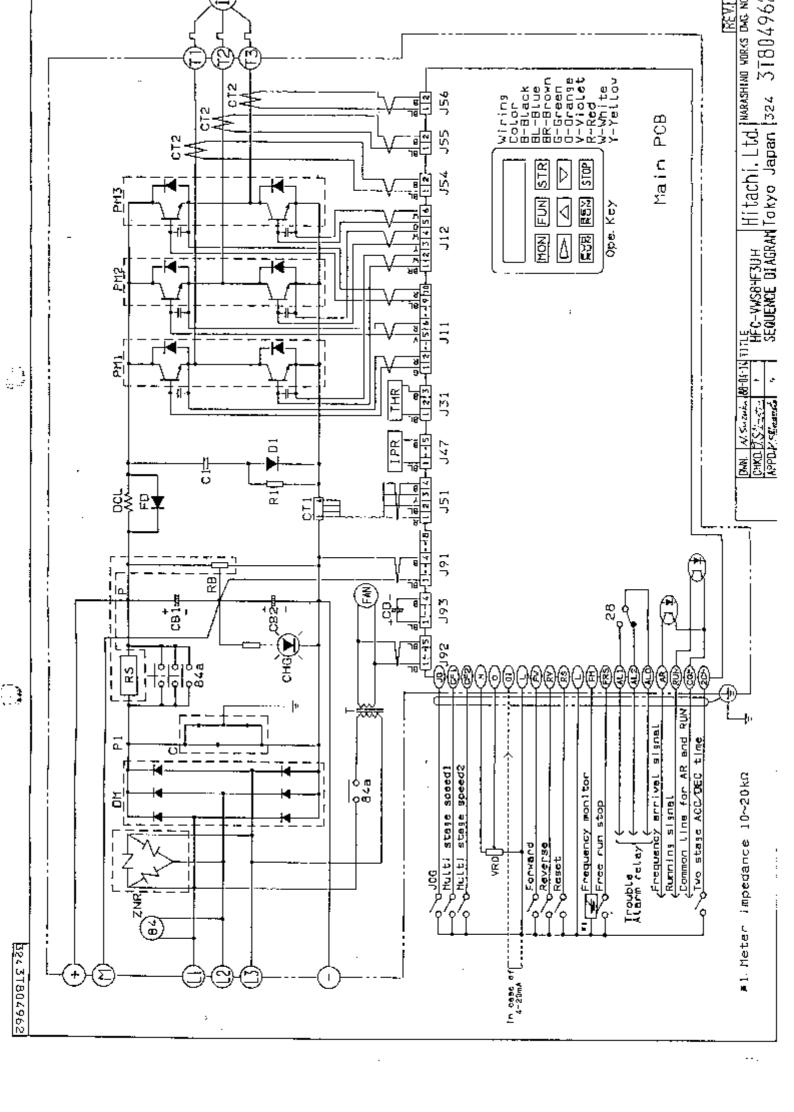
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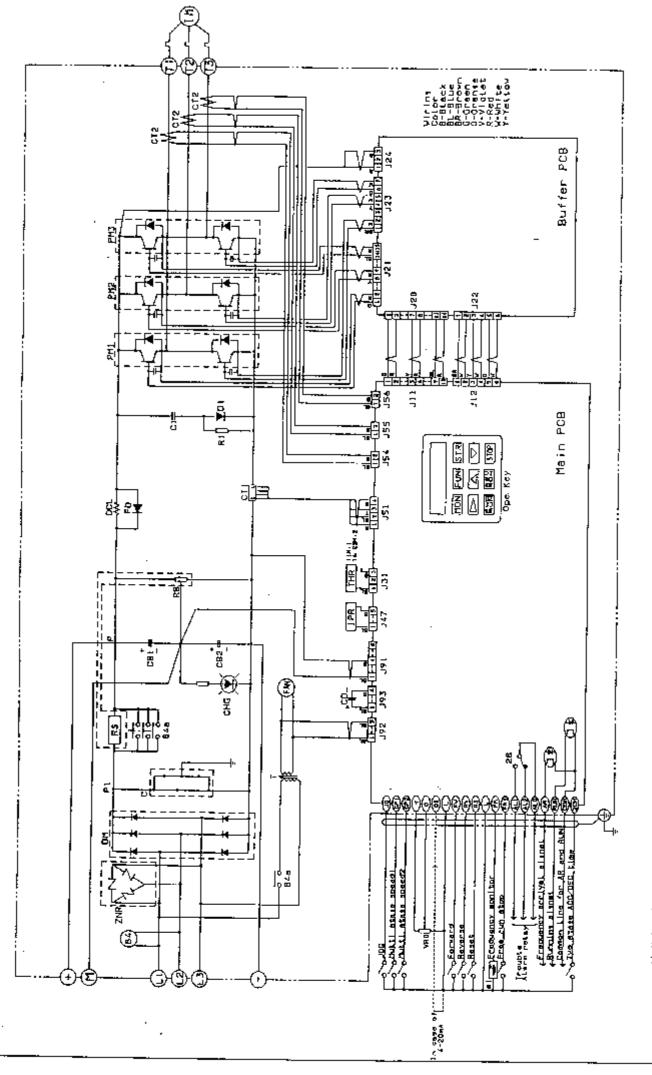
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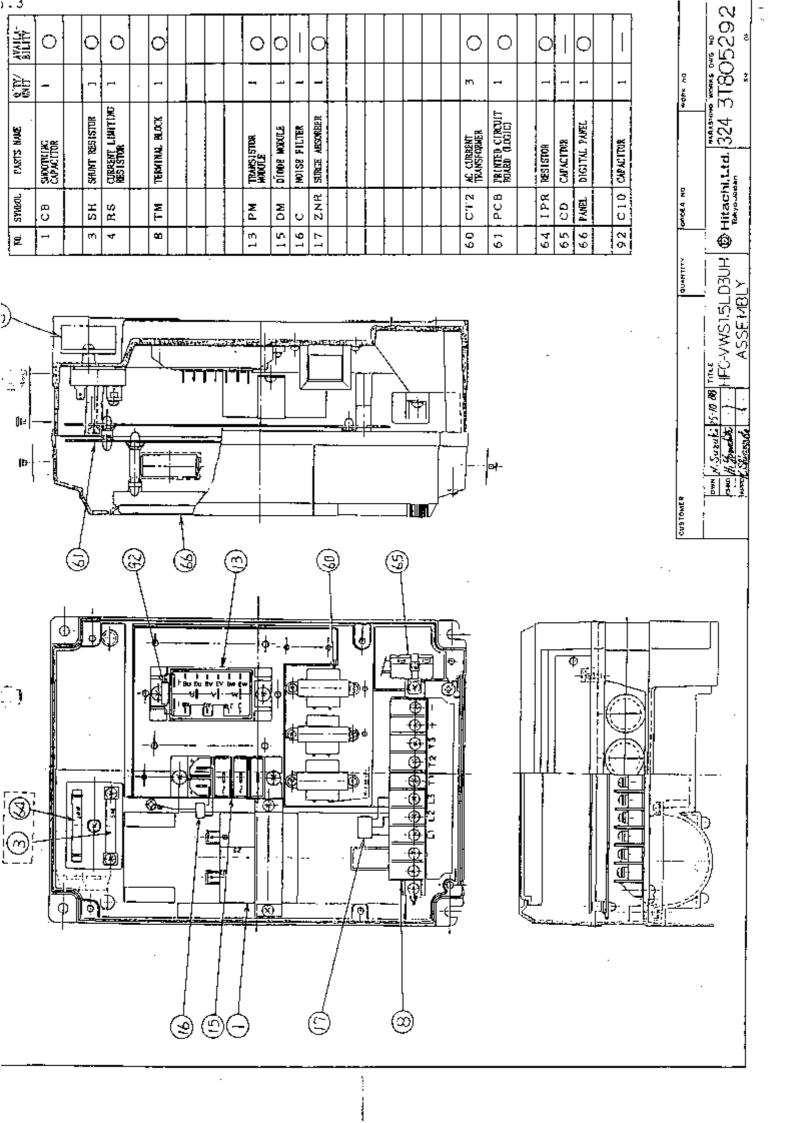
#1. Neter impedance 10-20Kh

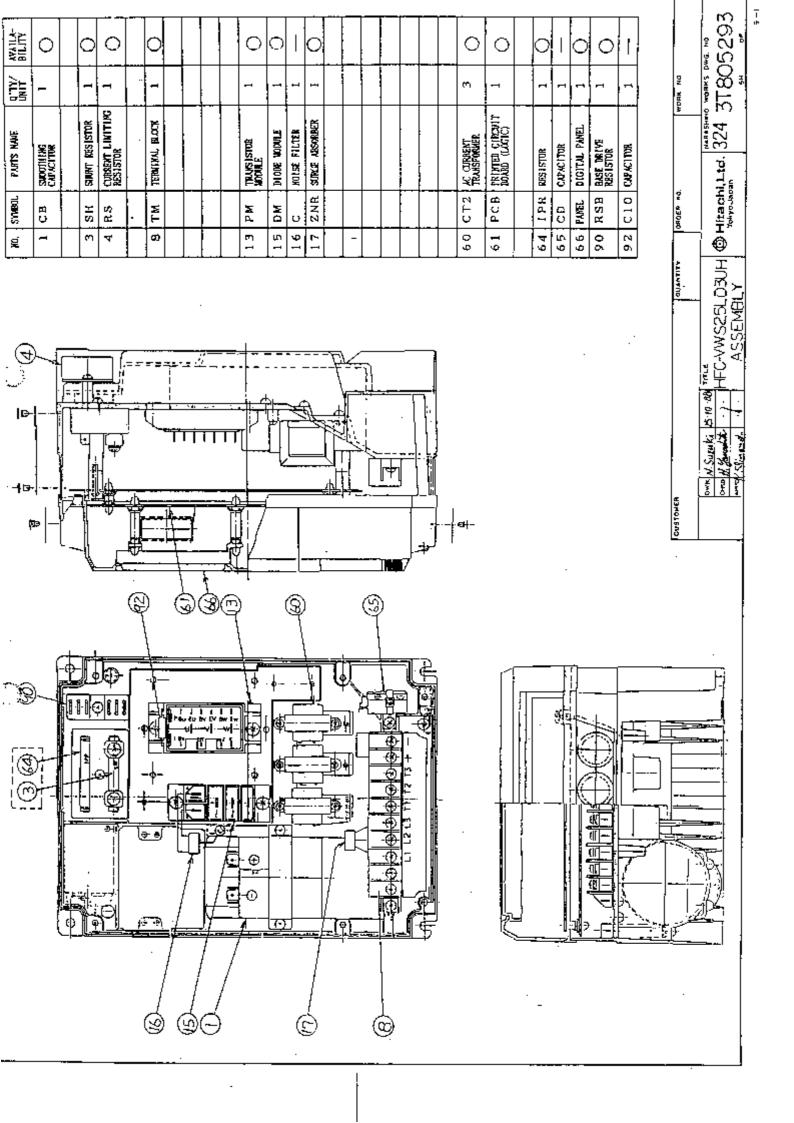
| REV | ASSAURT | PROPERTY | PROPERTY | HITACH | Ltd. | MARTSHEW VARKS AND | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LYD. | LY

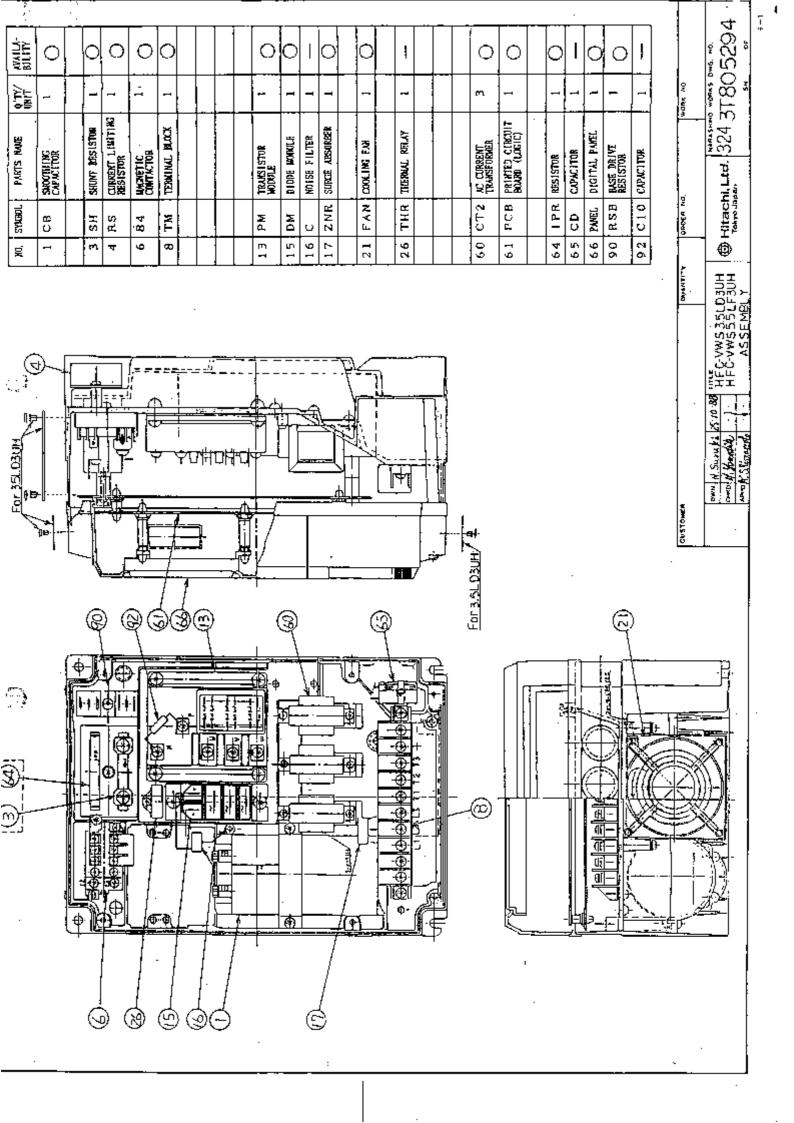
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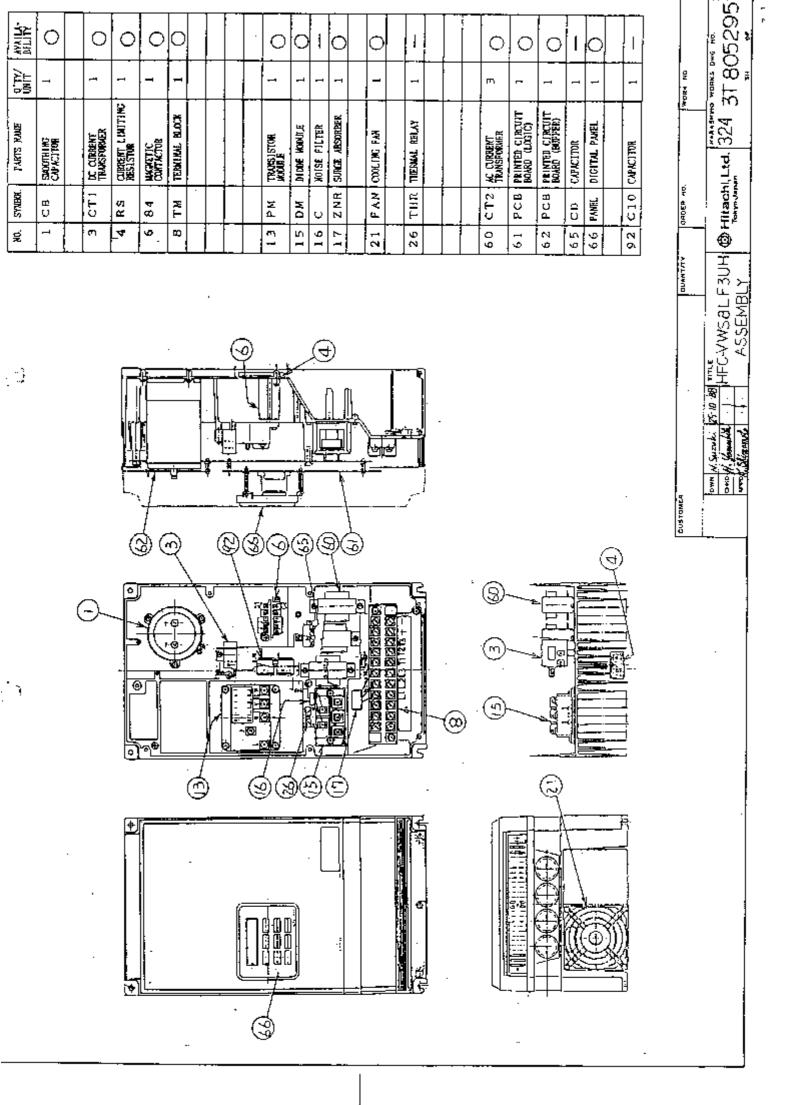
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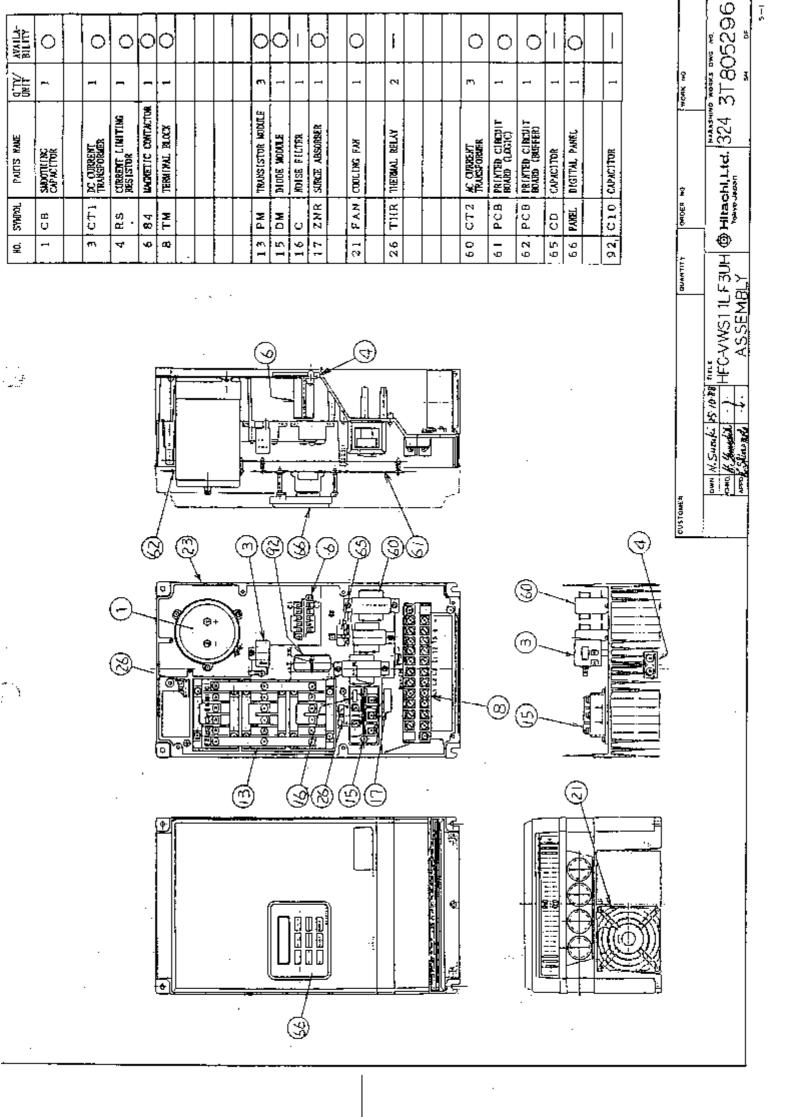
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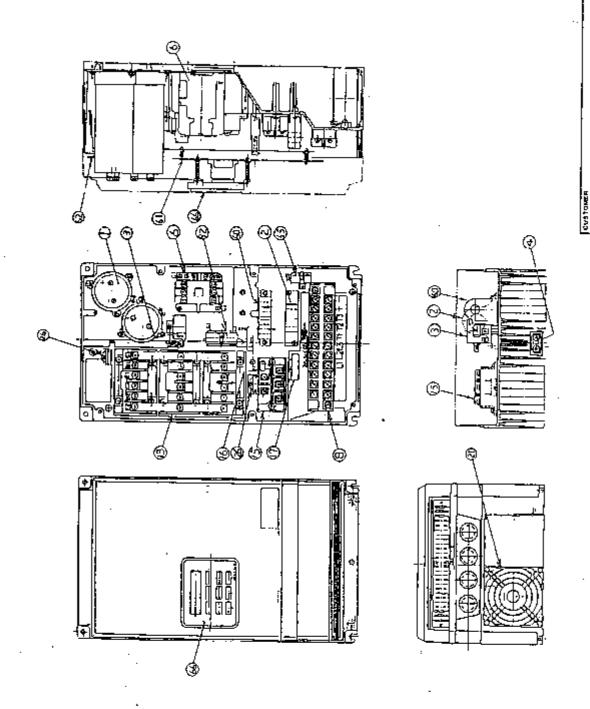




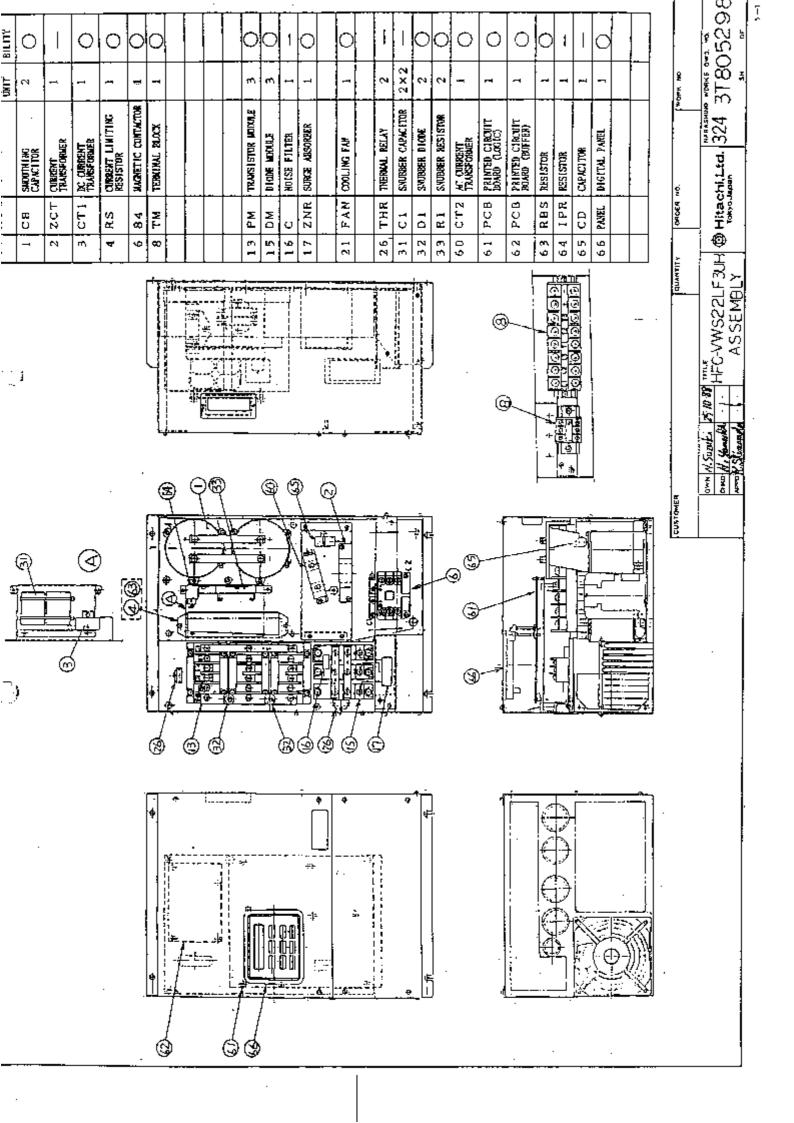


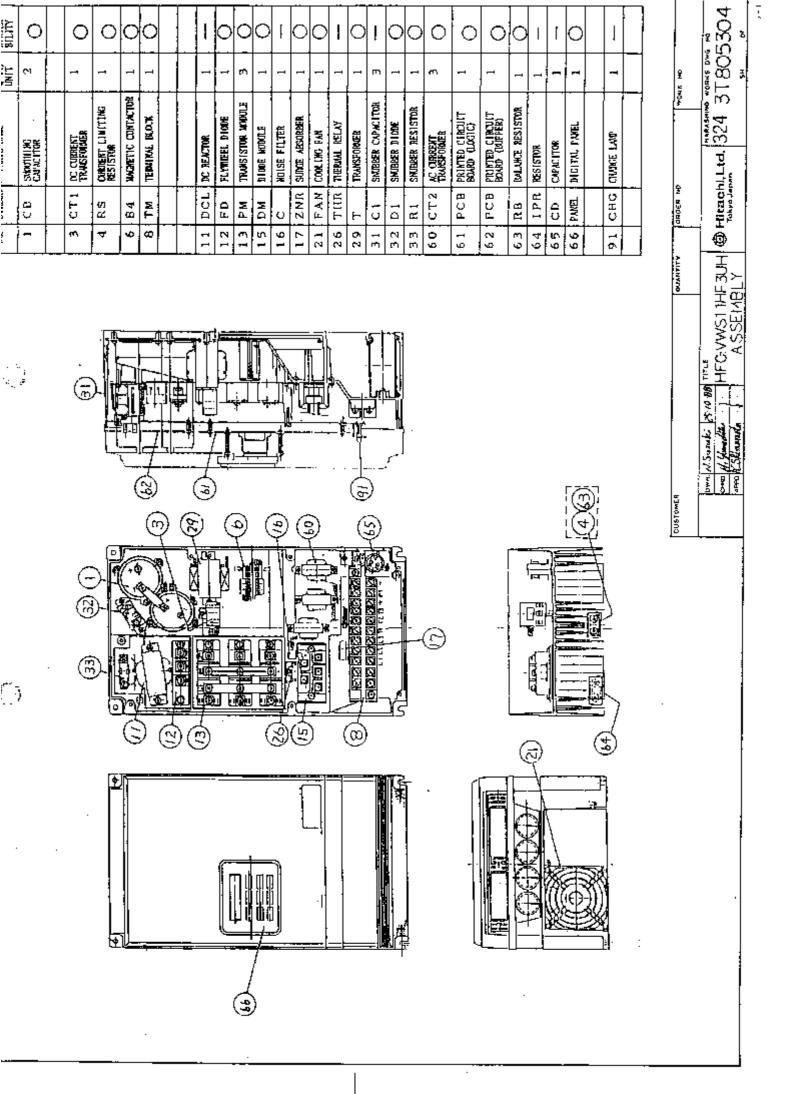
AVALLA- RELITY	0	0	0	0	0	0			0	0	1	0	0					0	0	0	1	0	ı
4.TY/ 1.KU	3	1	1	ĭ	-			<b>i</b>	m	-	-	-	1		2			_			_	1	1
ana staat	SMOOTHING	CURRENT TRANSFORMER	IC CURRENT TRANSFORMER	CURRENT CLAFFING RESISTOR	MACHETIC CONTACTOR	TERLING, BLOCK			TRANSISTOR MODULE	ETINAON BADIA	NOTESE FILTER	SURCE ABSOIDER	CDOLLING PAN		TIERNAL RELAY		:	AC CURRENT TRANSFORMER	PRINTED CIRCUIT BOARD (LOCIC)	PALINTED CHROUT BOARD (BUFFER)	CAPACITOR	MOUTHL PAISE	CAPACITOR
SYMPOL	CB	zcr	ст1	ЯS	84	M			PM	MO	υ	ZNR	FAN	ŀ	THR			CT2	РСВ	РСВ	CD	PANEL	010
ND.	1	2	3	4	9	Ø			13	51	91	17	21		26			60	19	62	6 5	99	9.2

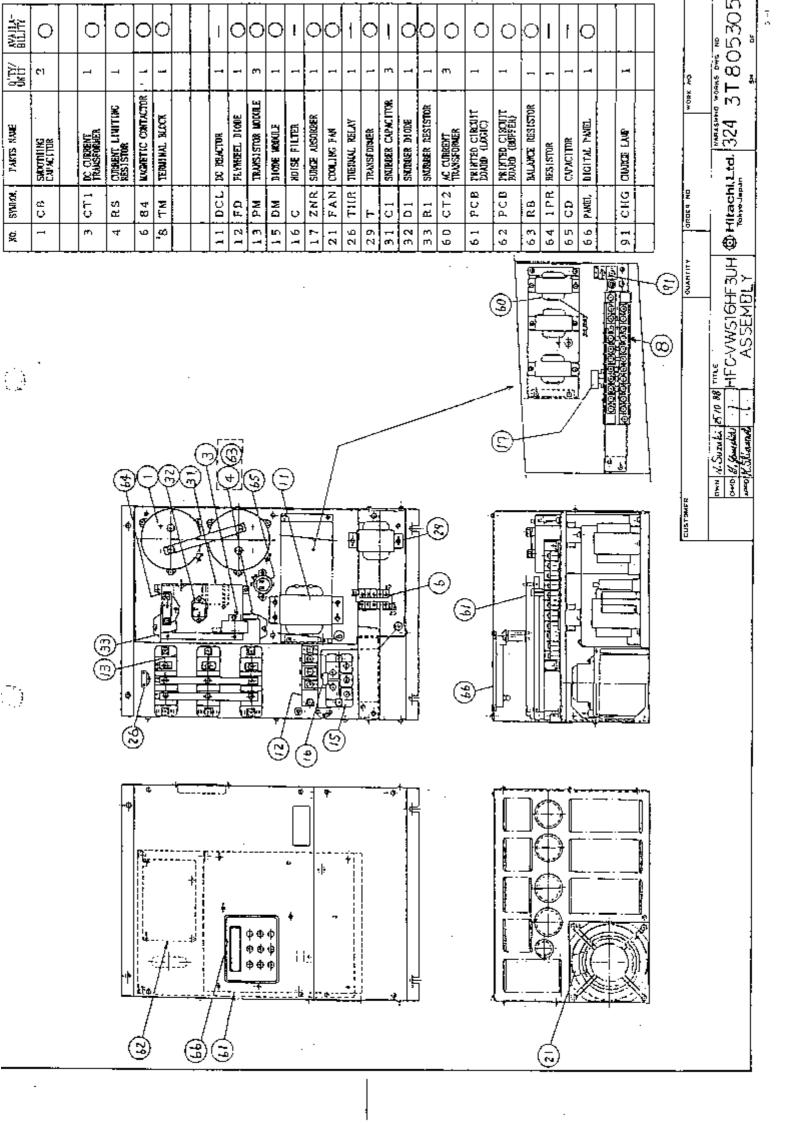
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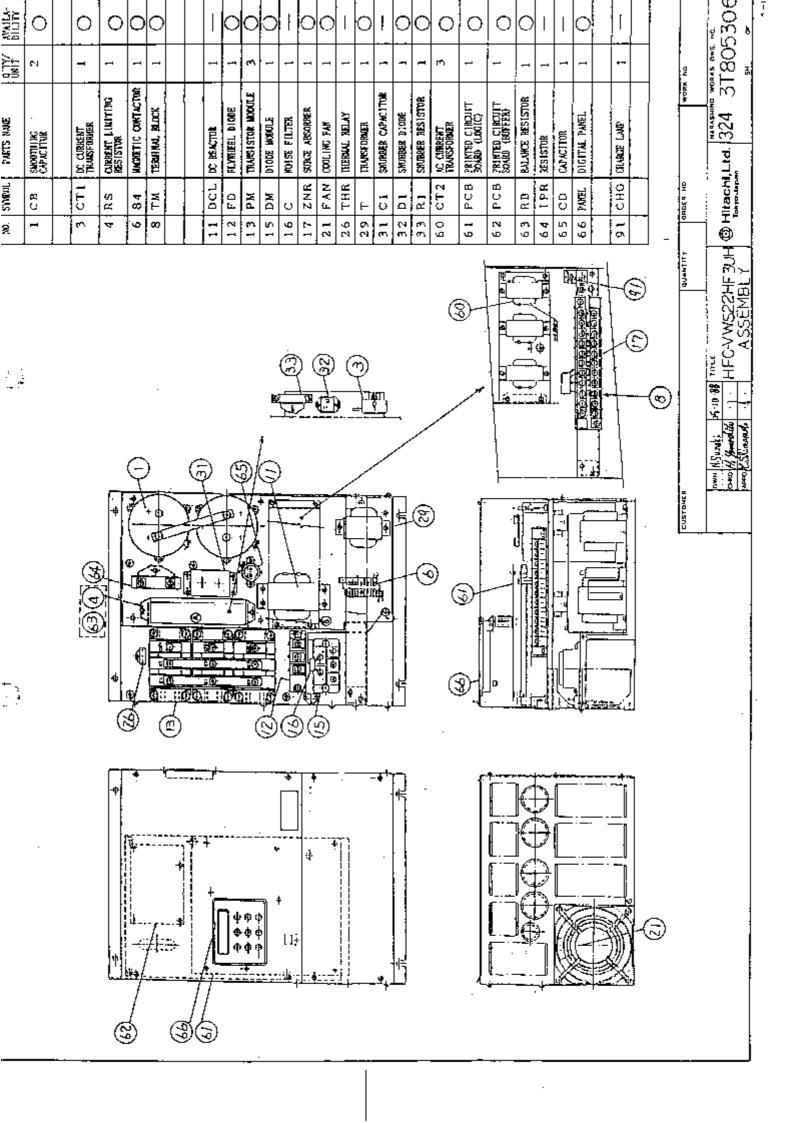


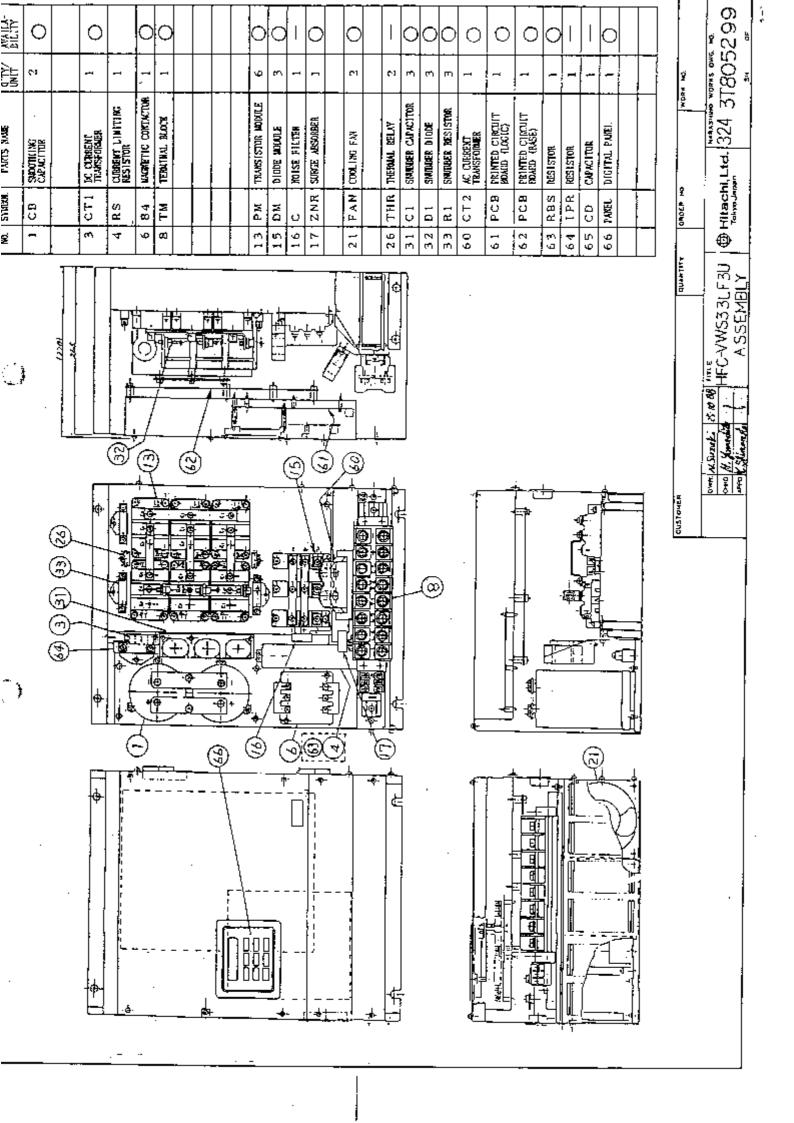
OWN ASSEME! 15.10:10 WING TO FEW STOLF BUH MITTACHULTED. 324 3T805297

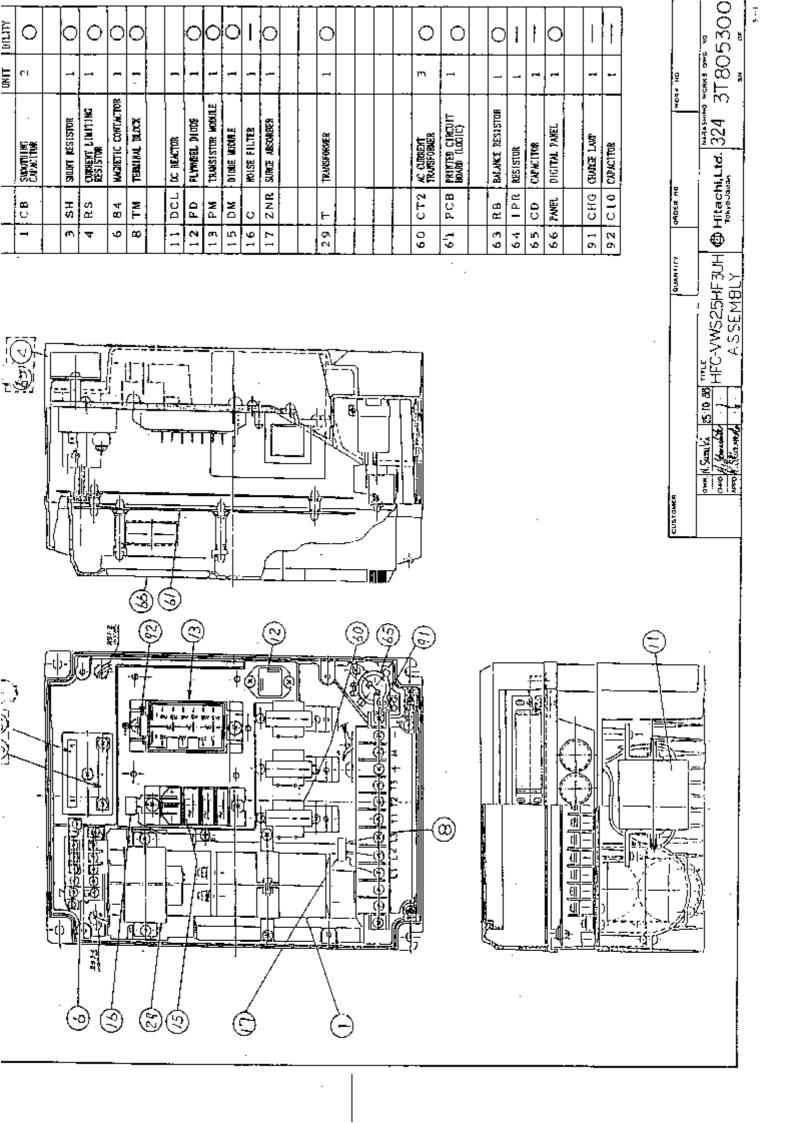


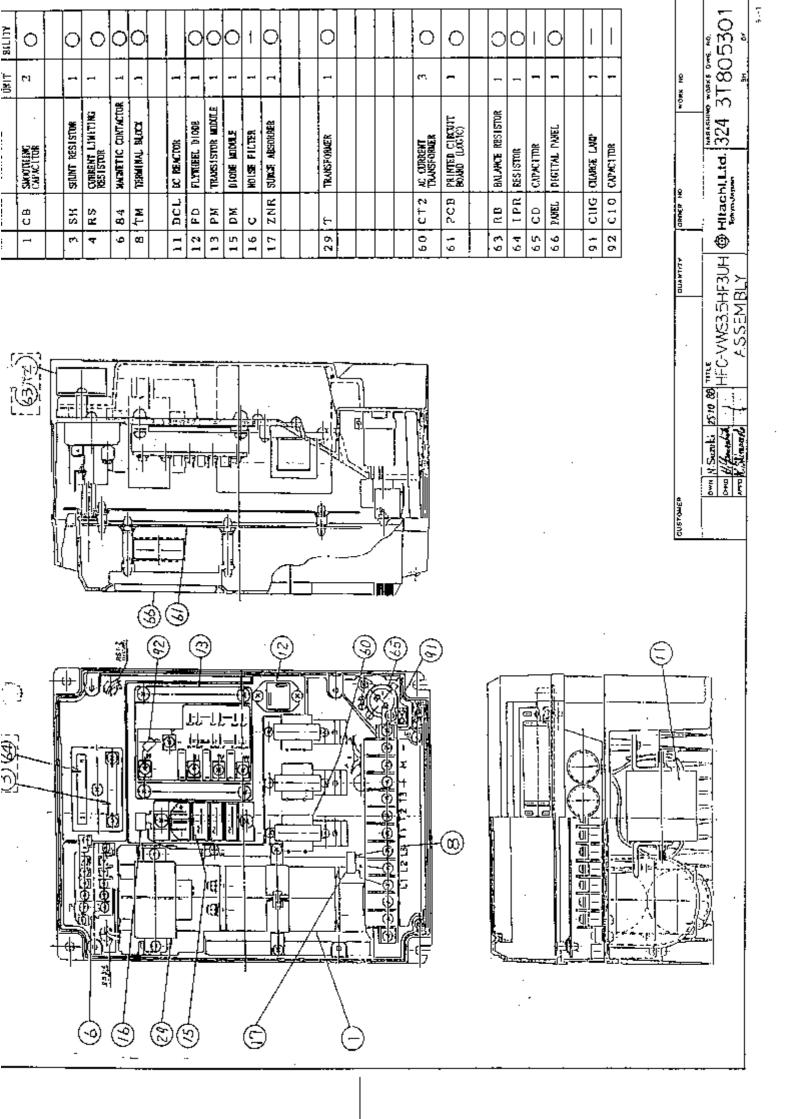


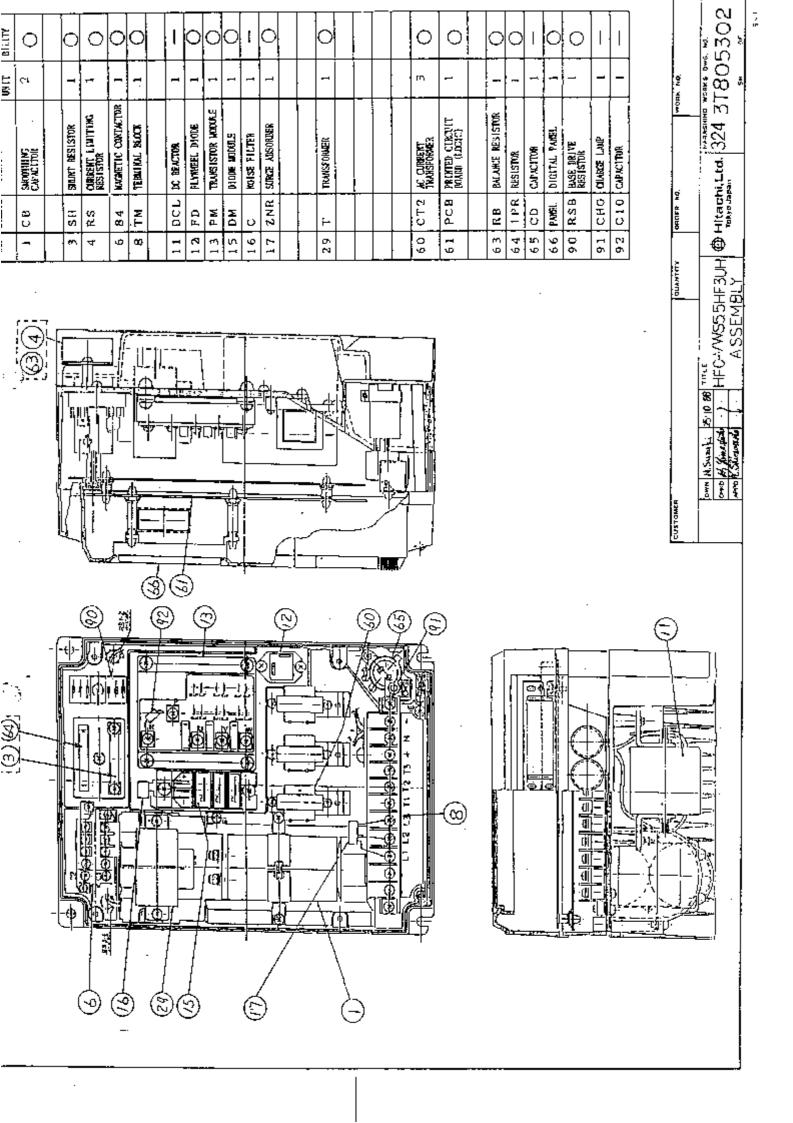


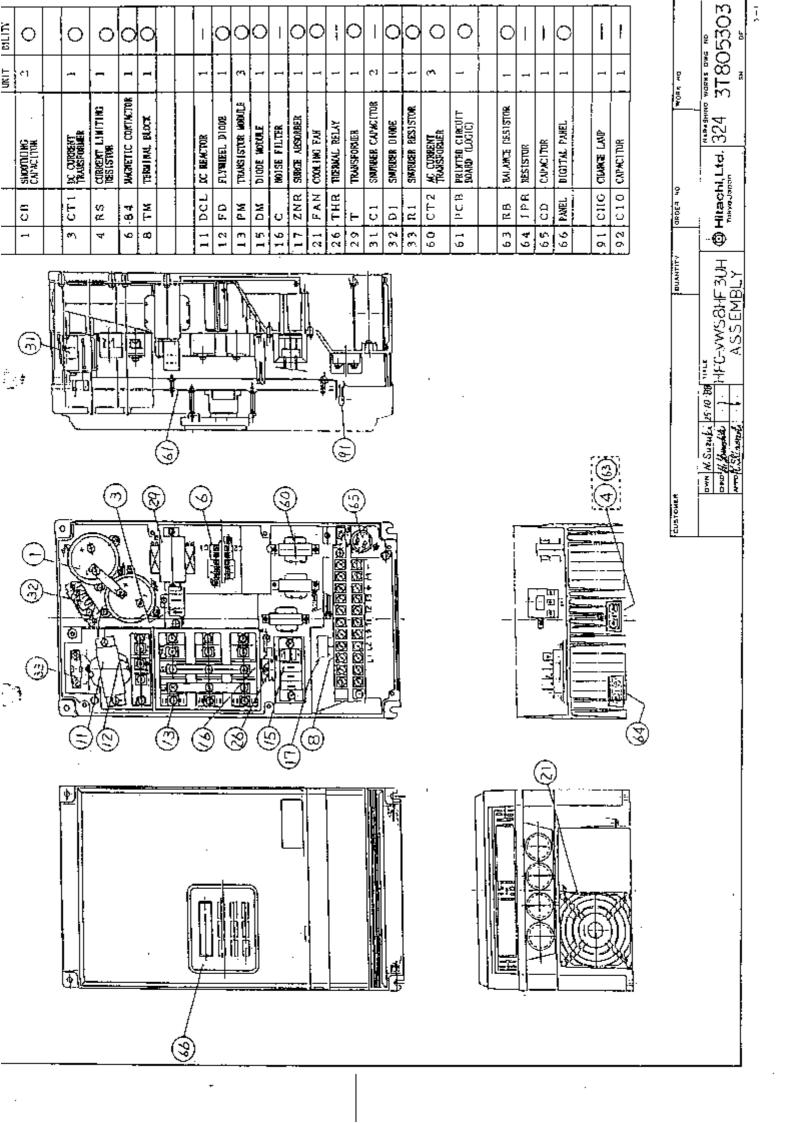












(FOR YOUR REFERENCE)
(1P23)

## 6.4 SELECTION OF VENTILATING FAN OF INVERTER BOX

When the inverter unit shall be received in the box, it is necessary to keep the ambient temperature as follows:

Enclosed wall mount type(A.& 8 type) Not Open wall mount type(C type) Not

Not exceed 40°C Not exceed 50°C

Then please install ventilating fan to ventilate well.

- (1) Inverter capacity, necessary ventilation and ventilating hole area
  - 1. The calculation examples are given in the list below. [Q is in case of 10°C at temperature ( $\Delta T=10^{\circ}C$ )]

		· · · · · · · · · · · · · · · · · · ·	
	н	Q	5
[nverter	Inverter	Necessary	Ventilating
generation	calorific	ventilation	hole area
loss(approx.	valuė	T=10 C	(minimum)
value)(KW)			(m2)
0.075	64,5.	0, 37	0.004
0.13	108	0.62	0.005
0.18	151	0.87	0.010
Q. 28	237	1.37	0.015
0.38	322	1.87	0.02
0.55	473	2.74	0.03
0.75	645	3.73	0.04
1.1	946	5. 47	_ 0.06
1.7	1419	8, 21	0.09
2.0	1720	9, 95	D. 11
2.5	2150	12.4	0.14
	2580	14.9	0.16
	3010	17.4	0, 20
	4300	24.9	0.28
	5160	29.9	0.33
7.5	6450	37.3	0, 42
	generation loss(approx. value)(KW) 0.075 0.13 0.18 0.28 0.38 0.55 0.75 1.1 1.7 2.0 2.5 3.5 5.0 6.0	Inverter generation calorific value (Kcal/hr)  0.075 64.5.  0.13 108  0.18 151  0.28 237  0.38 322  0.55 473  0.75 645  1.1 946  1.7 1419  2.0 2.5 2150  3.0 3.5 3010  5.0 4300  6.0 5160	Inverter generation calorific ventilation toss(approx. value) (KCal/hr) (m3/min)  0.075 64.5. 0.37  0.13 108 0.62  0.18 151 0.87  0.28 237 1.37  0.38 322 1.87  0.55 473 2.74  0.75 645 3.73  1.1 946 5.47  1.7 1419 8.21  2.0 1720 9.95  2.5 2150 12.4  3.0 2580 14.9  3.5 3010 17.4  5.0 4300 24.9  6.0 5160 29.9

(2.) Calculation formula

$$\Box = \frac{H}{K \times \Delta T \times 60} \quad (m^3 / min)$$

U: Necessary ventilation (m3/min)

H: Inverter calorific value (Kcal/hr)

Total value if having other heating power

K: Constant

 $\Gamma \cdot C\rho = 0.29 (Kcal/m<sup>3</sup>C)$ 

r: Specific gravity of air=1.2(kg/m)) .

Cp: Specific heat of air=0.24(Kcal/kg C)

AT: Allowable temperature rise( C)

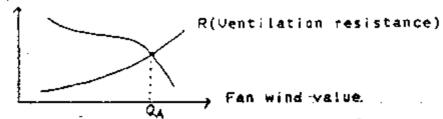
Remarks: 1KW=860Kcal/hr

## 2 Consideration of fan selection

Necessary ventilation Q shall be calculated in the way above mentioned. Fan shall be chosen considering the following matters.

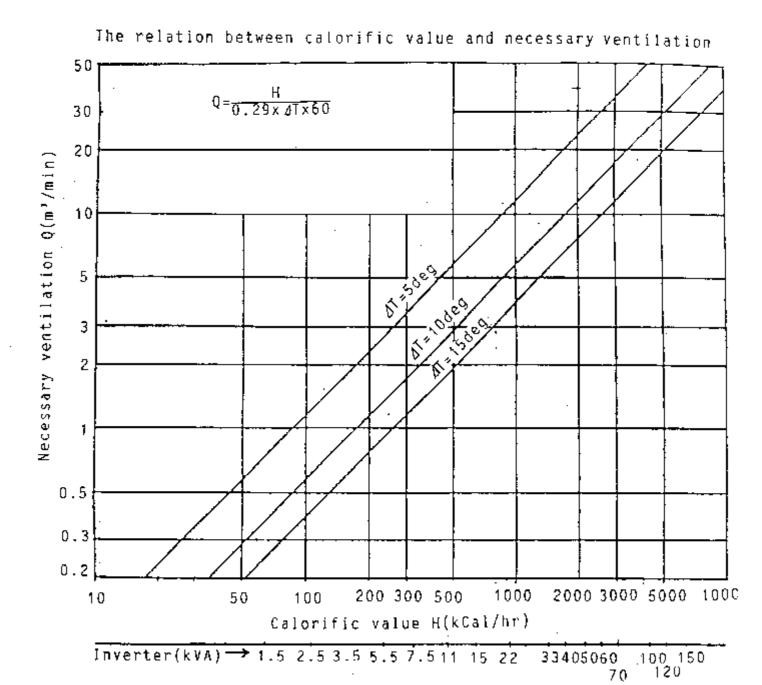
(1.) In case of mounting the filter at the ventilating entrance, operating point QA shall be calculated according to Q-H curve of the fan.

Wind pressure

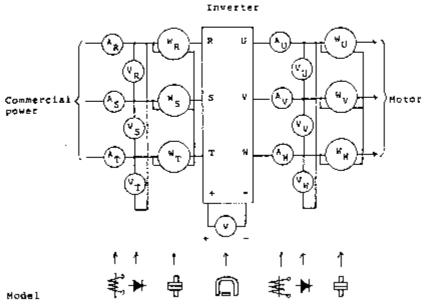


Wind value-Static pressure characteristic

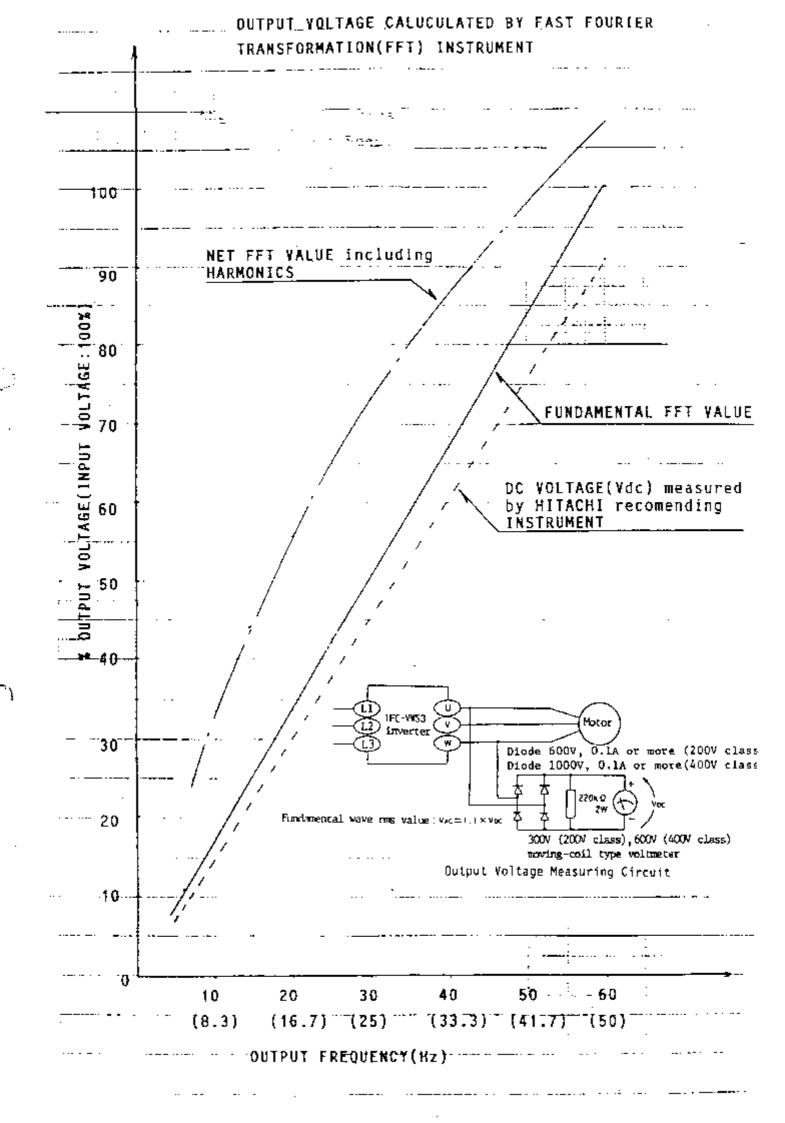
(2) In case of bad ventilation because of fully mounting in the box. it is also the same as the mentioned above.



# 6.5 HOW TO MEASURE THE VOLTAGE, CURRENT AND POWER MEASURING INSTRUMENTS AND MEASURING POINTS



Model			
Measuring items	Measuring points	Measuring instruments	Remarks (Measuring value)
Input voltage .V1	Between R-S,S-T, T-R	Moving iron-type or Rectifier- type	Commercial power 50Hz 180-230V 60Hz 180-230V
Input current	R,S,T(Line current)	Moving iron-type	
Input power	R,S,T or R-S,S-T, T-R	Electro- dynamic- type	P1=W <sub>R</sub> +W <sub>V</sub> +W <sub>T</sub> (Use 3 same type units)
Input power factor	Calculate acc	cording to the fol	lowing formula.
P <sub>f1</sub>	$P_{f1} = {\sqrt{3}}$	P1 x 100 (%)	
Output voltage V2	Between U-V.V-W W-U	Rectifier- type (Not moving iron- iron-type)	n –
Output current I2	υ,ν, <b>w</b>	Moving iron	n-
Output power P2	U,V,W U-V,V-W; W-U	Electro- dynamic- type	P1=W <sub>U</sub> +W <sub>V</sub> +W <sub>W</sub> (Use 3 same type units)
Output power factor	1	well as input pow P2 x 100 (%) 3V1 · I1	er factor.
Converter output VCB	Between ⊕ and ⊝	Moving iro type (Tester is 0.	



Output voltage

When you measure the fundamental harmonic effective value of output voltage, you can use a rectifier type voltmeter. There are many type voltmeters such as moving-iron type and thermoelectric type. The rectifier type voltmeter indicates the nearest value of the fundamental harmonic effective value.

shows the measurement characteristics of output voltage of PWM inverter by using each instrument and Fig. shows those of PAM inverter. The indication of the rectifier type shows a good lineality against the operating frequency and an approximate value of

the fundamental harmonic effective value (FFT).
You can get more approximate value of it by using a rectifier type voltmeter with connecting a filter to output terminals like Fig. when you measure the output voltage of PWM inverter which generates reverse voltage between output terminals eachtime PWM switches.

Measurement characteristics of output voltage of PWM inverter by using each instrument

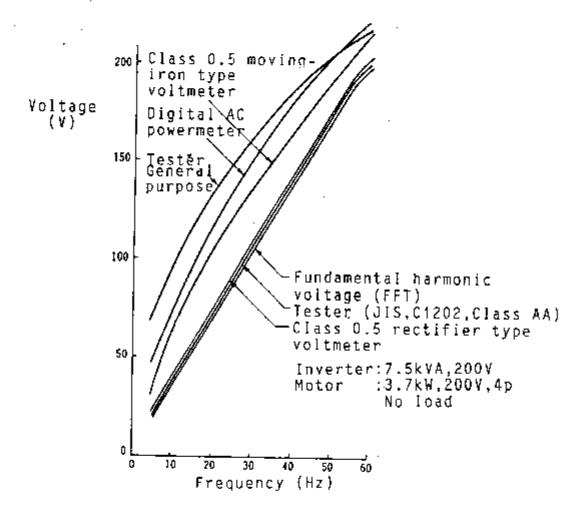


Fig. Measurement characteristics of output voltage of PAM inverter by using each instrument

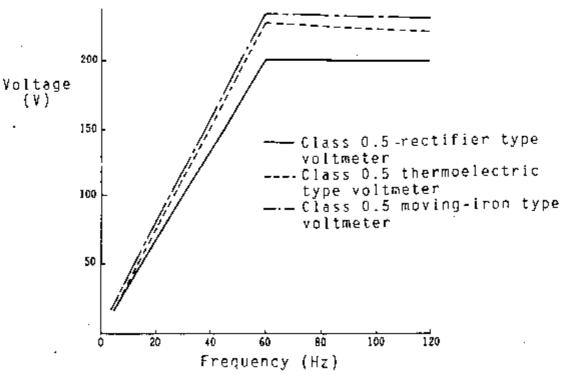
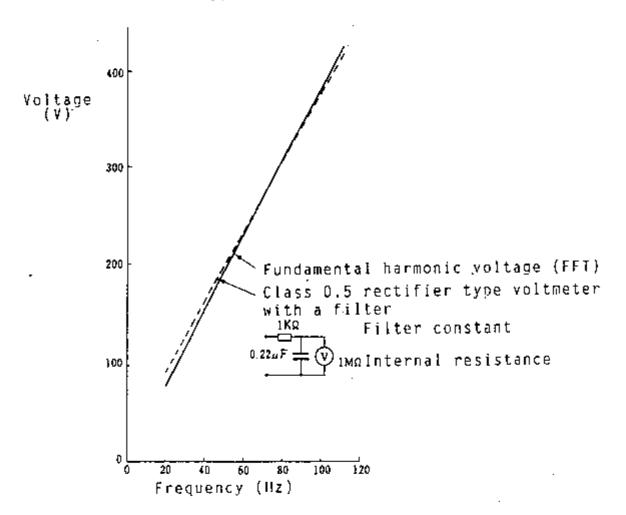


Fig. Measurement characteristics by using a rectifier type voltmeter with a filter



#### (2) Output current

When you measure the output current, you can use a moving-iron amperemeter because of necessity for the measurement of total effective current.

In case of the measurement of the effective current a thermoelectric type amperemeter is also available, but in many cases a moving-iron amperemeter is used due to ease to treat. Fig.—shows the comparison betwen measurement characteristics of the thermoelectric type amperemeter with resistance load and that of the moving-iron type amperemeter (There is a little difference between the fundamental harmonic current and total effective current in case of an actual motor load.) It is necessary to check the capacity of the current transformer when you use it because some current transformer saturate themselves in low frequency.

Fig. shows the saturation curves of current transformers in low frequency.

Fig. Measurement characteristics of output current by using each instrument

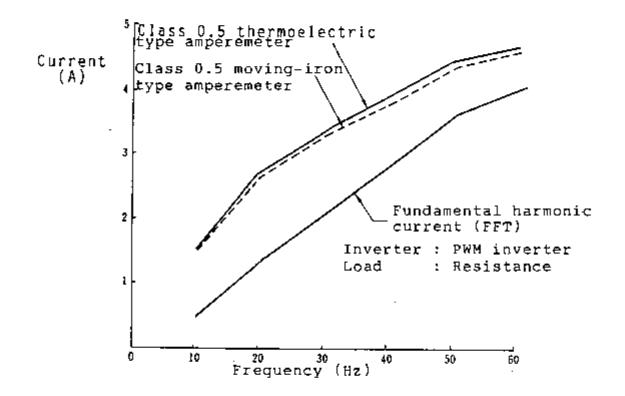


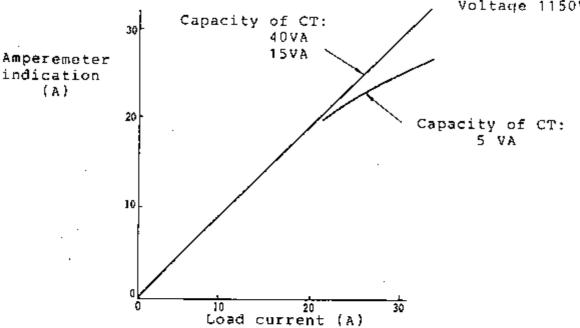
Fig Saturation curves of current transformers

Inverter Current transformer : 50/5A Through type

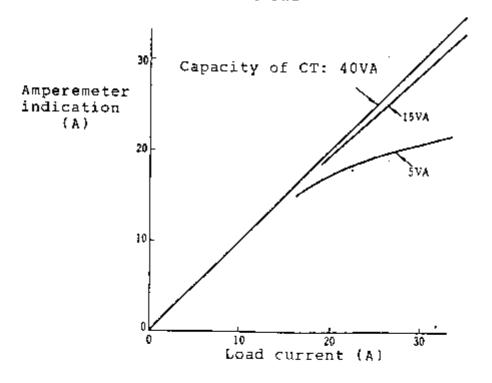
Error class 1.0

(a) Inverter frequency Over current rating more than 3

Voltage 1150V



(b) Inverter frequency at 5Hz



(3) Output power

The double wattmeters method and the triple wattmeters method are available for the measurement of the output power, and the double wattmeters method is often used because of ease to treat.

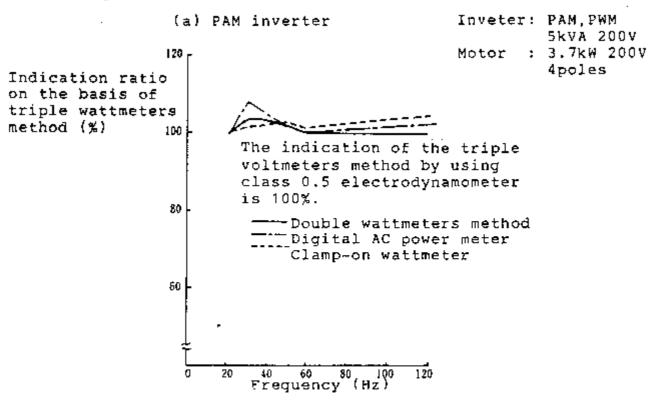
It is desirable to use the triple wattmeters method when the imbalance of the phase current is remarkable like the measurement of the input

There are two types of wattmeters such as the thermoelectric type and electrodynamometer type is useful because of the accuracy and the ease

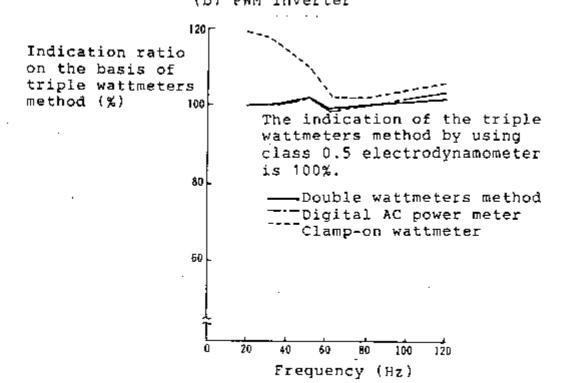
to obtain it.

shows the comparison of the indication ratio between the double wattmeters method and other wattmeters on the basis of the triple wattmeters method.

Fig Measurement characteristics by using each wattmeter



### (b) PWM inverter



NOTE: Both (a) and (b) show the indication ratio as the indication of the triple wattmeters method is 100% while the torque is constant from OHz to 60Hz and the power is constant for more than 60Hz.

(4) Power factor of inverter It is impossible to measure the power factor of the inverter by a power factor meter because the output frequency changes.

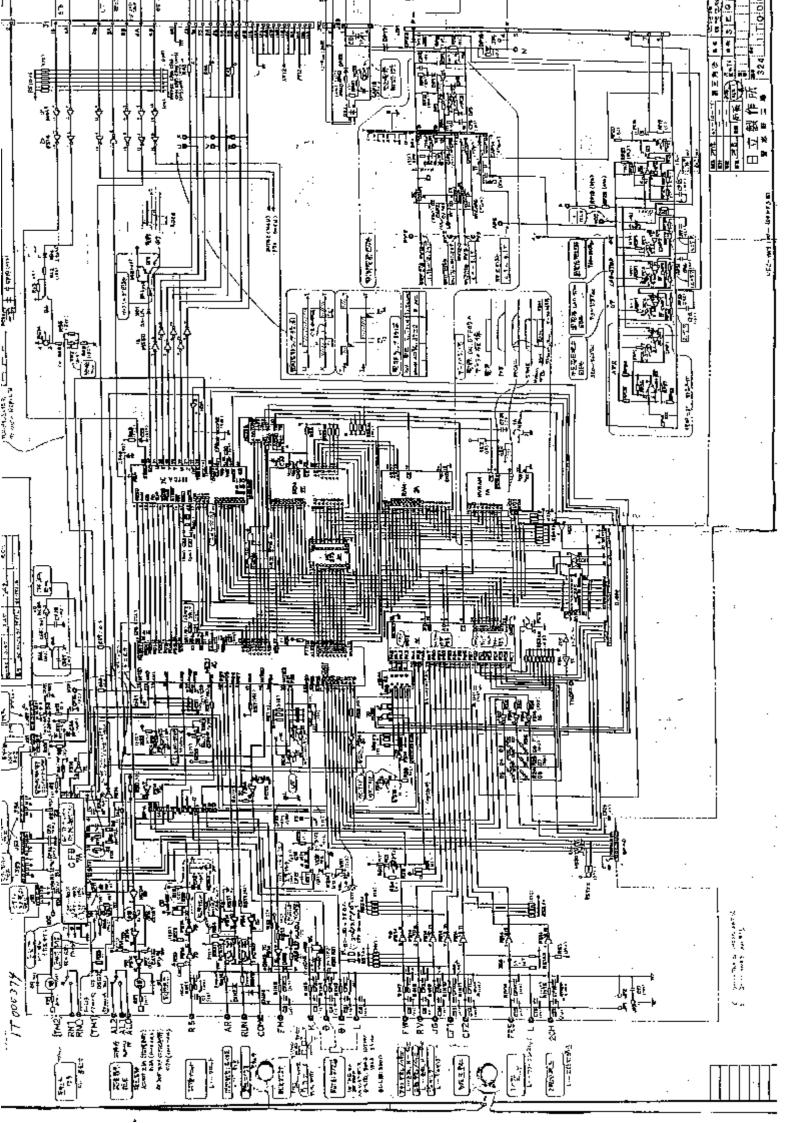
NOTE: It is possible to calculate the power factor through the output voltage, the output current and the output power. But there is difference between the power factor as is usually expressed and that which is obtained by calculation because of the difference of the measurement of higher harmonics. So the power factor of the inverter isn't ordinarily measured.

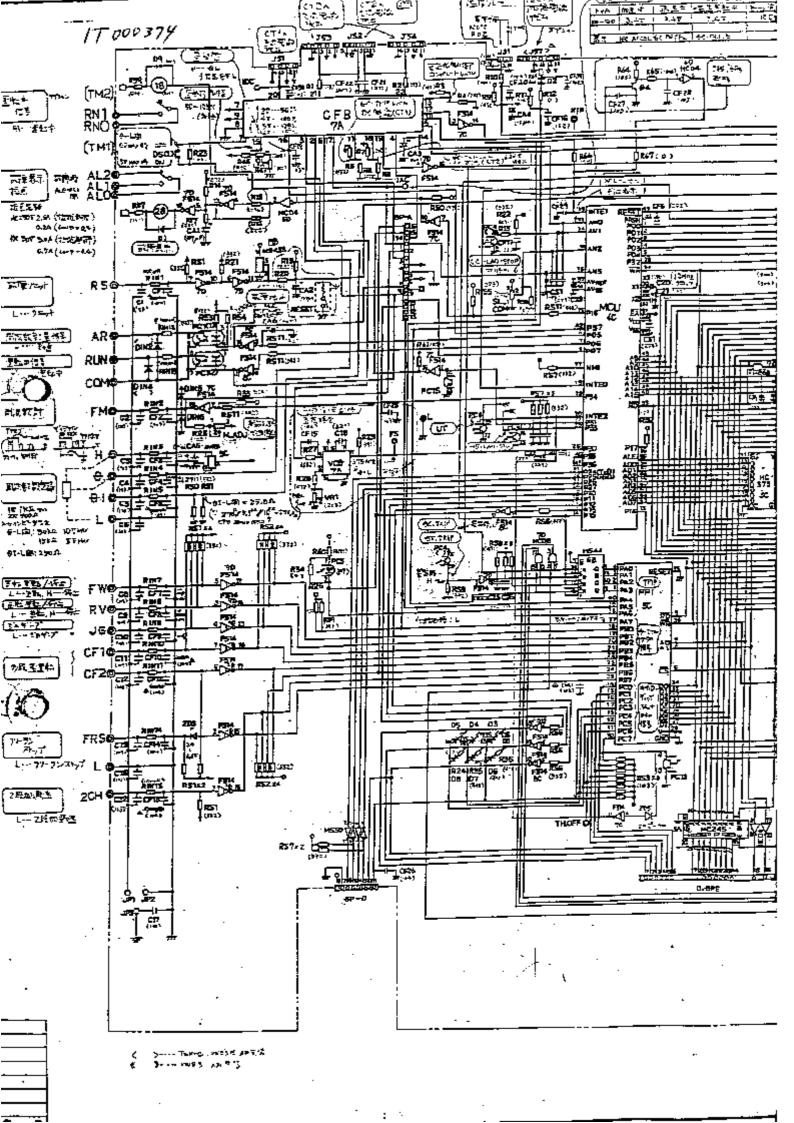
(5) Measured efficiency of inverter

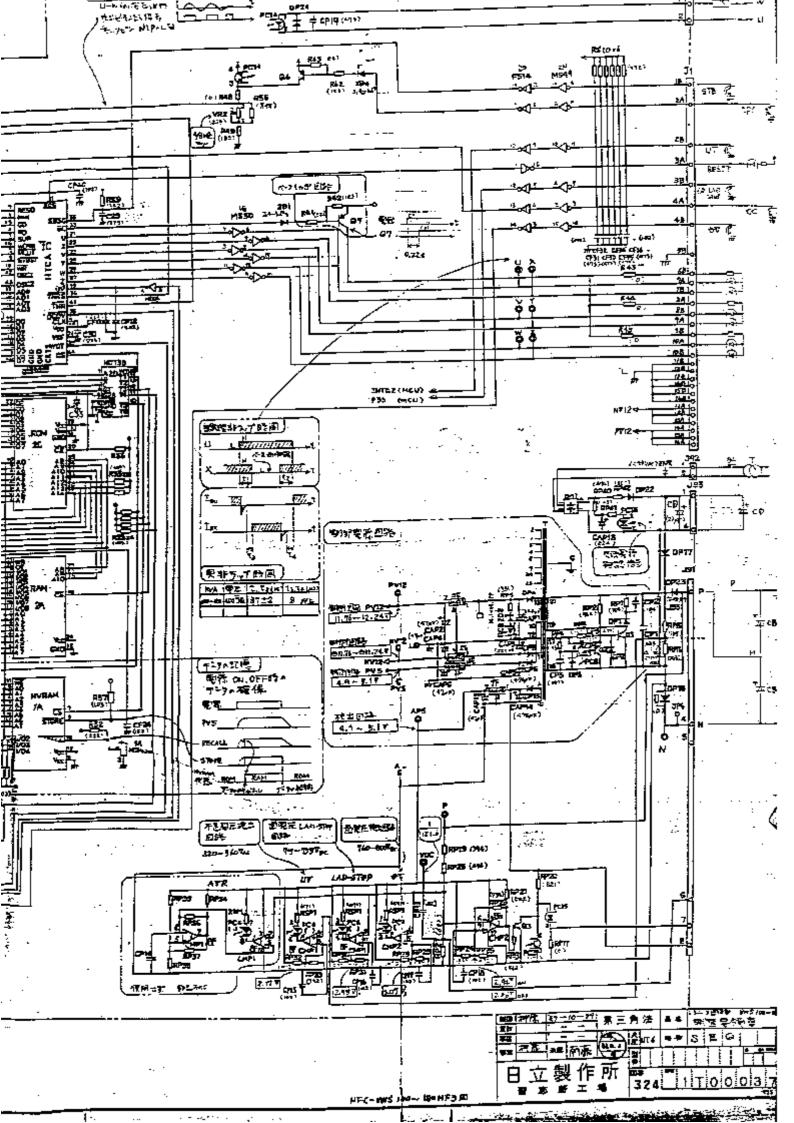
The measured efficiency of the inverter is defined as the ratio of the output active power and the input active power of the inverter.

Measured efficiency (%) =  $\frac{\text{Output active power}}{\text{Input active power}} \times 100$  (%)

(6) Output frequency
In many cases the output frequency of the inverter is output from
the inverter as the analogeue voltage or the pulse signal of frequency
control. So the output frequency is not measured directly by the output
voltage but measured by the frequency control signal.
The pulse signal is measured by a counter. The ratio of the pulse
signal and the output frequency is different among the manufacture.
When you measure it, it is necessary to ask the manufacturter.







#### END OF PAGE